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## On 1-Hamilton-connected claw-free graphs

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#### a b s t r a c t

A graph *G* is *k*-Hamilton-connected (*k*-hamiltonian) if *G*−*X* is Hamilton-connected (hamiltonian) for every set  $X \subset V(G)$  with  $|X| = k$ . In the paper, we prove that

- (i) every 5-connected claw-free graph with minimum degree at least 6 is 1-Hamiltonconnected,
- (ii) every 4-connected claw-free hourglass-free graph is 1-Hamilton-connected.
- As a byproduct, we also show that every 5-connected line graph with minimum degree at least 6 is 3-hamiltonian.
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#### **1. Introduction**

We follow the most common graph-theoretical terminology and for concepts and notations not defined here we refer e.g. to [\[1\]](#page--1-0). Specifically, by a *graph* we mean a finite undirected graph  $G = (V(G), E(G))$ ; in general, we allow graphs to have multiple edges. We use  $d_G(x)$  to denote the degree of a vertex x, and we set  $V_i(G) = \{x \in V(G) | d_G(x) = i\}, V_{\leq i}(G) = \{x \in V(G) | d_G(x) = i\}$  $V(G)|d_G(x) \leq i$  and  $V_{\geq i}(G) = \{x \in V(G)|d_G(x) \geq i\}$ . The weight of an edge e is the number of edges incident with e and distinct from it.

For a set  $M \subset V(G)$ ,  $\langle M \rangle_G$  denotes the *induced subgraph* on M, and for a simple graph *F*, *G* is said to be *F*-free if *G* is a simple graph that does not contain an induced subgraph isomorphic to *F* . Specifically, for *F* = *K*1,<sup>3</sup> we say that *G* is *claw-free*. The *hourglass* Γ is the only graph with degree sequence 4, 2, 2, 2, 2 (see [Fig. 2\)](#page--1-1), and for *F* = Γ we say that *G* is *hourglass-free*.

The *neighborhood* of a vertex *x*, denoted  $N_G(x)$ , is the set of all neighbors of *x*, and a vertex  $x \in V(G)$  is *simplicial* (*locally connected, locally disconnected, eligible*) if  $(N_G(x))$ <sup>*G*</sup> is a complete (connected, disconnected, connected noncomplete) subgraph of *G*. We will use  $V_{FL}(G)$  to denote the set of all eligible vertices in *G*. The *closed neighborhood* of a vertex *x* is the set  $N_G[x] = N_G(x) \cup \{x\}$ , and an edge  $e \in E(G)$  is *pendant* if one of its vertices is of degree 1.

For *x* ∈ *V*(*G*), *G* − *x* is the graph obtained from *G* by removing *x* and all edges incident to it. If *x*, *y* ∈ *V*(*G*) are such that  $e = xy \notin E(G)$ , then  $G + e$  is the graph with  $V(G + e) = V(G)$  and  $E(G + e) = E(G) \cup \{e\}$ , and, conversely, for  $e = xy \in E(G)$ we denote  $G - e$  the graph with  $V(G - e) = V(G)$  and  $E(G - e) = E(G) \setminus \{e\}$ . Specifically, for  $F \subset G$  and  $e \in E(G)$ , we set *F* − *e* = *F* if *e* ∈ *E*(*G*) \ *E*(*F*). We use  $\omega$ (*G*) to denote the *number of components* of *G*.

A graph *G* is *hamiltonian* if *G* contains a *hamiltonian cycle*, i.e. a cycle of length |*V*(*G*)|, and *G* is *Hamilton-connected* if, for any  $a, b \in V(G)$ , G contains a hamiltonian  $(a, b)$ -path, i.e., an  $(a, b)$ -path P with  $V(P) = V(G)$ . For  $k \ge 1$ , G is k-hamiltonian if *G* − *X* is hamiltonian for every set of vertices *X* ⊂ *V*(*G*) with |*X*| = *k*, and *k*-*Hamilton-connected* if *G* − *X* is Hamiltonconnected for every set of vertices  $X \subset V(G)$  with  $|X| = k$ . Note that a hamiltonian graph is necessarily 2-connected, a







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Hamilton-connected graph must be 3-connected, a *k*-hamiltonian graph must be (*k*+2)-connected, and if *G* is *k*-Hamiltonconnected, then *G* must be  $(k + 3)$ -connected. The *line graph* of a graph *H* is the simple graph  $L(H)$  with vertex set  $E(H)$ , in which two vertices are adjacent if and only if the corresponding edges of *H* share a vertex, and a graph *G* is a *line graph* if there is a graph *H* such that  $G = L(H)$ . Note that every line graph is claw-free, and that the degree of a vertex in G equals the weight of the corresponding edge in *H*.

<span id="page-1-1"></span>The main motivation of our research is the following conjecture by Thomassen.

#### **Conjecture A** (*[\[18\]](#page--1-2)*)**.** *Every* 4*-connected line graph is hamiltonian.*

There are many known equivalent versions of the conjecture (see [\[3\]](#page--1-3) for a survey on this topic). We mention here the following one, which is of importance for our results.

