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## **Q4** Safety impacts of bicycle infrastructure: A critical review

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#### ABSTRACT

Problem and method:This paper takes a critical look at the present state of bicycle infrastructure treatment safety16research, highlighting data needs.Safety literature relating to 22 bicycle treatments is examined, including17findings, study methodologies, and data sources used in the studies.Some preliminary conclusions related to18research efficacy are drawn from the available data and findings in the research.Results and discussion: While19the current body of bicycle safety literature points toward some defensible conclusions regarding the safety20and effectiveness of certain bicycle treatments, such as bike lanes and removal of on-street parking, the vast21majority treatments are still in need of rigorous research.Fundamental questions arise regarding appropriate22exposure measures, crash measures, and crash data sources.Practical applications: This research will aid transpor-23tation departments with regard to decisions about bicycle infrastructure and guide future research efforts toward24understanding safety impacts of bicycle infrastructure.25

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#### 37 1. Introduction and background

Increased use of active transportation can make direct and indirect 38 39contributions toward addressing both the health concerns arising from 40 sedentary lifestyles and other societal transportation issues including congestion, pollution, and equity problems (Barnes & Schlossberg, 41 2013; MacDonald, 2007; Pucher & Renne, 2003; Saelensminde, 2004; 42 WHO, 2002). While 10.9% of trips in the United States were made by 43 walking or by bicycling during 2009 (PBIC, 2010), those modes made 44 up 14% of all traffic fatalities nationally during the same year (NHTSA, 452014a, 2014b). The data suggest an over-representation of walking 46 and biking in crash fatalities; however, quantifying the risk associated 47 48 with walking and cycling is difficult (PBIC, 2014).

For biking to be a viable, healthy mode, travelers choosing the mode 49should be able to do so without either the fear or reality of excessive 50danger associated with their choice. Safety for non-motorized road 5152users is the responsibility of multiple parties, including the user and other travelers, but also transportation planners and engineers through 53facility design (AASHTO, 2010; Metroplan, 2010). Therefore, this paper 5455focuses on the safety research used to discern appropriate designs and countermeasures that enhance bicycle safety. 56

Local governments and transportation agencies are constantly making decisions about how best to achieve their goals given the limited resources available to them. When faced with the decision of how to design or re-design a facility to improve bicycle safety, knowing the expected safety performance of the alternatives can help decision- 61 makers allocate resources cost-effectively. With greater information 62 about the range of effects of a safety treatment, those effects can be 63 calibrated to the local situation and the expected safety performance 64 can be estimated. 65

#### 1.1. Highway Safety Manual

In the United States, the predominant guide for assessing the effects of 67 safety treatments is the Highway Safety Manual (HSM). The HSM 68 employs a simple method for assessing roadway safety treatment effec- 69 tiveness based on data inputs and analytical study (AASHTO, 2010). In 70 the highway safety method, safety performance is a function of a base 71 rate multiplied by a series of crash modification factors (CMFs), such that: 72

Safety Performance = 
$$(Base Rate) \times (CMF)_1 \times (CMF)_2 \times ... \times (CMF)_n.$$
(1)

74

66

The base rate term represents the expected number of crashes in the absence of special safety treatments, encompassing both risk and 75 exposure. Each CMF term in Eq. (1) is a multiplier that modifies the 76 number of expected crashes from the base rate according to the 77 expected safety effectiveness of a specific treatment. These CMFs 78 are normally estimated by observing changes in crash rates in the 79 presence/absence of a particular treatment using either longitudinal 80 (before/after) or cross-sectional (treatment/control) type studies. 81 These studies must, however, take into account a variety of confounding 82 effects including, but not limited to, temporal regression-to-the-mean 83 or changes in base rates over time. CMFs less than 1 indicate an 84

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expected safety improvement (crash decrease); CMFs greater than 1 in-85 86 dicate an expected safety decrease (increase in crashes). Exposure may be expressed in a variety of ways using a variety of data, including num-87 88 ber of trips, vehicle miles traveled (VMT), hours of exposure, number of roads crossed, number of left turns made, etc. Risk is expressed as the 89 probability of a crash occurring per unit of travel (i.e., distance, time, 90 91 trips, and turns) under specific conditions, presuming that the unit of 92 travel under the set of conditions represents exposure.

93 To develop or use crash modification factors, the HSM requires a 94significant amount of data for implementation of its quantitative 95approach to safety. These data needs can be classified into three main categories (AASHTO, 2010): crash data, exposure data, and roadway 96 characteristics data. The HSM requires several specific attributes for 97 98 crash data: year, location, type, severity level, relationship to intersection, and distance from intersection. For vehicular crashes, exposure data 99 requires Average Annual Daily Traffic (AADT) data, as well as minor and 100 major street AADT for safety evaluations occurring at intersections. The 101 roadway characteristic data requirements are detailed, and the needs dif-102fer depending on facility type. All three data categories and their attri-103 butes need to be customized for pedestrian and bicycle safety research. 104

Motor-vehicle traffic volumes and crash data are collected regularly 105 by transportation agencies. The sample sizes necessary for developing 106 107 and using CMFs for automobile-related safety interventions are often 108 available, given the large traffic volumes, significant number of vehicle crashes, crash occurrences, and known facility design features. 109However, as discussed throughout this paper, cycle-vehicle collisions 110 are fairly rare events compared to vehicle-vehicle crashes, few data 111 112 sources are available for bicycle traffic volumes, and cyclist-vehicle exposure data (combined volumes by mode and relative movement 113 data) are generally not readily available. These issues make the develop-114 ment of CMFs for vehicle-bicycle safety treatments difficult. 115

#### 116 1.2. Principles behind non-motorized roadway safety treatments

While motor vehicles are not the only threat to bicyclist safety
(Aultman-Hall & Kaltenecker, 1999; Moritz, 1997, 1998; Teschke et al.,
2012), collisions with motor vehicles are the main cause of thousands
of non-motorized road users' deaths each year, as well as many more
injuries (NHTSA, 2014a, 2014b). For this reason, most measures aimed
at improving the safety of non-motorized users focus on mitigating
the dangers posed by conflicts with motorized traffic.

