# Relation between the skew energy of an oriented graph and its matching number 

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#### Abstract

Let $G^{\sigma}$ be an oriented graph with skew adjacency matrix $S\left(G^{\sigma}\right)$. The skew energy $\varepsilon_{S}\left(G^{\sigma}\right)$ of $G^{\sigma}$ is the sum of the norms of all eigenvalues of $S\left(G^{\sigma}\right)$ and the skew rank $\operatorname{sr}\left(G^{\sigma}\right)$ of $G^{\sigma}$ is the rank of $S\left(G^{\sigma}\right)$. In this paper, it is proved that $\varepsilon_{S}\left(G^{\sigma}\right) \geq 2 \mu(G)$ for an arbitrary connected oriented graph $G^{\sigma}$ of order $n$, where $\mu(G)$ is the matching number of $G$, and the equality holds if and only if $G$ is a complete bipartite graph $K_{\frac{n}{2}, \frac{n}{2}}$ with partition $(X, Y)$ of equal size and $\sigma$ is switching-equivalent to the elementary orientation of $G$ which assigns all edges the same direction from vertices of $X$ to vertices of $Y$. As an application, we prove that $\varepsilon_{S}\left(G^{\sigma}\right) \geq \operatorname{sr}\left(G^{\sigma}\right)$ for an oriented graph $G^{\sigma}$ and the equality holds if and only if $G$ is the disjoint union of some copies of $K_{2}$ and some isolated vertices.


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## 1. Introduction

Analogous to the definition of the energy of a simple undirected graph, Adiga et al. [1] defined the skew energy $\varepsilon_{S}\left(G^{\sigma}\right)$ of an oriented graph $G^{\sigma}$, with adjacency matrix $S\left(G^{\sigma}\right)$, to be the sum of the norms of all eigenvalues of $S\left(G^{\sigma}\right)$. Since $S\left(G^{\sigma}\right)$ is skew symmetric, an eigenvalue of $S\left(G^{\sigma}\right)$ is either a pure imaginary number or 0 , thus the norm of an eigenvalue of $S\left(G^{\sigma}\right)$ is a singular value of $S\left(G^{\sigma}\right)$ and $\varepsilon_{S}\left(G^{\sigma}\right)$ also equals the sum of all singular values of $S\left(G^{\sigma}\right)$.

Adiga et al. [1] established a low bound and an upper bound for the skew energy of an oriented graph $G^{\sigma}$ in terms of the order and size of $G^{\sigma}$ as well as the maximum degree of its underlying graph.

Proposition 1.1 (Theorem 2.5, [1]). Let $G^{\sigma}$ be an oriented graph of $G$ with $n$ vertices, $m$ arcs and maximum degree $\Delta$. Then

$$
\sqrt{2 m+n(n-1) p^{\frac{2}{n}}} \leq \varepsilon_{S}\left(G^{\sigma}\right) \leq \sqrt{2 m n} \leq n \sqrt{\Delta}
$$

where $p=\left|\operatorname{det}\left(S\left(G^{\sigma}\right)\right)\right|$.
The upper bound $n \sqrt{\Delta}$ of $\varepsilon_{S}\left(G^{\sigma}\right)$ is called the optimum skew energy. It was proved that if an oriented graph $G^{\sigma}$ has the optimum skew energy, then $G$ is a $\Delta$-regular graph. Hence a natural question was posed in [1]: Which k-regular graphs $G$ on $n$ vertices have an orientation $\sigma$ such that $\varepsilon_{S}\left(G^{\sigma}\right)=n \sqrt{k}$ ? For a small $k$, some results have been obtained. If $k \leq 2$, the authors in [1] characterized the $k$-regular graphs which has an orientation such that $\varepsilon_{S}\left(G^{\sigma}\right)=n \sqrt{k}$. Gong and Xu [10] characterized all 3-regular oriented graphs with optimum skew energy. Chen et al. [5] and Gong et al. [11] independently determined the underlying graphs of all 4-regular oriented graphs with optimum skew energy and gave orientations of these underlying

[^0]graphs such that the skew energies of the resultant oriented graphs indeed attain optimum. Chen et al. [6] obtained some lower bounds of the skew energy of $G^{\sigma}$, which improves the known lower bound obtained by Adiga et al. [1]. For more recent results on skew adjacency matrix or skew energy of oriented graphs we refer the reader to [3,4,9,13-18].

