

Note

Symmetric and resolvable λ -configurations constructed from block designs

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Received 1 April 2005; received in revised form 12 July 2007; accepted 14 August 2007

Available online 24 September 2007

Abstract

A λ -configuration $(v_r, b_k)_\lambda$ is a finite incidence structure of v points and b blocks such that each block contains exactly k points, each point lies on exactly r blocks and two different points are connected by at most λ blocks. If $v = b$ and hence $r = k$, then a λ -configuration is symmetric. From any block design we construct λ -configurations. Some block designs lead to symmetric λ -configurations, and some leads to resolvable λ -configurations.

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Keywords: λ -configuration; Block design; Resolvable λ -configuration

1. Introduction

Definition 1. A λ -configuration $(v_r, b_k)_\lambda$ is a finite incidence structure $(\mathcal{P}, \mathcal{B}, I)$, where \mathcal{P} and \mathcal{B} are disjoint sets and $I \subseteq \mathcal{P} \times \mathcal{B}$, such that

1. $|\mathcal{P}| = v$,
2. $|\mathcal{B}| = b$,
3. every element of \mathcal{B} is incident with exactly k elements of \mathcal{P} ,
4. every element of \mathcal{P} is incident with exactly r elements of \mathcal{B} ,
5. every pair of distinct elements of \mathcal{P} is incident with at most λ elements of \mathcal{B} .

The elements of the set \mathcal{P} are called points, and the elements of the set \mathcal{B} are called blocks. If a point P is incident with a block x , we write Px .

A 2-configuration is called a spatial configuration. If $v = b$ and hence $r = k$, then a λ -configuration is symmetric.

Definition 2. A parallel class or resolution class in a λ -configuration is a set of blocks that partition the point set. A resolvable λ -configuration is a λ -configuration whose blocks can be partitioned into parallel classes.

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Definition 3. Let \mathcal{I} be an incidence structure with the set of points $\mathcal{P} = \{P_1, P_2, \dots, P_v\}$ and the set of blocks $\mathcal{B} = \{x_1, x_2, \dots, x_b\}$. The incidence matrix of \mathcal{I} is a $b \times v$ matrix $M = (m_{ij})$ defined by

$$m_{ij} = \begin{cases} 1 & \text{if } P_j \text{ is incident with } x_i, \\ 0 & \text{otherwise.} \end{cases}$$

Definition 4. Let M be the incidence matrix of an incidence structure \mathcal{I} . Denote by M^t the transpose of M . The graph with adjacency matrix

$$\begin{bmatrix} 0 & M \\ M^t & 0 \end{bmatrix}$$

is called the incidence graph of \mathcal{I} .

Definition 5. A (v, k, λ) block design is a λ -configuration $(v_r, b_k)_\lambda$ such that every pair of points is incident with exactly λ blocks. A $(v, 3, 1)$ block design is called a Steiner triple system.

For further basic definitions and properties of configurations and block designs we refer the reader to [1–3].

2. λ -configurations constructed from block designs

Let $\mathcal{D} = (\mathcal{P}, \mathcal{B}, I)$ be a (v, k, λ) block design. Let us define the incidence structure $\mathcal{D}_1 = (\mathcal{P}_1, \mathcal{B}_1, I_1)$ as follows:

$\mathcal{P}_1 = \{(P, x) \mid P \in \mathcal{P}, x \in \mathcal{B}, P I x\}$,

$\mathcal{B}_1 = \{(P, x, Q) \mid P, Q \in \mathcal{P}, P \neq Q, x \in \mathcal{B}, P I x, Q I x\}$,

$P_1 = (P, x), x_1 = (P, \bar{x}, Q), P_1 I_1 x_1 \Leftrightarrow P \in \{\bar{P}, \bar{Q}\}$.

Remark 1. Let G be the incidence graph of a (v, k, λ) block design $\mathcal{D} = (\mathcal{P}, \mathcal{B}, I)$ and $\mathcal{D}_1 = (\mathcal{P}_1, \mathcal{B}_1, I_1)$ be the incidence structure defined as above. Then we can describe the incidence structure \mathcal{D}_1 in the following way:

\mathcal{P}_1 is the set of all the edges of G ,

\mathcal{B}_1 is the set of all paths of length 2 in G with the first (and the last) vertex corresponding to a point of \mathcal{D} ,

$P_1 \in \mathcal{P}_1, x_1 \in \mathcal{B}_1, P_1 I_1 x_1$ if and only if the union of the corresponding edge and path of length 2 is a path of length 2 or 3.

Theorem 1. Let $\mathcal{D} = (\mathcal{P}, \mathcal{B}, I)$ be a (v, k, λ) block design and $\mathcal{D}_1 = (\mathcal{P}_1, \mathcal{B}_1, I_1)$ be the incidence structure defined as above. Then \mathcal{D}_1 is a $(v-1)\lambda$ -configuration $(v'_r, b'_k)_{(v-1)\lambda}$ with the following properties:

1. $v' = vr = bk$,
2. $b' = \binom{v}{2} \lambda$,
3. $k' = 2r$,
4. $r' = (v-1)\lambda$,
5. every pair of points is incident with exactly $(v-1)\lambda$ or λ blocks,
6. every pair of blocks is incident with exactly $2r$, r or 0 points.

Proof. It is obvious that $v' = vr = bk$. Two points of the design \mathcal{D} determine λ blocks in \mathcal{D}_1 , since every pair of points in (v, k, λ) block design is incident with exactly λ blocks. Therefore $b' = \binom{v}{2} \lambda$.

If a block x_1 in \mathcal{D}_1 corresponds to an ordered triple (P, x, Q) , then x_1 is incident with points which correspond to (P, y) or (Q, z) , $y, z \in \mathcal{B}$. Since the points P and Q in \mathcal{D} are incident with r blocks, x_1 is incident with $2r$ points.

A point $P_1 \in \mathcal{P}_1$ corresponding to an ordered pair (P, x) is incident with blocks which correspond to (P, y, Q) , $Q \in \mathcal{P}_1, y \in \mathcal{B}_1$. We can choose Q in $v-1$ ways, and each pair P, Q is incident with exactly λ blocks.

Let P_1 be a point in \mathcal{P}_1 which corresponds to an ordered pair (P, x) , $R_1 \in \mathcal{P}_1$ corresponds to (P, y) and $Q_1 \in \mathcal{P}_1$ corresponds to (Q, z) , $Q \neq P$. A block $x_1 \in \mathcal{B}_1$ is incident with P_1 if and only if it is incident with R_1 . On the other

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