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On the metric theory of *p*-adic continued fractions

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Abstract

An analogue of the regular continued fraction expansion for the *p*-adic numbers for prime *p* was given by T. Schneider, such that for *x* in $p\mathbb{Z}_p$, i.e. the open unit ball in the *p*-adic numbers, we have uniquely determined sequences $(b_n \in \{1, 2, ..., p-1\}, a_n \in \mathbb{N})$ (n = 1, 2, ...) such that

$$x = \frac{p^{a_0}}{b_1 + \frac{p^{a_1}}{b_2 + \frac{p^{a_2}}{b_3 + \frac{p^{a_3}}{b_4 + \dots}}}}.$$

A sample result that we prove is that if p_n (n = 1, 2, ...) denotes the sequences of rational primes, we have

$$\lim_{N \to \infty} \frac{1}{N} \sum_{n=1}^{N} a_{p_n}(x) = \frac{p}{p-1},$$

almost everywhere with respect to Haar measure. In the case where p_n is replaced by n this result is due to J. Hirsh and L. C. Washington. The proofs rely on pointwise subsequence and moving average ergodic theorems.

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1. Introduction

Extending the idea of the Euclidean algorithm, for a real number *x*, let

$$x = c_0 + \frac{1}{c_1 + \frac{1}{c_2 + \frac{1}{c_3 + \frac{1}{c_4 + \frac{1}{c_4 + \frac{1}{c_5 + \frac{1}{c_4 + \frac{1}{c_5 +$$

denote its *regular continued fraction expansion*, which is also written more compactly as $[c_0; c_1, c_2, ...]$. The terms $c_0, c_1, ...$ are called the *partial quotients* of the continued fraction expansion and the sequence of rational truncates

$$[c_0; c_1, \ldots, c_n] = \frac{p_n}{q_n}$$
 $(n = 1, 2, \ldots),$

are called the *convergents* of the continued fraction expansion.

For a real number y let $\{y\}$ denote its fractional part. We now consider the particular ergodic properties of the Gauss map, defined on [0, 1] by

$$Tx = \begin{cases} \left\{ \frac{1}{x} \right\} & \text{if } x \neq 0; \\ 0 & \text{if } x = 0. \end{cases}$$

Notice that $c_n(x) = c_{n-1}(Tx)$ (n = 1, 2, ...). The dynamical system (X, β, μ, T) where X denotes [0, 1], β is the σ -algebra of Borel sets on X, $\mu = \gamma$ is the measure on (X, β) defined for any A in β by

$$\gamma(A) = \frac{1}{\log 2} \int_A \frac{dx}{x+1},$$

and T is the Gauss map is ergodic. See [24], [8, pp. 165–177], or Chapter 4 of [10] for more details. This point of view can be used to prove results like the following.

Suppose $F : \mathbb{R}_{>0} \to \mathbb{R}$ is continuous, increasing and such that

$$\int_0^1 |F(c_1(x))| dx < \infty.$$

For each $n \in \mathbb{N}$ and arbitrary real numbers d_1, \ldots, d_n we set

$$M_{F,n}(d_1,\ldots,d_n)=F^{-1}\left[\frac{F(d_1)+\cdots+F(d_n)}{n}\right].$$

Then we have

$$\lim_{n \to \infty} M_{F,n}(c_1(x), \dots, c_n(x)) = F^{-1} \left[\int_0^1 F(c_1(x)) dx \right],$$

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