



# Distributed multi-agent based coordinated power management and control strategy for microgrids with distributed energy resources



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## ABSTRACT

In this paper, a distributed peer-to-peer multi-agent framework is proposed for managing the power sharing in microgrids with power electronic inverter-interfaced distributed energy resources (DERs). Recently, the introduction of electric vehicles (EVs) has gained much popularity by offering vehicle-to-home (V2H) technologies to support the sustainable operation of microgrids. Since microgrids often exhibit volatile characteristics due to natural intermittency and uncertainty, it is necessary to maintain the balancing of generation and demand through the proper management of power sharing. Therefore, the main purpose of this paper is to design an agent-based control framework to ensure the coordinated power management within the microgrids through effective utilization of EVs. The required agent communication framework is adhered to the graph theory where the control agents interact with each other using local as well as neighboring information and their distributed coordination effectively steers the proportional sharing of real and reactive powers among the inverter-interfaced EVs to maintain the stability of microgrids. The well known Ziegler-Nichols method is used to tune the proportional-integral (PI) controller of the inner current control loop within each individual control agent to perform necessary shared control tasks. A microgrid with solar photovoltaic (PV) and V2H systems is chosen to illustrate the results and it is seen that the proposed scheme improves the system performance in a smarter way through information exchange. Furthermore, the proposed framework is also validated by a comparison with an existing traditional approach and it is found that, the proposed scheme provides excellent robust and faster performance.

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## 1. Introduction

In present days, the vehicle-to-home (V2H) technologies equipping with the battery energy storage systems (BESSs) are most valuable electrification schemes due to the ever growing global concerns of environmental issues. A number of electric vehicles (EVs) across the world are currently utilized as alternative distributed energy resources (DERs) along with the renewable energy sources (RESs) in microgrids. As a result, multiple power electronic inverters need to be installed in conjunction with those EVs to support the DC-AC energy conversion and deliver adequate amount of energy from the DERs.

When multiple EVs are integrated into the microgrids through power electronic inverters, the control and management of multiple inverters adversely suffer from stability problems and power quality issues due to the lack of proper coordination among the control devices. Moreover, as microgrids are composed of various

control equipments, a lack of information exchange among different control schemes causes an imbalance between the generation and the load demand due to improper sharing of powers. However, a well managed power sharing strategy can be achieved at the expense of degrading the voltage and frequency regulation and vice versa [1]. Therefore, in order to provide reliable energy supply from the DERs, the real and reactive powers need to be shared proportionally from the EVs while maintaining the desired frequency and voltage within the microgrids as well as to keep the balance between the generation and the demand.

A number of centralized and decentralized droop control strategies have been proposed for inverter-interfaced EVs to achieve the desirable sharing of active and reactive powers [2–5] to maintain the voltage and frequency of the system. However, the conventional centralized droop control schemes reported several drawbacks due to a high cost of communication from central controller to all single equipment and these methods also possess risk of single-point failures. Moreover, often the existing hierarchical decentralized power management schemes [6–8] are unable to handle the fast-varying loads due to the slow dynamic response

