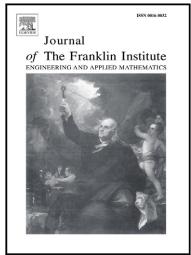
# Author's Accepted Manuscript

Gain Scheduling Output Feedback Control of Linear Plants with Actuator Saturation

Xiaojun Ban, Fen Wu



www.elsevier.com/locate/jfranklin

PII: S0016-0032(15)00240-9

DOI: http://dx.doi.org/10.1016/j.jfranklin.2015.06.005

Reference: FI2371

To appear in: Journal of the Franklin Institute

Received date: 21 August 2014 Revised date: 16 December 2014

Accepted date: 8 June 2015

Cite this article as: Xiaojun Ban, Fen Wu, Gain Scheduling Output Feedback Control of Linear Plants with Actuator Saturation, *Journal of the Franklin Institute*, http://dx.doi.org/10.1016/j.jfranklin.2015.06.005

This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting galley proof before it is published in its final citable form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.

## **ACCEPTED MANUSCRIPT**

# Gain Scheduling Output Feedback Control of Linear Plants with Actuator Saturation

Xiaojun Ban\*

Center for Control Theory and Guidance Technology Harbin Institute of Technology, Harbin 150001, P. R. China E-mail: banxiaojun@hit.edu.cn

Fen Wu

Department of Mechanical and Aerospace Engineering North Carolina State University, Raleigh, NC 27695, USA E-mail: fwu@ncsu.edu

#### Abstract

From a gain-scheduling perspective, we will study the output feedback control problem for linear systems with some of control channels subject to actuator saturation. This includes the scenario of all actuator saturation as a special case. A feedback controller, expressed in the form of linear fractional transformation, is proposed to guarantee regional stability of the closed-loop system and provide disturbance/error attenuation measured in  $\mathcal{L}_2$  gain. The resulting synthesis condition is formulated as linear matrix inequalities (LMIs) and can be solved efficiently. Moreover, explicit formulas are derived to calculate controller gains, which reduces the computational cost compared to the method of directly solving the LMI-based condition. Numerical examples are provided to demonstrate the proposed saturation control approach.

**Keywords** Actuator saturation; gain-scheduling; output feedback; regional stability; disturbance attenuation;  $\mathcal{L}_2$  gain.

Accel

<sup>\*</sup>Corresponding author. Phone: (0451) 86402224-8206, Fax: (0451) 86402689.

<sup>&</sup>lt;sup>0</sup>Xiaojun Ban's work is supported by the National Natural Science Foundation of China (NSFC) under Grant No. 61304006 and 61273095. Fen Wu's work is supported in part by the NSF Grant CMMI-0800044.

### Download English Version:

# https://daneshyari.com/en/article/4975172

Download Persian Version:

https://daneshyari.com/article/4975172

<u>Daneshyari.com</u>