



## Further results on optimal $(v, 4, 2, 1)$ -OOCs

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### ARTICLE INFO

#### Article history:

Received 24 November 2010

Received in revised form 3 September 2011

Accepted 20 September 2011

Available online 24 October 2011

#### Keywords:

Optical orthogonal code

Optimal

Good difference matrix

### ABSTRACT

Let  $\Phi(v, k, \lambda_a, \lambda_c)$  denote the maximum possible size among all  $(v, k, \lambda_a, \lambda_c)$ -OOCs. A  $(v, k, \lambda_a, \lambda_c)$ -OOC is said to be *optimal* if its size is equal to  $\Phi(v, k, \lambda_a, \lambda_c)$ . In this paper, the constructions and the sizes of optimal  $(v, 4, 2, 1)$ -OOCs are investigated. An upper bound for  $\Phi(v, 4, 2, 1)$  is improved. The exact value of  $\Phi(v, 4, 2, 1)$  with  $v \leq 201$  is given with the aid of computer search. An optimal  $(24hv, 4, 2, 1)$ -OOC with  $h \in \{1, 2\}$  and  $v = p_1 p_2 \cdots p_r$ , where prime  $p_i \equiv 1 \pmod{6}$  is constructed recursively. The existence of  $g$ -regular  $(gp, 4, 2, 1)$ -OOCs for  $g = 3, 6, 9, 16$ , and  $p$  a prime satisfying a suitable congruence is established by direct constructions. Furthermore, the sizes of several new infinite classes of optimal  $(v, 4, 2, 1)$ -OOCs are obtained. In particular,  $\Phi(v, 4, 2, 1) = U(v)$  for positive integer  $v \equiv 80, 400 \pmod{480}$ .

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### 1. Introduction

A  $(v, k, \lambda_a, \lambda_c)$  *optical orthogonal code* (or  $(v, k, \lambda_a, \lambda_c)$ -OOC) can be viewed as a collection  $\mathcal{C} = \{C_1, C_2, \dots, C_s\}$  of  $k$ -subsets (codeword-sets) of  $Z_v$ , such that any two distinct translates of a codeword-set share at most  $\lambda_a$  elements, while any two translates of two distinct codeword-sets share at most  $\lambda_c$  elements:

(1) (the *auto-correlation property*)  $|C_i \cap (C_i + t)| \leq \lambda_a$  for  $1 \leq i \leq s$  and  $1 \leq t \leq v - 1$ ;

(2) (the *cross-correlation property*)  $|C_i \cap (C_j + t)| \leq \lambda_c$  for  $1 \leq i \neq j \leq s$  and  $0 \leq t \leq v - 1$ .

The number of codeword-sets is called the *size* of  $\mathcal{C}$ . Let  $\Phi(v, k, \lambda_a, \lambda_c)$  denote the maximum possible size among all  $(v, k, \lambda_a, \lambda_c)$ -OOCs. A  $(v, k, \lambda_a, \lambda_c)$ -OOC is said to be *optimal* if its size is equal to  $\Phi(v, k, \lambda_a, \lambda_c)$ . When  $\lambda_a = \lambda_c = \lambda$ , the notations of  $(v, k, \lambda)$ -OOC and  $\Phi(v, k, \lambda)$  are employed. From the definition of optimal OOC, it is straightforward that an optimal OOC exists for all parameter values: it is simply an OOC of the largest possible size. For given parameters  $v, k, \lambda_a$  and  $\lambda_c$ , the constructions and determining the sizes of optimal  $(v, k, \lambda_a, \lambda_c)$ -OOCs are apparently difficult tasks. It is well known that the size of a  $(v, k, \lambda)$ -OOC cannot exceed the Johnson bound (see [26]), that is,

$$\Phi(v, k, \lambda) \leq J(v, k, \lambda)$$

where  $J(v, k, \lambda) = \lfloor \frac{1}{k} \lfloor \frac{v-1}{k-1} \rfloor \cdots \lfloor \frac{v-\lambda}{k-\lambda} \rfloor \rfloor \rfloor$ .

