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Partial differential equations

Explicit solutions in evolutionary genetics and applications

*Solutions explicites en génétique évolutive et applications*

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## ABSTRACT

We show that the solution to a nonlocal reaction–diffusion equation, present in evolutionary genetics, can be related explicitly to the solution of the heat equation with the same initial data. As a consequence, we show different possible scenario for the solution: it can be either well-defined for all time, or become extinct in finite time, or even be defined for no positive time. In the former case, we give the leading-order asymptotic behavior of the solution for large time, which is universal.

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## R É S U M É

Nous montrons que les solutions d'une équation de réaction–diffusion non locale, utilisée en génétique évolutive, peuvent être exprimées en fonction de la solution de l'équation de la chaleur avec même donnée initiale. Nous en déduisons plusieurs scénarios possibles pour la solution : elle peut, soit être définie pour tout temps, soit devenir identiquement nulle en temps fini, ou encore n'être définie pour aucun temps positif. Dans le premier cas, nous donnons le comportement asymptotique en temps grand de la solution, faisant intervenir un profil universel.

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## 1. Introduction

We consider *replicator–mutator* equations, that is nonlocal reaction–diffusion problems of the form

$$\partial_t u = \partial_{xx} u + \left( f(x) - \int_{\mathbb{R}} f(x) u(t, x) dx \right) u, \quad t > 0, x \in \mathbb{R},$$

where  $f(x)$  is a given weight. In this context,  $u(t, x)$  is the density of a population (at time  $t$  and per unit of a phenotypic trait) on a one-dimensional trait space, and  $f(x)$  represents the fitness. The nonlocal term then stands for the mean fitness at time  $t$ . In this Note, we focus on the case  $f(x) = x$ . We refer to [1] for explicit formulas when  $f$  is more generally of the form  $f(t, x) = a(t)x^j$  for  $j = 1$  or  $2$ . We therefore consider here

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$$\partial_t u = \partial_{xx} u + (x - \bar{u}(t))u, \quad t > 0, x \in \mathbb{R}, \quad (1)$$

where the nonlocal term is given by

$$\bar{u}(t) := \int_{\mathbb{R}} x u(t, x) dx. \quad (2)$$

In the context of evolutionary genetics, Eq. (1) was introduced by Tsimring et al. [7], where they propose a mean-field theory for the evolution of RNA virus populations on a fitness space. Little seems to be known concerning existence and behaviors of solutions in (1). Let us here mention the main result of Biktashev [2]: for compactly supported initial data, solutions converge, as  $t \rightarrow \infty$ , to a Gaussian profile, where the convergence is understood in terms of the moments of  $u(t, x)$ . One may then conjecture that this property remains valid for “arbitrary” initial data. In this work, we show in particular that this is completely false: tails of the initial data have a strong influence on solutions. This suggests that the model should probably be adapted, in the spirit of the modifications presented in [7,3–5].

To be relevant from the biological point of view, (1) is associated with some initial datum  $u_0$  that is everywhere non-negative, and such that

$$\int_{\mathbb{R}} u_0(x) dx = 1.$$

Formally  $\int_{\mathbb{R}} u(t, x) dx = 1$  for  $t \geq 0$ . Indeed, if we formally integrate (1) over  $x \in \mathbb{R}$ , we see that the total mass  $m(t) := \int_{\mathbb{R}} u(t, x) dx$  solves the Cauchy problem

$$\frac{d}{dt}(m(t) - 1) = \frac{d}{dt}m(t) = (1 - m(t))\bar{u}(t), \quad m(t) - 1|_{t=0} = 0. \quad (3)$$

Gronwall lemma yields  $m(t) = 1$  as long as  $\bar{u}(t)$  is finite. We show that the above formal argument may turn out to be completely wrong, in the sense that the solution may become extinct in finite time,  $u(t, x) = 0$  for all  $x \in \mathbb{R}$  and  $t \geq T$ . In this Note, we always assume  $u_0 \geq 0$ , with  $\int_{\mathbb{R}} u_0 = 1$ .

## 2. Explicit formula

**Theorem 2.1.** *As long as  $\bar{u}(t)$  is finite, the solution of (1) with initial data  $u_0$  is given by*

$$u(t, x) = \frac{e^{tx} \int_{\mathbb{R}} e^{-(x+t^2-y)^2/(4t)} u_0(y) dy}{\sqrt{4\pi t} \int_{\mathbb{R}} e^{ty} u_0(y) dy}. \quad (4)$$

To sketch the proof of this result, we introduce the solution of two different equations with the same initial datum,

$$\partial_t w = \partial_{xx} w, \quad t > 0, x \in \mathbb{R}; \quad w|_{t=0} = u_0, \quad (5)$$

which is the standard heat equation, and

$$\partial_t v = \partial_{xx} v + xv, \quad t > 0, x \in \mathbb{R}; \quad v|_{t=0} = u_0. \quad (6)$$

Formally, we have

$$v(t, x) = u(t, x) e^{\int_0^t \bar{u}(s) ds}.$$

By integrating over  $x \in \mathbb{R}$  and then integrating in time, we see that so long as  $\int_0^t \bar{v}(s) ds > -1$ , we have

$$u(t, x) = \frac{v(t, x)}{1 + \int_0^t \bar{v}(s) ds}. \quad (7)$$

Note that this computation ceases to be valid if  $\bar{u}(t)$  (or, equivalently,  $\bar{v}(t)$ ) becomes infinite. Now  $v$  and  $w$  can be related thanks to a modification of the celebrated Avron–Herbst formula, known in the context of the Schrödinger equation with an external electric field (essentially,  $t$  is replaced by  $it$ ; see, e.g., [6]):

$$v(t, x) = w(t, x + t^2) \exp\left(tx + \frac{t^3}{3}\right). \quad (8)$$

**Theorem 2.1** then follows from the explicit formula for the heat kernel; we refer to [1] for more details.

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