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Modeling the tensile steel reinforcement strain in RC-beams subjected to cycles of loading and unloading



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ABSTRACT

Tension stiffening affects the strain distribution along the tensile reinforcement in a cracked reinforced concrete beam and in the tensile concrete between cracks. It also affects the overall stiffness and hence the deflection of the beam. In this paper, the results of experiments on eleven reinforced concrete beams with reinforcement ratios between 0.56% and 0.88% are reported. The overall strain in the reinforcement and the load-deflection response under both monotonic loading and cycles of loading and unloading were measured for each beam. Based on the experimental results, a model of the effective strain in the reinforcement is presented and is used to assess the effective moment of inertia of reinforced concrete beams subjected to in-service monotonic loading. Measurements from the test beams were used to calibrate a model of the steel-concrete interface damage caused by cycles of loading and unloading. The comparisons between predicted and measured overall stiffness and load-deflection responses show the validity of the present model.

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1. Introduction

To ensure the serviceability of reinforced concrete structures, deflection control is an important design objective. Excessive concrete cracking and excessive deformation are one of the most common causes of damage and result in large annual cost to the construction industry.

Reinforced concrete beams in service are usually cracked, as the tensile strength of concrete is low [1]. Under normal service conditions, the concrete between the primary cracks is able to continue to carry tensile stress, due to the transfer of forces from the tensile reinforcement to the concrete through bond. This phenomenon is known as *tension stiffening*, which affects the beam's stiffness and hence its deflection, especially for lightly reinforced concrete beams [2]. As a result, the tension stiffening effect must be accurately modeled to simulate the in-service behavior of reinforced concrete structures, particularly under repeated loading [3].

Most of existing models for the flexural reinforced concrete beams deal with monotonic loading. The smeared-crack model is a popular way to simulate the tension stiffening effect. In this approach, an average stress-strain relation is considered for the

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whole tension area to account for the "average" deformation response of a cracked member [4]. A modified constitutive relationship for the steel reinforcement [5,6] or an updated descending branch of the tensile stress-strain curve for concrete have been developed and implemented in finite element analyses [5,7–12]. In addition, the so-called microscopic models based on the bondslip mechanism and discrete cracking have been proposed by Floegl and Mang [13], Gupta and Maestrini [14], and Choi and Cheung [15].

Alternatively, several empirical models have been widely accepted by engineers in design for the control of deflections, involving determination of the effective moment of inertia (I_e) for a cracked member under monotonic loading. Branson developed a well-known model [16], which was adopted by the ACI Building Code [17]. Branson's equation gives a weighted average of the uncracked and cracked stiffness of the reinforced concrete cross-section at any load level, but it has been shown to overestimate the effective stiffness of lightly reinforced concrete beams and slabs [2]. In comparison with Branson's model, Bischoff suggested a weighted average of the uncracked and cracked flexibility of reinforced concrete cross-sections [18,19]. Experiments carried out on reinforced slabs having reinforcement ratios ranging between 0.18% and 0.84% demonstrated that Bischoff's model is more accurate than Branson's model for lightly reinforced concrete members [2]. A statistical study that employed data from nine



