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Complete pivoting strategy for the left-looking Robust Incomplete Factorization preconditioner

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ABSTRACT

In this paper, we have used a complete pivoting strategy to compute the left-looking version of *RIF* preconditioner. This pivoting is based on the complete pivoting strategy of the *IJK* version of Gaussian Elimination process. There is a parameter α to control the pivoting process. To study the effect of α on the quality of the left-looking version of *RIF* preconditioner with complete pivoting strategy, we have used ten different values of this parameter. In the numerical experiments section, the quality of the left-looking version of *RIF* preconditioner with complete pivoting strategy has been compared to the quality of the right-looking version of this preconditioner.

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1. Introduction

Consider the linear system of equations of the form

$$Ax = b$$
,

(1)

where the coefficient matrix $A \in \mathbb{R}^{n \times n}$ is nonsingular, large, sparse and nonsymmetric and also $x, b \in \mathbb{R}^n$. Krylov subspace methods can be used to solve this system [1].

An implicit preconditioner *M* for system (1) is an approximation of matrix *A*, *i.e.*, $M \approx A$. If *M* is a good approximation of *A*, then it can be used as the right preconditioner for system (1). In this case, instead of solving system (1), it is better to solve the right preconditioned system

$$AM^{-1}u = b; \qquad x = M^{-1}u,$$

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by the Krylov subspace methods. *ILU* preconditioners are examples of the implicit preconditioners. This type of preconditioners are in the form of M = LDU where *L* and U^T are unit lower triangular matrices and *D* is a diagonal matrix. Different versions of Gaussian Elimination process [1] can be used to compute the *ILU* preconditioners. In this case, one should work with the Schur-Complement matrices, explicitly and the computation of *L* and *U* depends on to each other.

Every matrix M which is an approximation of A^{-1} , *i.e.*, $M \approx A^{-1}$, can be considered as an explicit preconditioner of system (1). If M is a good approximation of A^{-1} , then it is recommended to solve the right preconditioned system AMu = b, where x = Mu, instead of system (1). The *AINV* preconditioner is an example of explicit preconditioners [2]. This preconditioner is computed when we apply dropping strategies in the *A*-biconjugation process. There are two left and right-looking versions for the *A*-biconjugation process. Therefore, there are two left and right-looking versions for the *AINV* preconditioner.

Robust Incomplete Factorization preconditioner or *RIF* is an example of *ILU* preconditioners [3]. This preconditioner is computed as the by-product of the *AINV* preconditioner. This means that there are also two left and right-looking versions for this preconditioner. To compute both versions of the *RIF* preconditioner, we do not need to work with the Schur-Complement matrices, explicitly and the *L* and *U* are computed, independently.

In [4], Bollhöfer and Saad proved that at the beginning of step *i* of the right-looking version of *A*-biconjugation process, one can implicitly compute the whole Schur-Complement matrix which is obtained at the end of step i - 1 of the *IJK* version of Gaussian Elimination process. This was the main key to extend the complete pivoting strategy of the *IJK* version of Gaussian elimination process to the right-looking versions of *AINV* and *RIF* preconditioners [5,6].

Consider the *i*th step of the left-looking version of *A*-biconjugation process. At the end of this step, it is only possible to implicitly compute the first column and the first row of the Schur-Complement matrix which is obtained at the end of step i - 1 of the *IJK* version of Gaussian Elimination process. This relation, enabled us to extend the complete pivoting strategy of the *IJK* version of Gaussian Elimination process to the left-looking version of *AINV* preconditioner [7].

In this paper, we present the complete pivoting strategy of the left-looking version of *RIF* preconditioner.

This paper is organized as follows. In Section 2, we review the left-looking version of *RIF* preconditioner and in Section 3, we present a complete pivoting strategy for this preconditioner. In Section 4, the quality of both the left and the right-looking versions of *RIF* preconditioner with complete pivoting strategy will be compared.

2. Left-looking version of RIF preconditioner

Suppose that matrix A has the

$$A = \overline{L}\overline{D}\overline{U},$$

(2)

factorization where \bar{L} and \bar{U}^T are unit lower triangular matrices and \bar{D} is a diagonal matrix. This factorization can be computed by Algorithm 1, which is the *IJK* version of Gaussian Elimination process [1]. In this algorithm, matrices \bar{L} and \bar{U} are computed column-wise and row-wise, respectively. Suppose that $S^{(0)} = A$. At the end of step i - 1 of this algorithm, the relation



holds where $\bar{g}_k \in \mathbb{R}^{(n-k)\times 1}$ and $\bar{h}_k \in \mathbb{R}^{1\times (n-k)}$, for $1 \leq k \leq i-1$, are the already computed columns and rows of matrices \bar{L} and \bar{U} , respectively. The submatrix $(\bar{S}^{(i-1)})_{j,k\geq i}$ in (3) is termed the Schur-Complement matrix of step i-1.

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