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## Nomenclature

<i>BESS</i>	battery energy storage system	$R_0, R_1, R_2$	battery resistors
<i>DER</i>	distributed energy resource	$C_1$	battery capacitor
<i>EV</i>	electric vehicle	$E_m$	internal voltage of battery
<i>ICT</i>	information and communication technology	$m$	modulation index in time-variant mode
<i>KCL</i>	Kirchoff's current law	$I_1$	current through the battery
<i>KVL</i>	Kirchoff's voltage law	$\tau_1$	$R_1 C_1$
<i>MAS</i>	multi-agent system	$M_d, M_q$	switching functions of generation modulation index in $dq$ -frame
<i>PI</i>	proportional integral	$\alpha_f$	firing angle
<i>PV</i>	photovoltaic	$I_d, I_q$	$dq$ -frame inverter current
<i>PWM</i>	pulse width modulation	$R$	line resistance
<i>RES</i>	renewable energy source	$L$	equivalent inductance of filter and line
<i>SOC</i>	state-of-charge	$\omega$	angular frequency
<i>V2H</i>	vehicle-to-home	$\theta$	angle between d-axis and magnetic axis of phase-a winding
$\alpha$	diode current constant	$E_d, E_q$	$dq$ -frame voltage
$k$	Boltzmann's constant	$v_{dc}$	voltage across the capacitor ( $C_{dc}$ )
$q$	charge of electron	$I_{dc}, V_{c1}$	dc current and voltage
$T_c$	temperature of PV cell in Kelvin	$S_{discharging}$	discharging energy
$A$	ideality factor of p-n junction diode	$P_b$	battery capacity
$I_s$	saturation current	$P_0, Q_0, V_0$	nominal set point of ZIP load model
$V_{pv}$	output voltage of PV array	$A_g$	adjacency matrix
$R_s, R_{sh}$	series and shunt resistances	$P_d$	real power delivery
$I_L$	light integrated current source	$Q_d$	reactive power delivery
$s$	solar irradiation	$P_L$	real power load
$I_{sc}$	short-circuit current	$Q_L$	reactive power load
$k_i$	short-circuit current coefficient		
$T_{ref}$	reference temperature of PV cell		
$N_s$	number of cells in series		
$N_p$	number of modules in parallel		

and also these methods have lack of broader information exchange among the subsystems. In last few decades, the distributed control schemes have gained much attention to coordinate the inverter-interfaced DERs in islanded microgrids [9–11]. However, the conventional distributed approaches viably require faster communications among the control schemes for proper sharing of powers within the system.

In recent years, the multi-agent system (MAS) has been established as one of the most popular distributed platforms to effectively manage the coordination and communication among the power electronic inverters in islanded microgrids. A multi-agent based control strategy for EV integrated energy system is proposed in [12] to manage the sharing of powers within the system. In [13], a mixed homogeneous and heterogeneous multi-agent based framework is proposed to achieve a faster coordinated control of voltage and frequency in islanded microgrids. In [14], a multi-agent based reinforcement learning algorithm is proposed for optimal power sharing in microgrids. Multi-agent based adaptive and cooperative voltage and frequency control approach with communication constraints is proposed in [15,16] for different network configurations. In [17], a multi-agent based hybrid supervisory control scheme is proposed for energy management system in microgrids. A decentralized multi-agent system based on non-cooperative game theory is proposed in [18,19] to provide a cooperative control framework for the complex power management in the autonomous microgrid systems. In [20,21], a communication assisted agent-based adaptive decentralized control scheme is proposed to control the inverter-interfaced DERs for sharing real and reactive powers in islanded microgrids. An intelligent coordinated control of a microgrid in both grid-connected and islanded modes using the multiagent system (MAS) technique is proposed in [22,23]. A consensus algorithm-based distributed hierarchical control for residential microgrids is proposed in [24] and in [25], a

multi-agent based self-triggered communication enabled distributed control scheme is proposed.

Though the MAS approaches so far presented offer a number of benefits to control and manage the sharing of powers among the DERs, however, the existing MAS-based methods presented in [12–25] did not completely explore the system vulnerability due to a sudden change in the network configurations (perhaps due to natural or physical events) which often do not guarantee the proportional sharing of real and reactive powers to maintain the frequency and voltage of the system. In order to take the challenges over the existing and previous methods, an intelligent distributed peer-to-peer MAS is proposed for managing and controlling the DERS within the microgrids. The agent interaction adheres to a communication diagram (using graph theory) through which control agents can exchange information to manage the coordinated control activities in a distributed manner and further determine their set points to regulate the real and reactive powers. In order to perform the necessary power control and management tasks, each control agent is considered to be embedded to a local proportional integral (PI) regulator-based inner current control scheme for each individual inverter of associated EV unit. The well known Ziegler-Nichols tuning approach [26] is used to select the gain of the controller whereas the agents use the information from local as well as neighboring EV units to facilitate the coordinated control of the  $dq$ -axis component of the inverter currents. However, the main three contributions of this paper are summarized below which distinguish the proposed framework from the existing traditional approaches:

1. The designed multi-agent framework provides a communication infrastructure to enable the information exchange among various control equipment for the effective and proportional sharing of real and reactive powers.

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