

Listing all the minimal separators of a 3-connected planar graph

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Abstract

We present an efficient algorithm that lists the minimal separators of a 3-connected planar graph in $O(n)$ per separator.
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1. Introduction

In the last ten years, minimal separators have been increasingly studied in graph theory leading to many algorithmic applications [5,9,10,12].

For example, minimal separators are an essential tool to study the treewidth and the minimum fill-in of graphs. In [5], Bodlaender et al. conjecture that for a class of graphs with a polynomial number of minimal separators, these problems can be solved in polynomial time. Bouchitté and Todinca introduced the concept of potential maximal clique [2] and showed that, if the number of potential maximal cliques is polynomial, treewidth and minimum fill-in can be solved in polynomial time. They later showed [3] that if a graph has a polynomial number of minimal separators, it has a polynomial number of potential maximal cliques. Those results rely on deep understandings of minimal separators.

Extensive research has been performed to compute the set of the minimal separators of a graph [1,6,7,11]. Berry et al. [1] proposed an algorithm of running time $O(nm)$ per separator¹ that uses the concept of generating new minimal separators from a previous minimal separator S by finding the minimal separators contained in $S \cup N(x)$ for $x \in S$. This simple process can generate all the minimal separators of a graph. However, by using this algorithm a minimal separator can be generated many times.

The aim of this article is to address the problem of finding the minimal separators of a 3-connected planar graph G . In order to avoid the problem of recalculation, we define the set $\mathcal{S}_a(S, O)$ of the a, b -minimal separators S' for some b such that the connected component of a in $G \setminus S'$ contains the connected component of a in $G \setminus S$ but avoids the set O . Therefore, it is possible to ensure that a given minimal separator is never computed more than five times.

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¹ The authors only proved a running time of $O(n^3)$ but the actual bound is $O(nm)$ [8].

2. Definitions

Throughout this paper, $G = (V, E)$ is a 3-connected graph without loops with $n = |V|$ and $m = |E|$. For $x \in V$, $N(x) = \{y \mid (x, y) \in E\}$ and for $C \subseteq V$, $N(C) = \{y \notin C \mid \exists x \in C, (x, y) \in E\}$. When the sets A and B are disjoint, their union is denoted by $A \sqcup B$.

A set $S \subseteq V$ is a *separator* if $G \setminus S$ has at least two connected components, an *a, b-separator* if a and b are in different connected components of $G \setminus S$, an *a, b-minimal separator* if no proper subset of S is an *a, b-separator*. The connected component of a in $G \setminus S$ is $C_a(S)$. The component $C_a(S)$ is a *full connected component* if $N(C_a(S)) = S$. For an *a, b-minimal separator* S , both $C_a(S)$ and $C_b(S)$ are full. A set S is a *minimal separator* if there exist a and b such that S is an *a, b-minimal separator* or, which is equivalent, if it has at least two full connected components. An *a, *-minimal separator* of a graph $G = (V, E)$ is an *a, b-minimal separator* of G for some $b \in V$. The set of the *a, *-minimal separators* is denoted by \mathcal{S}_a and the set of the *minimal separators* of G is denoted by $\mathcal{S}(G)$.

It is possible to order the *a, *-minimal separators* in the following way:

$$S_1 \preceq_a S_2 \text{ if } C_a(S_1) \subseteq C_a(S_2).$$

The minimal separator S_1 is *closer* to a than S_2 . The set of *a, b-minimal separators* is a lattice for the relation \preceq_a [4] but we only need the following weaker lemma:

Lemma 1. *Let C be a set of vertices of a graph G inducing a connected subgraph of G , a be a vertex of C and b be a vertex of $G \setminus (C \cup N(C))$.*

*The neighbour S of $C_b(C \cup N(C))$ is an *a, b-minimal separator* such that C is a subset of $C_a(S)$ that is closer to a than any *a, b-minimal separator* S' such that C is a subset of $C_a(S')$.*

Proof. By construction, C is a subset of $C_a(S)$. By definition, the component $C_b(S)$ is full and since S is a subset of $N(C)$, the component $C_a(S)$ is also a full component which implies that S is an *a, b-minimal separator*.

Let S' be an *a, b-minimal separator* such that C is a subset of $C_a(S')$. Let p be a path in $C_b(S')$ with b as one of its ends. The vertices of S' are at least at distance 1 of C so the vertices of p are at least at distance 2 of C . Since S is a subset of $N(C)$, $p \cap S = \emptyset$. In other words p is a subset of $C_b(S)$ and $C_b(S') \subseteq C_b(S)$. This last inclusion implies that $C_a(S) \subseteq C_a(S')$ i.e. S is closer to a than S' . \square

For S an *a, *-minimal separator* and $O \subseteq V$, the set $\mathcal{S}_a(S, O)$ is the set of the *a, *-minimal separators* S' further from a than S and such that $O \cap C_a(S') = \emptyset$. If $x \in V$, the set $\mathcal{S}_a^x(S, O)$ is the set of $S' \in \mathcal{S}_a(S, O)$ such that $x \in C_a(S')$.

Remark 2. If $x \in S$, then $\mathcal{S}_a(S, O)$ is the disjoint union

$$\mathcal{S}_a(S, O \cup \{x\}) \sqcup \mathcal{S}_a^x(S, O).$$

More precisely, if $(S_i)_{i \in I}$ are the elements of $\mathcal{S}_a^x(S, O)$ closest to a , then

$$\mathcal{S}_a(S, O) = \mathcal{S}_a(S, O \cup \{x\}) \sqcup \left(\bigcup_{i \in I} \mathcal{S}_a(S_i, O) \right).$$

This gives the skeleton of an algorithm to compute the set $\mathcal{S}_a(S, O)$.

Remark 3. If S belongs to $\mathcal{S}_a^x(S, O)$, then $\mathcal{S}_a^x(S, O) = \mathcal{S}_a(S, O)$.

The algorithm is based on Remarks 2 and 3. To list \mathcal{S}_a , the algorithm computes the sets $\mathcal{S}_a(S, \emptyset)$ for every S closest to a in \mathcal{S}_a . During this calculation, it computes $\mathcal{S}_a(S, O)$ with $O \subseteq S$. To do so, it chooses x in $S \setminus O$ and calculates $\mathcal{S}_a^x(S, O)$ and $\mathcal{S}_a(S, O \cup \{x\})$. The set $\mathcal{S}_a^x(S, O)$ is itself a union of $\mathcal{S}_a(S_i, O)$. But to obtain such a decomposition, one needs to find the elements of $\mathcal{S}_a^x(S, O)$ closest to a , which the following proposition does.

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