Optical orthogonal codes have many important applications because of their good correlation properties. This was first motivated by an application in a fiber-optic code-division multiple-access (CDMA) channel. Recent work has been done on using OOCs for multimedia transmission in fiber-optic local-area networks (LANs) and in multi-rate fiber-optic CDMA systems. The reader may refer to [23,24,28,33] for details.

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For a long time, research on OOCs has mainly concentrated on the case  $\lambda_a = \lambda_c = \lambda$  in the literature. Constructions of optimal  $(v, k, 1)$ -OOCs has been investigated in [8,23]. It is often closely related to *difference families* [1,7,13,20,21,35] and to *relative difference families* [9,10,15–19,27,31] in view of their importance in design theory [2,6]. Recently, several results have also been done on optimal  $(v, k, \lambda)$ -OOCs with  $\lambda = 2$  [3,22,25] and even with  $\lambda > 2$  [4].

There is little in the literature regarding optimal  $(v, k, \lambda_a, \lambda_c)$ -OOCs with  $\lambda_a \neq \lambda_c$ . An earlier investigation about them was given in [34], where it is shown that the size of a  $(v, k, \lambda_a, \lambda_c)$ -OOC cannot exceed  $\frac{\lambda_a(v-1)(v-2)\cdots(v-\lambda_c)}{k(k-1)(k-2)\cdots(k-\lambda_c)}$  with  $\lambda_a \geq \lambda_c$ . Known results on optimal  $(v, k, k-1, 1)$ -OOCs (which are also called *conflict-avoiding codes*) have been treated in [29,30]. The research on optimal  $(v, 4, 2, 1)$ -OOCs was first dealt with in [32], where several direct and recursive constructions for optimal  $(v, 4, 2, 1)$ -OOCs were presented. Later in [14], the constructions of perfect  $(v, 4, 2, 1)$ -OOCs were given for several infinite classes. In [5], all optimal  $(v, 4, 2, 1)$ -OOCs with  $v < 71$  are determined up to equivalence.

In this paper, we shall investigate the sizes and constructions of optimal  $(v, 4, 2, 1)$ -OOCs. In the next section, we introduce the concept of good difference matrix and state recursive constructions for  $(v, 4, 2, 1)$ -OOCs. In Section 3, we improve the upper bound of the sizes of optimal  $(v, 4, 2, 1)$ -OOCs, and we also give direct constructions of optimal  $(v, 4, 2, 1)$ -OOCs for  $v \leq 201$  with the aid of computer. In Section 4, we construct optimal  $(24hv, 4, 2, 1)$ -OOCs with  $h \in \{1, 2\}$  and  $v = p_1 p_2 \cdots p_r$ , where prime  $p_i \equiv 1 \pmod{6}$ . Finally, in Section 5, we establish the existence of a  $g$ -regular  $(gp, 4, 2, 1)$ -OOC with  $g = 3, 6, 9, 16$ , and obtain three new infinite classes of optimal  $(v, 4, 2, 1)$ -OOCs.

## 2. Recursive constructions

Let  $K = (v_1, v_2, v_3) - v_4$  be a kite, that is, the graph consisting of a triangle  $\{v_1, v_2, v_3\}$  with an attached edge  $\{v_3, v_4\}$ .

An  $(n, K, 1)$  difference matrix, briefly  $DM(n, K, 1)$ , is a  $4 \times n$  matrix with entries in  $Z_n$ , such that the differences between its  $i$ -th row and its  $j$ -th row is a permutation of  $Z_n$  whenever  $v_i$  and  $v_j$  are adjacent in  $K$ . (For the definition of an  $(n, \Gamma, \lambda)$  difference matrix where  $\Gamma$  is any graph and  $\lambda$  is any positive integer, the reader is referred to [11]). A  $DM(n, K, 1)$  is called *good* if it is of the form

$$\begin{pmatrix} a_1 & a_2 & \cdots & a_n \\ a_1 + b_1 & a_2 + b_2 & \cdots & a_n + b_n \\ 0 & 0 & \cdots & 0 \\ 2a_1 + b_1 & 2a_2 + b_2 & \cdots & 2a_n + b_n \end{pmatrix}.$$

The following result can be found in [32].

