



Robust error estimation in energy and balanced norms for singularly perturbed fourth order problems



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ABSTRACT

We consider singularly perturbed fourth order problems in two dimensions. Under assumptions on the structure of their solutions, we construct layer-adapted meshes and prove for a mixed-method convergence and supercloseness in the associated energy norms as well as convergence in balanced norms.

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1. Introduction

We mainly consider the singularly perturbed plate bending problem given by the fourth-order differential equation

$$\varepsilon^2 \Delta^2 u - b \Delta u + (c \cdot \nabla) u + du = f \quad \text{in } \Omega := (0, 1)^2, \quad (1a)$$

where $b \geq b_0 > 1$, $d - \frac{1}{2}(\operatorname{div} c + \Delta b) \geq \delta > 0$ and $f \in L^2(\Omega)$ are smooth functions, with the boundary conditions

$$u = \frac{\partial u}{\partial n} = 0 \quad \text{on } \Gamma := \partial\Omega. \quad (1b)$$

This is a model for the so-called clamped plate. With the usual weak formulation we immediately have a unique solution $u \in H_0^2(\Omega)$. But a conforming finite element discretisation requires C^1 -elements, see i.e. [1], which are less popular in 2d. Therefore, mixed or non-conforming methods are widely used. In this paper we want to study mixed methods.

Using in the non-singularly perturbed case ($\varepsilon = 1$) a p -th order finite-element approximation for u and $w = \Delta u$ results in an error estimate

$$\|u - u_h\|_1 + h \|w - w_h\|_0 \leq Ch^p \|u\|_{p+1} \quad (2)$$

for the discrete solutions u_h and w_h on a standard shape-regular mesh with $p \geq 2$, see, for instance, [2,3]. We use the standard notation of Sobolev spaces, where $\|\cdot\|_0$ is the L^2 -norm, $|\cdot|_k$ the seminorm in H^k and $\|\cdot\|_k$ the full H^k -norm. Furthermore, we denote by $\langle u, v \rangle_D$ the L^2 -scalar product over a domain $D \subset \Omega$. If $D = \Omega$ we drop the subscript. In the singularly perturbed

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case the boundary layers of problem (1), even if the layers are weak, lead to $\|u\|_{p+1} \rightarrow \infty$ for $\varepsilon \rightarrow 0$ and $p \geq 2$. Thus, the estimate (2) becomes worthless in this scenario.

In this paper we use layer-adapted meshes with a number of cells of order N^2 . Then we are able to prove for problem (1) with $b > 0$ the robust error estimate (see Section 3)

$$\|u - u_h\|_1 + \varepsilon \|w - w_h\|_0 \leq C(\varepsilon^{1/2} + N^{-1} \ln N)(N^{-1} \ln N)^{p-1}, \tag{3}$$

where here and further on C denotes a generic constant independent of ε and N . This result can be improved using supercloseness properties for \mathcal{Q}_p -elements to robust p -th order convergence. Finally, we also estimate the error in a so-called balanced norm.

For non-conforming methods, some robust error estimates on standard meshes are known [4–7] but characterised by a low order (1/2). Layer-adapted meshes are to our knowledge only investigated in combination with the C^0 -interior penalty method [8], resulting in an error estimate similar to (3). For our mixed method however, we can additionally prove supercloseness for \mathcal{Q}_p -elements and estimate in a balanced norm. Both of these results are open questions for the C^0 -interior penalty method.

In Section 4 we apply the techniques of Section 3 to two other problems. First we investigate a problem modelling the simply supported plate: Eq. (1a) together with the boundary conditions

$$\tilde{u} = \Delta \tilde{u} = 0 \quad \text{on } \Gamma. \tag{1c}$$

In Section 4.2 we consider the “reaction–diffusion-type” problem

$$\varepsilon^2 \Delta \tilde{u} + d \tilde{u} = f \quad \text{in } \Omega$$

with $d \geq \delta > 1$ and the boundary conditions (1b) or (1c). This problem is characterised by strong boundary layers and we have to modify the techniques from Section 3.

If $b \geq b_0 > 0$, in a rectangular domain we have $u \in H_0^2 \cap H^4$, see [9] and $\tilde{u} \in H_0^1 \cap H^4$, see [10]. The same holds for \tilde{u} if $d \geq \delta > 0$.

2. Solution decomposition and meshes

Asymptotic expansions for higher-order elliptic singularly perturbed problems are known in smooth domains [11]. In this case only boundary layers exist. From second-order problems it is known, that in domains with corners additional corner layers arise. The proof of the existence of solutions of the corner-layer equations for reaction–diffusion problems is extremely complicated, see [12, Section 3.2]. For higher-order problems this is an open problem.

We simply prescribe the layer structure analogously to the results for second-order equations and assume (requiring additional smoothness of the solution and the data) that the solution u of problem (1a) + (1b) can be decomposed into a smooth part, boundary layers and corner layers:

$$u = S + E_1 + E_2 + E_3 + E_4 + E_{12} + E_{23} + E_{34} + E_{41} = S + \sum_{k \in \mathcal{I}} E_k, \tag{4}$$

where $\mathcal{I} = \{1, 2, 3, 4, 12, 23, 34, 41\}$. Here S stands for the smooth part, E_k with $k = 1, 2, 3, 4$ for a boundary layer and E_k with $k = 12, 23, 34, 41$ for a corner layer. More precisely, we assume

$$\begin{aligned} \|\partial_x^i \partial_y^j S\|_0 &\leq C, & |\partial_x^i \partial_y^j E_1(x, y)| &\leq C \varepsilon^{1-i} e^{-x/\varepsilon}, \\ |\partial_x^i \partial_y^j E_2(x, y)| &\leq C \varepsilon^{1-j} e^{-y/\varepsilon}, & |\partial_x^i \partial_y^j E_{12}(x, y)| &\leq C \varepsilon^{1-i-j} e^{-x/\varepsilon} e^{-y/\varepsilon}, \end{aligned}$$

and similarly for the other components of the decomposition. Similarly, we assume a decomposition for \tilde{u} with

$$\tilde{u} = \tilde{S} + \sum_{i \in \mathcal{I}} \tilde{E}_i \tag{5}$$

where

$$\begin{aligned} \|\partial_x^i \partial_y^j \tilde{S}\|_0 &\leq C, & |\partial_x^i \partial_y^j \tilde{E}_1(x, y)| &\leq C \varepsilon^{2-i} e^{-x/\varepsilon}, \\ |\partial_x^i \partial_y^j \tilde{E}_2(x, y)| &\leq C \varepsilon^{2-j} e^{-y/\varepsilon}, & |\partial_x^i \partial_y^j \tilde{E}_{12}(x, y)| &\leq C \varepsilon^{2-i-j} e^{-x/\varepsilon} e^{-y/\varepsilon}, \end{aligned}$$

and similarly for the other components of the decomposition.

Remark 2.1. In the following numerical analysis we need the estimates from above assumptions in a $L^2(D)$ -sense for non-empty subdomains $D \subset \Omega$ for $i + j = p + 1$ and in the supercloseness analysis additionally for $i = 1, 2$ and $j = p + 1$ as well as $i = 1$ and $j = p + 2$ and the pairs with interchanged i and j .

The pointwise estimates for the layer components are essentially only needed for $i + j = 0, 1$ and in the supercloseness analysis additionally for $i = 1$ and $j = p + 1$, and $i = p + 1$ and $j = 1$.

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