In this paper, we study the relation between the skew energy $\varepsilon_{S}\left(G^{\sigma}\right)$ of an oriented graph $G^{\sigma}$ and its matching number. In Section 2, we prove that $\varepsilon_{S}\left(G^{\sigma}\right) \geq 2 \mu(G)$ for a connected oriented graph $G^{\sigma}$ with matching number $\mu(G)$. In Section 3 , we characterize the oriented graphs $G^{\sigma}$ with equality $\varepsilon_{S}\left(G^{\sigma}\right)=2 \mu(G)$, proving that the equality holds if and only if $G$ is a complete bipartite graph with equal bipartite $(X, Y)$ and $\sigma$ is switching-equivalent to the elementary orientation of $G$ which assigns all edges the same direction from vertices of $X$ to those of $Y$. As an application, we prove that $\mathcal{E}_{S}\left(G^{\sigma}\right) \geq \operatorname{sr}\left(G^{\sigma}\right)$ for an oriented graph $G^{\sigma}$ and the equality holds if and only if $G$ is the disjoint union of some copies of $K_{2}$ and some isolated vertices.

## 2. A lower bound of the skew energy of an oriented graph in terms of matching number

Let $G$ be a simple graph of order $n$ with vertex set $V(G)=\left\{v_{1}, v_{2}, \ldots, v_{n}\right\}$ and edge set $E(G)$. Based on $G$, we define an oriented graph $G^{\sigma}$ obtained from $G$ by assigning each edge of $G$ a direction, where $G$ is called the underlying graph of $G^{\sigma}$. The skew adjacency matrix associated to $G^{\sigma}$, written as $S\left(G^{\sigma}\right)$, is defined to be an $n \times n$ matrix ( $s_{i j}$ ) such that $s_{i j}=1$ if there is an arc from $v_{i}$ to $v_{j}, s_{i j}=-1$ if there is an arc from $v_{j}$ to $v_{i}$ and $s_{i j}=0$ otherwise. The skew rank of $G^{\sigma}$, denoted by $\operatorname{sr}\left(G^{\sigma}\right)$, is defined to be the rank of $S\left(G^{\sigma}\right)$, which is even since $S\left(G^{\sigma}\right)$ is skew symmetric. Let $C_{k}^{\sigma}=u_{1} u_{2} \cdots u_{k} u_{1}$ be an oriented cycle. The sign of $C_{k}^{\sigma}$, denoted by $\operatorname{sgn}\left(C_{k}^{\sigma}\right)$, is defined to be the sign of $\left(\Pi_{i=1}^{k-1} s_{u_{i} u_{i+1}}\right) s_{u_{k} u_{1}}$. An even oriented cycle $C_{2 m}^{\sigma}$ is called evenly-oriented (resp., oddly-oriented) if its sign is positive (resp., negative). If every even cycle in $G^{\sigma}$ is evenly-oriented, then $G^{\sigma}$ is called evenly-oriented. An induced subgraph $H^{\sigma}$ of $G^{\sigma}$ is an oriented graph such that $H$ is an induced subgraph of $G$ and each arc of $H^{\sigma}$ has the same orientation as that in $G^{\sigma}$. For $U \subseteq V\left(G^{\sigma}\right), G^{\sigma}-U$ is the subgraph obtained from $G^{\sigma}$ by deleting all vertices in $U$ and all incident arcs. A vertex of a graph $G^{\sigma}$ is called pendant if it is only adjacent to one vertex. A set $M$ of edges in $G$ is a matching if every vertex of $G$ is incident with at most one edge in $M$. It is a perfect matching if every vertex of $G$ is incident with exactly one edge in $M$. We denote by $\mu(G)$ the matching number of $G$ (i.e. the number of edges of a maximum matching in $G$ ). We respectively use $P_{n}, C_{n}, K_{n}, K_{p, n-p}$ to denote a path, a cycle, a complete graph and a complete bipartite graph on $n$ vertices.

