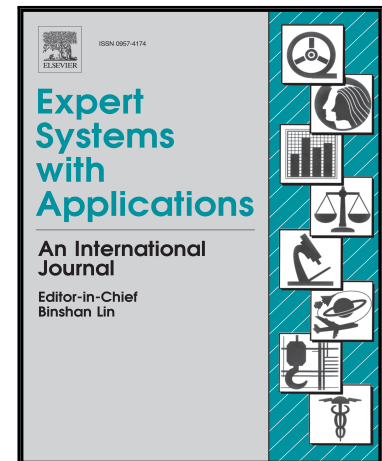


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Integrated Trust Based Control System for Multirobot Systems:
Development and experimentation in real environment

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Highlights

- Novel trust evaluation model is proposed that integrates reinforcement learning with heuristics.
- Developed an integrated trust based control system for multirobot environment.
- Proposed system is evaluated against the benchmark systems in literature.
- Tested the proposed control system in real world environment with successful outcomes.

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