

Accepted Manuscript

New Robot Navigation Algorithm for Arbitrary Unknown Dynamic Environments based on Future Prediction and Priority Behavior

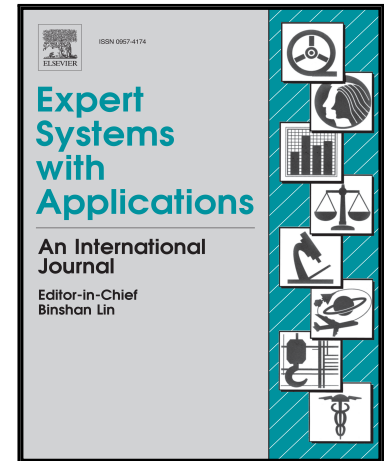
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PII: S0957-4174(17)30380-9
DOI: [10.1016/j.eswa.2017.05.059](https://doi.org/10.1016/j.eswa.2017.05.059)
Reference: ESWA 11351

To appear in: *Expert Systems With Applications*

Received date: 18 April 2016
Revised date: 8 May 2017
Accepted date: 24 May 2017

Please cite this article as: Farah Kamil , Tang Sai Hong , Weria Khaksar , Mohammed Yasser Moghrabiah , Norzima Zulkifli , Siti Azfanizam Ahmad , New Robot Navigation Algorithm for Arbitrary Unknown Dynamic Environments based on Future Prediction and Priority Behavior, *Expert Systems With Applications* (2017), doi: [10.1016/j.eswa.2017.05.059](https://doi.org/10.1016/j.eswa.2017.05.059)



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Highlights

- Establish a new sensor-based path planning in an unknown dynamic environment.
- This approach depends on future prediction behavior and priority behavior
- Successful in handling complex dynamic environments with various obstacle shapes

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