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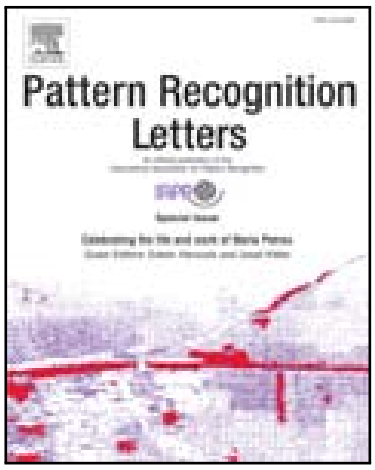

Modelling depth for nonparametric foreground segmentation using RGBD devices

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