Let $s_{j}(C)$ denote a singular value of a complex matrix $C$. Day and So [8] obtained an inequality about a partitioned matrix $C$ as follows.
Lemma 2.1 (Theorem 2.2, [8]). For a partitioned matrix $C=\left[\begin{array}{cc}A & X \\ Y & B\end{array}\right]$, where both $A$ and $B$ are square matrices, we have $\sum_{j} s_{j}(A)+\sum_{j} s_{j}(B) \leq \sum_{j} s_{j}(C)$. Equality holds if and only if there exist unitary matrices $U$ and $V$ such that $\left[\begin{array}{cc}U A & U X \\ V Y & V B\end{array}\right]$ is positive semi-definite.

Lemma 2.2 (Corollary 2.4, [8]). For a partitioned matrix $C=\left[\begin{array}{cc}A & X \\ Y & B\end{array}\right]$, where both $A$ and $B$ are square matrices, we have $\sum_{j} s_{j}(A) \leq \sum_{j} s_{j}(C)$. Equality holds if and only if $X, Y$ and $B$ are all zero matrices.

Applying Lemma 2.2 to an induced subgraph $H^{\sigma}$ of an oriented graph $G^{\sigma}$, we obtain a similar result as Theorem 3.1 of [8].
Lemma 2.3. Let $H^{\sigma}$ be an induced subgraph of an oriented graph $G^{\sigma}$. Then $\varepsilon_{S}\left(H^{\sigma}\right) \leq \varepsilon_{S}\left(G^{\sigma}\right)$ and equality holds if and only if $E(H)=E(G)$.

We write $G^{\sigma}-H^{\sigma}$ for the oriented graph obtained from $G^{\sigma}$ by deleting all vertices of an induced subgraph $H^{\sigma}$ and all arcs incident with $H^{\sigma}$. This is also called the complement of $H^{\sigma}$ in $G^{\sigma}$. Moreover, when no arcs of $G^{\sigma}$ join $H^{\sigma}$ and its complement $G^{\sigma}-H^{\sigma}$, we write $G^{\sigma}=H^{\sigma} \oplus\left(G^{\sigma}-H^{\sigma}\right)$. If $E$ is a set of arcs of $G^{\sigma}$ such that $G^{\sigma}-E$, the subgraph of $G^{\sigma}$ obtained from $G^{\sigma}$ by deleting all arcs in $E$, is the union of two complementary induced subgraphs, then $E$ is called a cut set of $G^{\sigma}$. Theorem 3.4 of [8] proved that the energy of a spanned subgraph of a simple graph $G$ does not exceed that of $G$ when a cut set of $G$ is deleted. A similar result also holds for oriented graphs.

Lemma 2.4. If $E$ is a cut set of an oriented graph $G^{\sigma}$ then $\varepsilon_{S}\left(G^{\sigma}-E\right) \leq \varepsilon_{S}\left(G^{\sigma}\right)$.
Proof. Since $E$ is a cut set of $G^{\sigma}, G^{\sigma}-E=H^{\sigma} \oplus K^{\sigma}$, where $H^{\sigma}$ and $K^{\sigma}$ are two complementary induced subgraphs of $G^{\sigma}$. Applying Lemma 2.1 to $S\left(G^{\sigma}\right)=\left[\begin{array}{cc}S\left(H^{\sigma}\right) & * \\ * & S\left(K^{\sigma}\right)\end{array}\right]$, we obtain the desired conclusion.

Theorem 3.6 of [8] proved that $\mathcal{E}(G-E)<\mathcal{E}(G)$ if $E$ is a cut set of a graph $G$ which forms a star, where $\mathcal{E}(G)$ denotes the energy of $G$ (see [8] for its definition). This result can also be translated to oriented graphs. The proof of the following lemma is analogous to that of Theorem 3.6 of [8], thus omitted.

Lemma 2.5. If $E$ is a cut set of an oriented graph $G^{\sigma}$ such that the arcs of $E$ form an oriented star, then $\varepsilon_{S}\left(G^{\sigma}-E\right)<\varepsilon_{S}\left(G^{\sigma}\right)$.
Now, we apply Lemma 2.4 to obtain a lower bound of the skew energy of an oriented graph in terms of matching number.

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