**Lemma 2.1** ([32]). *If  $\gcd(n, 6) = 1$ , then*

$$\begin{pmatrix} 1 & 2 & \cdots & n \\ 2 \cdot 1 & 2 \cdot 2 & \cdots & 2 \cdot n \\ 0 & 0 & \cdots & 0 \\ 3 \cdot 1 & 3 \cdot 2 & \cdots & 3 \cdot n \end{pmatrix}$$

*is a good  $(n, K, 1)$  difference matrix.*

In order to state Lemmas 2.2 and 2.3, we recall some basic terminologies defined in [14].

For a given subset  $C$  of  $Z_v$ , its *list of differences* is denoted by  $\Delta C$ , that is the multiset of all differences  $x - y$  with  $(x, y)$  an ordered pair of distinct elements of  $C$ . The underlying set of  $\Delta C$  is called the *support* of  $\Delta C$  and it is denoted by  $\text{supp}(\Delta C)$ . More generally, the list of differences of a set  $\mathcal{C}$  of subsets of  $Z_v$  is the multiset  $\Delta \mathcal{C} = \bigcup_{C \in \mathcal{C}} \Delta C$ . Also, the support of  $\Delta \mathcal{C}$  is the underlying set of  $\bigcup_{C \in \mathcal{C}} \Delta C$ .

If  $\delta$  is the size of  $\text{supp}(\Delta C)$ , namely the number of distinct differences appearing in  $\Delta C$ , we will say that  $C$  is of *type*  $t(C) = \delta$ . It is obvious that  $t(C)$  cannot exceed the size of  $\Delta C$ , that is  $t(C) \leq k(k-1)$  where  $k$  is the size of  $C$ . Saying that  $\mathcal{C}$  is of type  $[\delta_1^{x_1}, \delta_2^{x_2}, \dots, \delta_t^{x_t}]$ , we mean that  $\mathcal{C}$  has exactly  $x_i$  codeword-sets of type  $\delta_i$  for  $i = 1, 2, \dots, t$ .

The *missing differences* of a  $(v, k, \lambda_a, 1)$ -OOC  $\mathcal{C}$  is the set  $M$  of  $Z_v$  that are not covered by the list of differences of  $\mathcal{C}$ . If the OOC is of type  $[\delta_1^{x_1}, \delta_2^{x_2}, \dots, \delta_t^{x_t}]$ , it is clear that  $m = |M| = v - (\delta_1 x_1 + \delta_2 x_2 + \cdots + \delta_t x_t)$ . If  $M$  is a subgroup of  $Z_v$ , then the OOC is called  *$m$ -regular*.

The following constructions come from Theorem 5.3 of [32], here we rewrite it with two lemmas using the concept of good difference matrix.

**Lemma 2.2.** *Suppose that there exist both a  $g$ -regular  $(gm, 4, 2, 1)$ -OOC  $\mathcal{F}$  such that  $|\text{supp}(\Delta X)| = 8$  for every  $X \in \mathcal{F}$ , and a good  $DM(n, K, 1)$ . Then there exists a  $gn$ -regular  $(gmn, 4, 2, 1)$ -OOC  $\mathcal{F}'$  satisfying  $|\text{supp}(\Delta Y)| = 8$  for  $Y \in \mathcal{F}'$ .*

**Lemma 2.3.** *If there are a  $gm$ -regular  $(gmn, 4, 2, 1)$ -OOC  $\mathcal{F}$  such that  $|\text{supp}(\Delta X)| = 8$  for every  $X \in \mathcal{F}$ , and a  $(gm, 4, 2, 1)$ -OOC  $\mathcal{F}'$  with size  $s$ , then there exists a  $(gmn, 4, 2, 1)$ -OOC with size  $gm(n-1)/8 + s$  that is  $g$ -regular if  $\mathcal{F}'$  is such. Moreover, every codeword-set  $Y$  of the resultant OOC satisfies  $|\text{supp}(\Delta Y)| = 8$  if  $\mathcal{F}'$  has the same property.*

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