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Nomenclatur	e
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As	area of the tensile reinforcement	<i>z</i> _{nc}	lever-arms of the internal forces on the uncracked
$A_{\rm tc.eff}$	effective area of the tensile concrete		cross-section
$D_{\rm ccc}$	scalar damage variable	$Z(\mathbf{X})$	lever-arms of the internal forces between cracks
Ec	elastic modules of concrete	$\Delta_{\rm m}$	measured overall lengthening of the tensile reinforce-
E _s	elastic modules of steel		ment
Ι	moment of inertia	α	interpolation shape coefficient for effective strains of
Ia	average moment of inertia		reinforcement
Icr	moment of inertia of the fully cracked section	γ	evolution parameter of D_{ccc}
I _e	effective moment of inertia	δ	displacement from LVDT to the tensile reinforcement
Iuncr	moment of inertia of the uncracked section	8 _{ce}	effective strain of the top fiber compressive concrete
$I(\mathbf{x})$	moment of inertia at a point <i>x</i> from the crack within the	Ece.cr	effective strain of the top fiber compressive concrete at
× /	transfer length	,	the moment of cracking
Lelem	average crack spacing	Ece.v	effective strain of the top fiber compressive concrete at
Lt	transfer length	,5	the moment of yielding
Ma	applied moment	ε_{s}^{p}	permanent residual strain of tensile reinforcement
M _{cr}	cracking moment	Esav	average strain of tensile reinforcement
M _v	vield moment	Ese	effective strain of tensile reinforcement
M(x)	bending moment along the transfer length	Ese cr	effective strain of the reinforcement at the moment of
Nc	total number of cracks spacing in the pure bending re-	se,er	cracking
	gion	Ese.v	effective strain of the reinforcement at the moment of
а	thickness of the reinforcement layers in the cross-		yielding
	sections	<i>E</i> snc	reinforcement strain at the uncracked section (where
b	width of the rectangle cross-section		$x \ge L_t$)
d	effective depth of the tensile reinforcement	$\varepsilon_{s}(x)$	reinforcement strain between cracks
d_{b}	bar diameter	E _{s0}	reinforcement strain at the cracked section (where
$f_{\rm c}$	compressive strength of concrete		x = 0)
$f_{\rm cu}$	compressive cube strength of concrete	$\varepsilon_{\rm tc}(x)$	tensile concrete strain between cracks
f_{tc}	tensile strength of concrete	$\epsilon_{ m ts,max}$	concrete strain at the level of tensile reinforcement sec-
f_y	yield strength of reinforcement		tion at $x = L_t$
g(x)	interpolation function between cracks	θ	beam's rotation
h	height of the rectangle cross-sections	χ _{exp}	measured curvature of the reinforced concrete beam
l_0	length of the neutral axis in the measure region	χpredicted	predicted curvature of the reinforced concrete beam
l_1	length of the reinforcement in the measure region	$\bar{\chi}$	average ratio of $\chi_{\text{predicted}}/\chi_{\text{exp}}$
l_2	length measured with LVDT in the measure region	v _{perm,cr}	irreversible deflection of the cracked reinforced con-
l _{s, max}	maximum cracks spacing		crete beam
l _{s, min}	minimum cracks spacing	ho	reinforcement ratio $\rho = A_s/(bd)$
п	modular ratio (E_s/E_c)	$ ho_{ m min}$	minimum reinforcement ratio
r	radius of curvature of the deflected centroidal axis	$\sigma_{ m s0}$	stress of the tensile reinforcement at the cracked section
r _e	effective radius of curvature	$\sigma_{ m s,ccc}$	critical axial steel stress at the cracked location related
x	distance from the cracks		to cover-controlled cracking
y_{oa}	average depth of the neutral between cracks	$\bar{\sigma}$	relative stress intensity of the tensile reinforcement at
$y_{\rm oc}$	depth of the neutral axis of the fully cracked section		the cracked section
y _{onc}	depth of the neutral axis of the uncracked section	$\chi(x)$	curvature at a point <i>x</i> from the crack within the transfer
$y_{o}(x)$	neutral axis depth along the transfer length		length
Zc	lever-arms of the internal forces on the cracked cross-		
	section		

experimental programs involving a total of 80 specimens showed a similar conclusion that the Branson's model overestimated the stiffness significantly for reinforcement ratios ranging between 0.4% and 0.8% [20]. In fact, the accuracy of deflection predictions made using all the techniques decreased significantly for beams with small reinforcement ratios [20]. In this paper, an alternative empirical model to Bischoff and Branson's models is proposed. Contrary to Bischoff and Branson's models, which are both based on weighted averages of uncracked and cracked moment of inertia, the model proposed is based on the local measurement and modeling of the steel reinforcement strains in the tensile zone.

Due to the tension stiffening effect, the distribution of the tensile strain along the reinforcement bars between the cracks is not uniform, but rises to a maximum at each crack and drops to a minimum mid-way between adjacent cracks. In some experimental studies, strain gauges glued to the bar surface have been used to measure steel strain [21]. However, this is not entirely satisfactory, as the bond properties of the reinforcement bars are affected by the strain gauges [22]. Alternatively, magnetic methods and fiberoptical strain measurements have been used to measure the distribution of strain in the reinforcing steel [22,23]. In this paper, instead of measuring the distribution of reinforcing steel strain, a simple apparatus was adopted to measure the overall steel reinforcement strain over a length of the cracked tension zone containing two or more primary cracks. The mid-span deflection of the test beam was also measured. In total, eleven reinforced concrete beams were tested. Using the experimental results, a model for the overall steel reinforcement strain, termed the effective steel strain, has been developed for monotonic loading. The moment of inertia can then be deduced by homogenization across the height of the reinforced concrete beam, thereby providing an alternative way to calculate the effective moment of inertia (I_e) . The performance of the new model is compared to results from Bischoff's model results for different reinforcement ratio.

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