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# Unique continuation type theorem for the self-similar Euler equations



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## ARTICLE INFO

### Article history:

Received 3 November 2014

Received in revised form 26 May 2015

Accepted 6 June 2015

Available online 28 July 2015

Communicated by Charles Fefferman

### MSC:

35Q31

76B03

76W05

### Keywords:

Self-similar Euler equations

Unique continuation theorem

Discretely self-similar solution

Inviscid MHD

## ABSTRACT

We prove a unique continuation type theorem for the self-similar Euler equations in  $\mathbb{R}^3$ , assuming the time periodicity. Namely, if a time periodic solution  $V(y, s)$  of the time dependent self-similar Euler equations has the property that  $V(0, s) = 0$  for all  $s \in [0, S_0]$ , where  $S_0$  is the time period, and  $y = 0$  is a local extremal point of  $V(y, s)$  near the origin, then,  $V(y, s) = 0$  for all  $(y, s) \in \mathbb{R}^3 \times [0, S_0]$ . A similar result holds for more general system with arbitrary coefficients, and also for the inviscid incompressible magnetohydrodynamic (MHD) system. As a consequence we obtain new criteria for the absence of the discretely self-similar singularities for the 3D Euler equations and the inviscid 3D MHD.

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## 1. The main theorems

### 1.1. The Euler equations

We are concerned on the Cauchy problem for the incompressible 3D Euler equations in  $\mathbb{R}^3$ :

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<http://dx.doi.org/10.1016/j.aim.2015.06.021>

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$$(E) \begin{cases} \frac{\partial v}{\partial t} + v \cdot \nabla v = -\nabla p, \\ \operatorname{div} v = 0, \\ v(x, 0) = v_0(x), \end{cases}$$

where  $v(x, t) = (v_1(x, t), v_2(x, t), v_3(x, t))$  is the velocity,  $p = p(x, t)$  is the pressure, and  $v_0(x)$  is the initial data satisfying  $\operatorname{div} v_0 = 0$ . For (E) it is well-known that for the initial data belonging to the standard Sobolev space,  $v_0 \in H^m(\mathbb{R}^3)$ ,  $m > 5/2$ , the local well-posedness holds (see e.g. [15]). The question of the finite time singularity for the local classical solution, however, is still an outstanding open problem (see [2,11]). For survey books or articles on the study of the finite time blow-up problem of (E) we refer e.g. [17,10,1]. For studies of the possibility of self-similar blow-up or its generalized version, discretely self-similar blow-up for the Euler and the Navier–Stokes equations there are previous studies (e.g. [19,4,6,5,7–9,21,22,18]). For studies of self-similar solutions to the other nonlinear equations we refer e.g. [13,14,12].

Once the velocity  $v(x, t)$  is known for a solution to (E), the pressure is determined by solving the Poisson equation  $\Delta p = -\operatorname{div} \operatorname{div}(v \otimes v)$ , and therefore, up to an addition of harmonic function, is given by the well-known formula

$$p(x, t) = -\frac{|v(x, t)|^2}{3} + \frac{1}{4\pi} P.V. \int_{\mathbb{R}^3} \frac{3(y \cdot v(y, t))^2 - |y|^2 |v(y, t)|^2}{|y|^5} dy. \quad (1.1)$$

Given a solution  $(v, p)$  of (E) and  $(x_*, T) \in \mathbb{R}^3 \times \mathbb{R}_+$ , we consider a canonical transform of  $(v, p) \mapsto (V, P)$ , called the self-similar transform, which is defined by

$$v(x, t) = \frac{1}{(T-t)^{\frac{\alpha}{\alpha+1}}} V(y, s), \quad p(x, t) = \frac{1}{(T-t)^{\frac{2\alpha}{\alpha+1}}} P(y, s), \quad (1.2)$$

where

$$y = \frac{x - x_*}{(T-t)^{\frac{1}{\alpha+1}}}, \quad s = \log \left( \frac{T}{T-t} \right), \quad (1.3)$$

and  $\alpha \neq -1$ . Note that our physical space–time domain  $\mathbb{R}^3 \times [0, T)$  is transformed into  $\mathbb{R}^3 \times [0, \infty)$ . Substituting (1.2)–(1.3) into (E), we obtain the following system for  $(V, P)$ :

$$(SSE)_\alpha \begin{cases} \frac{\partial V}{\partial s} + \frac{\alpha}{\alpha+1} V + \frac{1}{\alpha+1} (y \cdot \nabla) V + (V \cdot \nabla) V = -\nabla P, \\ \operatorname{div} V = 0, \\ V(y, 0) = V_0(y) = T^{\frac{\alpha}{\alpha+1}} v_0(T^{\frac{1}{\alpha+1}} y). \end{cases} \quad (1.4)$$

Let us temporarily denote the pressure  $P$  of (1.4) by  $\bar{P}$ . Taking operation  $\operatorname{div}$  on the first equation of (1.4) we obtain the Poisson equation  $\Delta \bar{P} = -\operatorname{div} \operatorname{div}(V \otimes V)$ . Since this equation determines (up to an addition of harmonic function) the self-similar pressure  $\bar{P}$  by the self-similar velocity  $V$ , simultaneous prescription of  $V$ ,  $P$  by (1.2) may cause the

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