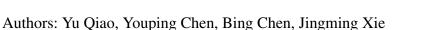
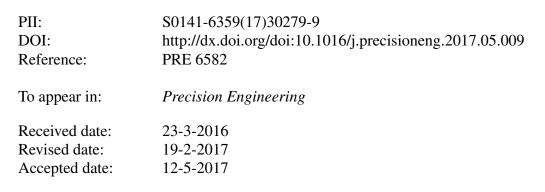
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A novel calibration method for multi-robots system utilizing calibration model without nominal kinematic parameters

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