<span id="page-1-0"></span>**Theorem B** (*[\[16\]](#page--1-4)*)**.** *The following statements are equivalent:*

- (i) *Every* 4*-connected line graph is hamiltonian.*
- (ii) *Every* 4*-connected claw-free graph is* 1*-Hamilton-connected.*

In this paper, we prove the following two results giving a partial affirmative answer to the statement (ii) of [Theorem B,](#page-1-0) i.e., equivalently, to [Conjecture A:](#page-1-1)

- in Section [3,](#page--1-5) we show that every 4-connected claw-free hourglass-free graph is 1-Hamilton-connected,
- in Section [4,](#page--1-6) we show that every 5-connected claw-free graph with minimum degree at least 6 is 1-Hamilton-connected.

As a byproduct, in Section [5](#page--1-7) we show that every 5-connected line graph with minimum degree at least 6 is 3-hamiltonian.

#### **2. Preliminaries**

In this section we summarize some background knowledge that will be needed for our results.

Let *H* be a graph and  $G = L(H)$ . It is well-known that if we allow *H* to be a multigraph, then (unlike in line graphs of simple graphs), for a line graph *G*, a graph *H* such that  $G = L(H)$  is not uniquely determined. A simple example is the hourglass  $\Gamma$  in [Fig. 2,](#page--1-1) where  $\Gamma$  is the line graph of all three graphs to the right. As shown in [\[14\]](#page--1-8), this difficulty can be overcome by imposing an additional requirement that simplicial vertices in *G* correspond to pendant edges in *H*.

The *basic graph* of a multigraph is the simple graph with the same vertex set, in which every multiedge is replaced by a single edge. A *multitriangle* (*multistar*) is a multigraph such that its basic graph is a triangle (star). The *center* of a multistar *S* with *m* edges is the vertex  $x \in V(S)$  with  $d_S(x) = m$  (for  $|V(S)| = 2$  we choose the center arbitrarily), and all other vertices of *S* are its *leaves*. An induced multistar *S* in *H* is *pendant* if none of its leaves has a neighbor in *V*(*H*) \ *V*(*S*), and similarly a multitriangle *T* is pendant if exactly one of its vertices (called the *root*) has neighbors in  $V(H) \setminus V(S)$ . We will use the following operations, introduced in [\[20\]](#page--1-9) (Operation B) and [\[14\]](#page--1-8) (Operation C).

Operation B. Choose a pendant multitriangle in *H* with vertices { $v$ ,  $x$ ,  $y$ } and root  $v$ , delete all edges joining  $v$  and  $x$ , and add the same number of edges between v and *y*.

Operation C. Choose a pendant multistar in *H* and replace every leaf of degree *k* ≥ 2 by *k* leaves of degree 1.

Now, for a multigraph *H*, *BC*(*H*) denotes the multigraph obtained from *H* by recursively repeating operations *B* and *C*. It can be shown that  $L(H) = L(BC(H))$ ,  $BC(H)$  is uniquely determined and has the property that simplicial vertices in  $L(H)$ correspond to pendant edges in *H*.

#### <span id="page-1-2"></span>**Proposition C** (*[\[14\]](#page--1-8)*)**.** *Let G be a connected line graph of a multigraph. Then there is, up to an isomorphism, a uniquely determined multigraph H such that a vertex e*  $\in$  *V*(*G*) *is simplicial in G if and only if the corresponding edge e*  $\in$  *E*(*H*) *is a pendant edge in H.*

For a line graph *G*, we will always consider its preimage to be the unique multigraph with the properties given in [Proposition C;](#page-1-2) this preimage will be denoted  $L^{-1}(G)$ . Similarly, we will write  $x = L(e)$  and  $e = L^{-1}(x)$  if  $e \in E(L^{-1}(G))$ is the edge corresponding to a vertex  $x \in V(G)$ . In accordance with our definitions, when working with a claw-free graph or with a line graph *G*, we always consider *G* to be a simple graph, while if *G* is a line graph, for its preimage *H* = *L* −1 (*G*) we always admit *H* to be a multigraph, i.e. we always (even if we say ''a graph *H*'') allow *H* to have multiple edges.

An edge cut *R* of a graph *H* is *essential* if *H* −*R* has at least two nontrivial components. For an integer *k* > 0, *H* is *essentially k*-*edge-connected* if every essential edge cut *R* of *G* contains at least *k* edges. Obviously, a line graph *G* = *L*(*H*) of order at least *k* + 1 is *k*-connected if and only if the graph *H* is essentially *k*-edge-connected.

Given a trail *T* and an edge *e* in a multigraph *G*, we say that *e* is *dominated (internally dominated)* by *T* if *e* is incident to a vertex (to an interior vertex) of *T* , respectively. A trail *T* in *G* is called an *internally dominating trail*, shortly *IDT*, if *T* internally dominates all the edges in *G*. For  $e_1$ ,  $e_2 \in E(G)$ , an IDT with terminal edges  $e_1$ ,  $e_2$  will be referred to as an  $(e_1, e_2)$ -*IDT*. If *T* is a closed trail, every vertex of *T* is considered to be an internal vertex, hence every dominated edge is internally dominated, and we simply say that *T* is a *dominating trail*. A classical result by Harary and Nash-Williams [\[5\]](#page--1-10) shows that a line graph  $G = L(H)$  of order at least 3 is hamiltonian if and only if *H* contains a dominating closed trail. The following result relates hamiltonian paths in a line graph to internally dominating trails in its preimage.

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