

## Accepted Manuscript

Title: Optical force sensing principle based on transparent elastomer with a rough surface

Author: L.E. Helseth

PII: S0924-4247(17)30483-1

DOI: <http://dx.doi.org/doi:10.1016/j.sna.2017.07.033>

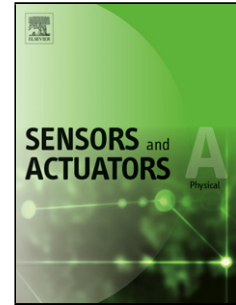
Reference: SNA 10228

To appear in: *Sensors and Actuators A*

Received date: 21-3-2017

Revised date: 15-7-2017

Accepted date: 18-7-2017



Please cite this article as: L.E.Helseth, Optical force sensing principle based on transparent elastomer with a rough surface, *Sensors and Actuators: A Physical*<http://dx.doi.org/10.1016/j.sna.2017.07.033>

This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting proof before it is published in its final form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.

# Optical force sensing principle based on transparent elastomer with a rough surface

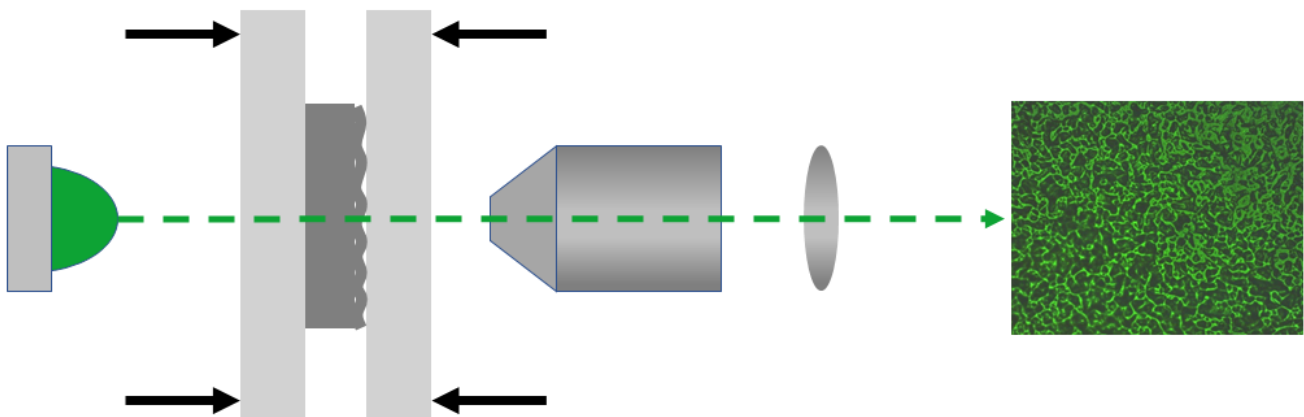
*L.E. Helseth*

*Department of Physics and Technology, Allegaten 55, 5020 Bergen, University of Bergen, Norway*

**Phone: 47 5588307**

**Email: [Lars.Helseth@ift.uib.no](mailto:Lars.Helseth@ift.uib.no)**

## Table of Contents Graphic



Download English Version:

<https://daneshyari.com/en/article/5008047>

Download Persian Version:

<https://daneshyari.com/article/5008047>

[Daneshyari.com](https://daneshyari.com)