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A multi-view model for visual tracking via correlation filters

Xin Li, Qiao Liu, Zhenyu He, Hongpeng Wang, Chunkai Zhang, Wen-Sheng Chen

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Highlights

- The first contribution is proposing to combine features from distinct views to do tracking via correlation filters. The fusion method is induced by minimizing the KullbackLeibler (KL) divergence under a probabilistic framework.
- The second contribution is proposing a simple and effective scale evaluation model.

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