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Enhanced Particle-filtering Framework for Vessel Segmentation and Tracking

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#### ACCEPTED MANUSCRIPT

#### Highlights

- In this paper, we propose a robust vessel segmentation and tracking method that is based on a particle filtering framework.
- To enhance the segmentation and tracking performance, the importance density of the particle filter is localized by estimating the translation of an object's boundary.
- To minimize problems of degeneracy and sample impoverishment in the particle filter, a newly proposed weighting policy is investigated, which is used to update of particle's weight with the goal of attaining a higher level of accuracy.
- Compared with the existing method, the proposed algorithm exhibited better performance in terms of segmentation and tracking.
- In particular, for a limited number of iterations, the performance difference between the two algorithms increased.
- Moreover, the proposed method demonstrated a tendency toward lower degeneracy and sample impoverishment.

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