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## Properly immersed submanifolds in complete Riemannian manifolds

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#### Abstract

We consider a properly immersed submanifold M in a complete Riemannian manifold N. Assume that the sectional curvature  $K^N$  of N satisfies  $K^N \ge -L(1 + \operatorname{dist}_N(\cdot, q_0)^2)^{\frac{\alpha}{2}}$  for some  $L > 0, 2 > \alpha \ge 0$  and  $q_0 \in N$ . If there exists a positive constant k > 0 such that  $\Delta |\mathbf{H}|^2 \ge k|\mathbf{H}|^4$ , then we prove that M is minimal. We also obtain similar results for totally geodesic submanifolds. Furthermore, we consider a properly immersed submanifold M in a complete Riemannian manifold N with  $K^N \ge -L(1 + \operatorname{dist}_N(\cdot, q_0)^2)^{\frac{\alpha}{2}}$  for some  $L > 0, 2 > \alpha \ge 0$  and  $q_0 \in N$ . Let u be a smooth non-negative function on M. If there exists a positive constant k > 0 such that  $\Delta u \ge ku^2$ , and  $|\mathbf{H}| \le C(1 + \operatorname{dist}_N(\cdot, q_0)^2)^{\frac{\beta}{2}}$  for some C > 0 and  $1 > \beta \ge 0$ , then we prove that u = 0 on M. By using the above result, we show that a non-negative biminimal properly immersed submanifold M in a complete Riemannian manifold N with  $0 \ge K^N \ge -L(1 + \operatorname{dist}_N(\cdot, q_0)^2)^{\frac{\alpha}{2}}$  is minimal. These results give affirmative partial answers to the global version of generalized Chen's conjecture for biharmonic submanifolds.

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### 1. Introduction

Theory of harmonic maps has been applied into various fields in differential geometry. Harmonic maps between two Riemannian manifolds are critical points of the energy functional  $E(\phi) = \frac{1}{2} \int_{M} |d\phi|^2 dv_g$ , for smooth maps  $\phi : (M^m, g) \to (N^n, h)$  from an *m*-dimensional

0001-8708/\$ - see front matter © 2013 Elsevier Inc. All rights reserved. http://dx.doi.org/10.1016/j.aim.2013.12.001 Riemannian manifold into an *n*-dimensional Riemannian manifold, where  $dv_g$  denotes the volume element of g. The Euler–Lagrange equation of E is

 $\tau(\phi) := \operatorname{Trace} \nabla d\phi = 0,$ 

where  $\tau(\phi)$  is called the *tension field* of  $\phi$ .

On the other hand, in 1983, J. Eells and L. Lemaire [15] proposed the study of *polyharmonic maps of order k*. In 1986, G.Y. Jiang [17] studied *biharmonic maps* (that is, polyharmonic maps of order 2) which are critical points of the *bi-energy functional* 

$$E_2(\phi) := \frac{1}{2} \int_M |\tau(\phi)|^2 dv_g.$$
(1)

The Euler–Lagrange equation of  $E_2$  is

$$\tau_2(\phi) := -\Delta^{\phi} \tau(\phi) - \sum_{i=1}^m R^N \big( \tau(\phi), d\phi(e_i) \big) d\phi(e_i) = 0,$$

where  $\Delta^{\phi} := \sum_{i=1}^{m} (\nabla_{e_i}^{\phi} \nabla_{e_i}^{\phi} - \nabla_{\nabla_{e_i} e_i}^{\phi})$ ,  $\nabla^{\phi}$  is the induced connection on the induced bundle  $\phi^{-1}TN$ ,  $R^N$  is the Riemannian curvature of N i.e.,  $R^N(X, Y)Z := [\nabla_X^N, \nabla_Y^N]Z - \nabla_{[X,Y]}^NZ$  for any vector fields X, Y and Z on N, and  $\{e_i\}_{i=1}^{m}$  is a local orthonormal frame field on M. The section  $\tau_2(\phi)$  in the induced bundle is called the *bi-tension field* of  $\phi$ . Clearly, harmonic maps are biharmonic maps.

If an isometric immersion  $\phi : (M, g) \to (N, h)$  is biharmonic, then *M* is called a *biharmonic* submanifold in *N*. In this case, we remark that the tension field  $\tau(\phi)$  of  $\phi$  is written as  $\tau(\phi) = m\mathbf{H}$ , where **H** is the mean curvature vector field of *M*.

For biharmonic submanifolds, there is an interesting problem, namely Chen's conjecture (cf. [8]).

#### **Conjecture 1.** Any biharmonic submanifold in $\mathbb{E}^n$ is minimal.

There are many affirmative partial answers to Conjecture 1 (cf. [8,9,13,14,16]). Conjecture 1 is solved completely if M is one of the following: (a) a curve [14], (b) a surface in  $\mathbb{E}^3$  [8], (c) a hypersurface in  $\mathbb{E}^4$  [13,16].

Note that, since there is no assumption of *completeness* for submanifolds in Conjecture 1, this is a problem of *local* differential geometry. Recently, Conjecture 1 was reformulated as a problem of *global* differential geometry (cf. [1,19,21,22]):

#### **Conjecture 2.** Any complete biharmonic submanifold in $\mathbb{E}^n$ is minimal.

On the other hand, Conjecture 1 was generalized as follows: Any biharmonic submanifold in a Riemannian manifold with non-positive sectional curvature is minimal (cf. [2–6]). This generalization is also a problem of local differential geometry. Y.-L. Ou and L. Tang [23] gave a counterexample of this conjecture (see [17] for an affirmative answer). With these understandings, it is natural to consider the following conjecture.

**Conjecture 3.** Any complete biharmonic submanifold in a Riemannian manifold with nonpositive sectional curvature is minimal. Download English Version:

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