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## Effects of the calibration procedure on the metrological performances of stereophotogrammetric systems for human movement analysis

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## ABSTRACT

This paper proposes a methodology for evaluating the effect of different stereophotogrammetric system calibration procedures on the calculation of marker-based kinematics information. The methodology, based on calibrating the system using data recorded from capture volumes of different sizes and in trials of different durations, was applied to two different systems. The calibration data were used to reconstruct the static and dynamic position and orientation in space of a rigid wand carrying markers in known positions. The inaccuracies in the reconstruction of distances and angles from the wand markers were independent on the calibration data, with average errors lower than 1.7 mm and 0.7°, respectively. Similar results were obtained from human gait data, with the highest variations observed in the transverse plane kinematics and in the foot segment, suggesting that successful calibration procedures of different durations and performed in different volumes did not affect the metrological performance of the investigated systems.

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### 1. Introduction

In the past decades, movement analysis techniques have been increasingly used to study human/animal motion [1–4]. Besides emerging techniques based on MIMU systems [5–8] and markerless approaches [9–12], the majority of the human movement analysis techniques are based on the measurement of three-dimensional posi-

tion of active or passive markers attached to the body skin, as obtained using a stereophotogrammetric approach. These markers are used to track the three-dimensional pose of the subject's bones, to which they are uniquely associated through a procedure called anatomical calibration [1]. Once the pose of a bone is known, the joint kinematics, i.e. the relative orientation between adjacent bones, are estimated and used to quantify movement alterations and limitations and to plan and evaluate a patient's treatment.

Although stereophotogrammetric systems (SS) are routinely used in research and clinical practice, relevant data suffer from a number of inaccuracy sources that could hin-

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**Nomenclature**

|          |                                     |       |                                 |
|----------|-------------------------------------|-------|---------------------------------|
| Abd/Add  | abduction/adduction                 | SS#2  | stereophotogrammetric system #2 |
| CMC      | coefficient of multiple correlation | SS    | stereophotogrammetric system    |
| ECS      | embedded coordinate system          | STA   | soft tissue artefact            |
| Flx/Ext  | flexion/extension                   | SV-LH | sub-volume left and high        |
| GV       | global volume                       | SV-LL | sub-volume left and low         |
| Int/Ext  | internal/external rotation          | SV-RH | sub-volume right and high       |
| Inv/Eve  | inversion/eversion                  | SV-RL | sub-volume right and low        |
| Plt/Drts | plantar/dorsiflexion                |       |                                 |
| RF       | refinement frames                   |       |                                 |
| SS#1     | stereophotogrammetric system #1     |       |                                 |

der the sought information. The main sources of inaccuracy are: (i) the soft-tissue artefacts (STA) due to the relative movement between the markers attached on the skin and the underlying bones [13]; (ii) errors in the anatomical calibration due to markers' misplacement [14]; and (iii) instrumental errors [15]. Whereas the first two errors are intrinsic in the use of skin markers, the third one is due to the use of a camera-based approach and it has been found to be dependent on: the number and position of the cameras [16,17], their lens distortion [18], the dimension of the capture volume [19,20] and, last but not least, the algorithms used for the reconstruction of a marker's 3D position [21], i.e. the marker tracking.

The effect of instrumental error on marker tracking have been originally quantified by placing a goniometer equipped with retroreflective markers in different zones of the capture volume [19,22], imposing known static angles and random trajectories to the goniometer and then comparing its outputs with the angles measured with a SS. More recently, a T-pendulum has been used for similar purposes, and it has been shown that increased angular velocities of the body under observation can decrease the accuracy of angle measurements [23]. Shifting the problem closer to the human movement analysis, a 'walking test' was proposed in [24,25]: a subject was asked to walk at a self-selected speed within the capture volume holding an aluminium bar equipped with two markers and eight SSs were tested. They showed that the systems with low noise generally seem to exhibit better performances. Subsequently, the Movement Analysis Laboratory (MAL) test has been proposed [26], which is based on recording the position of a rod carrying a 2-marker cluster, manually rotated around its tip either following a pseudo circle or two orthogonal arches. The MAL test allows to quantify both precision and accuracy associated with SS-based measurements (respectively related to random and systematic errors).

The need to move cameras, the changes in light conditions, or the presence of reflecting objects call for frequent recalibration of a stereophotogrammetric system within the human movement analysis context. As a matter of fact, the SS manufacturers recommend performing a calibration before each session of data collection. This calibration procedure is performed manually by the operator, who usually has to freely move an object within the camera capture volume, and is hence dependent on the modality of its exe-

cutio. The evaluation of possible errors associated with the calibration procedure of the SS has been the object of a few investigations. In [27,28] two different methodologies to quantify the intrinsic error of the calibration algorithms that reconstruct the marker time histories have been introduced. Despite providing interesting results concerning the quantification of the calibration algorithm errors, they are by definition not useful in quantifying the variations following the need of a system recalibration. More recently, a custom-made robot, which could be used to move a L-frame equipped with retroreflective markers to perform the calibration, has been devised [16]. The authors showed that the use of the robot can significantly improve the accuracy of the calibration. However, the robot was moved within a capture volume ( $180 \times 180 \times 150 \text{ mm}^3$ ) that is much smaller than those needed in human movement analysis. Last but not least, the effects that the calibration procedure has on the metrological performances of a SS – to the authors' knowledge – have not been fully exploited.

The aim of this paper is to propose a methodology that can be used to evaluate the effect of different calibration procedures, as executed on data capture from different acquisition volumes and of longer or shorter duration, and to use it to quantify the relevance of the effects that those calibration procedures can have on the estimate of the joint kinematics. The proposed methodology will be applied to two different SSs.

**2. Material and methods***2.1. Calibration procedure*

Two stereophotogrammetric systems were set up in two centres: an 8-camera Vicon system MX-series (SS#1 installed at the Movement Analysis and Robotics Laboratory 'MARLab' of the Children Hospital 'Bambino Gesù', Palidoro – Rome, Italy) and a 10-camera Vicon system T-series (SS#2 installed at The University of Sheffield, Sheffield – United Kingdom). The data collection was performed with a sampling frequency of 200 Hz and the marker position reconstruction was performed using the software Vicon Nexus 1.8.5 (Vicon Motion Systems, Oxford – UK). It is worth noticing that having a different number of cameras in the two systems does not affect the accuracy of the calibration, since at least six cameras have been used

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