For a safety treatment to reduce number or severity of collisions between a motor vehicle and a non-motorized road user, the treatment generally needs to address one or more of the following objectives (expanded from Retting, Ferguson, & McCartt, 2003):

- Increasing the separation of bicycles and motor vehicles in time and space
- 130 Increasing the visibility and conspicuity of non-motorized users
- 131 Improving lines of sight between the modes
- Reducing the number of interactions between modes (e.g., number of driveways)
- 134 Reducing motor-vehicle speeds

135

Maintaining a physical separation between bicycles and motor 136vehicles (space and/or time) will prevent the two modes from colliding. 137138 Separated bikeways and bicycle signal phases are employed to maintain a separation between modes in space and time. Increased separation in 139time and space at any given time will also increase the reaction time 140 available to both modes to avoid an impending collision. Hence, bicycle 141 lanes enhance this separation. Increasing bicycle and vehicle visibility 142gives motorists and cyclists more time to react and avoid a collision. 143For example, bike boxes that allow cyclists to proceed to the head of a 144 queue at an intersection are designed to increase cyclists' visibility at 145key locations. Reducing motor-vehicle speeds increases motorists' and 146 147 cyclists' reaction time, reducing the frequency of collisions. When collisions do occur, the reduced speed differential between vehicle and 148 cyclist reduces the severity of the collisions and probability of severe 149 injury and death (Leaf & Preusser, 1999). A variety of traffic calming 150 design measures, use of bicycle boulevards, and construction of round-151 abouts can decrease motor-vehicle speeds (Brude & Larsson, 2000). 152

Given the arguments outlined above, the goal of roadway safety 153 design for non-motorized users would seem to be to maximize the 154 criteria discussed above. In reality, there are complex interactions 155 between the criteria, and roadway designers often have to seek 156 compromises. For example, increasing visual complexity in the roadway 157 environment has been shown to decrease vehicle speeds. Shared space 158 schemes employed in Auckland, New Zealand, actually are designed to 159 minimize the separation between various road users in an effort to re- 160 duce motor-vehicle speeds by adding complexity to the environment 161 (Karndacharuk, Wilson, & Dunn, 2013). Hence, increased separation 162 may increase vehicle speeds and collision severity. 163

Physically separating bicyclists from motorized traffic by diverting 164 them to multi-use trails may create a visibility issue at locations 165 where the trail crosses roads. The separation of motor vehicles and 166 bicyclists can also be problematic at major intersections when bicycles 167 are often merged with vehicles to cross busy streets. Diverting cyclist 168 traffic to a multi-use trail that is shared with pedestrians, pets, and 169 other trail users may increase a cyclist's risk of falling or being involved 170 in a collision with another trail user (Aultman-Hall & Kaltenecker, 171 1999). Separation may also be inappropriate from a transportation 172 planning perspective when access to specific activities and surrounding 173 destinations is the main goal of bicycle use (e.g., commuting to work, 174 shopping) because the separation typically limits accessibility by the 175 bicycle mode. It is difficult to balance the integration/separation of 176 cyclist and vehicle traffic, while ensuring that the system provides 177 positive mobility benefits to all users and also ensuring comparative 178 safety for all system users. 179

#### 1.3. Developing crash modification factors

Over the past several decades, many studies have been conducted to 181 evaluate the potential safety impacts of bicycle treatments. However, 182 bicycle safety research conducted to date has been insufficient to 183 support the development of crash modification factors for treatment 184 installation because the research does not satisfy the data requirements 185 outlined in the Highway Safety Manual (AASHTO, 2010). As noted 186 earlier, cycle-vehicle collisions are fairly rare, extensive cycle activity 187 monitoring is not undertaken, and solid cyclist-vehicle exposure data 188 are generally not readily available. This paper reviews a body of 189 literature (i.e., technical reports, journal papers, and conference papers) 190 related to bicycle safety treatments and the reported potential effective- 191 ness. The research team reviewed the treatment details, research 192 methods, data sources, findings, and research conclusions presented in 193 each of these papers. This research seeks to identify common inferences 194 in the literature related to treatment effectiveness, and identify gaps in 195 existing bicycle safety data and methods that currently prevent the 196 generation of statistically significant crash modification factors. Finally, 197 this research identifies the kinds of data that will be necessary for 198 generating bicycle intervention crash modification factors using the 199 HSM method and recommends how data issues could be addressed in 200 the future. 201

#### 1.4. State of bicycle safety research

In the absence of base crash rate data necessary for the HSM method, 203 many researchers and transportation agencies have developed other 204 research methods to estimate safety effects of bicycle and pedestrian 205 treatments. Some studies employ simple before–after methodology, 206 possibly incorporating a comparison group to control for area- 207 wide changes in risk or exposure. Such studies do not incorporate data 208 on exposure and crash risk for specific treatment locations and may 209

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