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# On empirical likelihood statistical functions

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# **1. Introduction**

Empirical likelihood (EL) can be traced all the way back to [Thomas](#page--1-0) [and](#page--1-0) [Grunkemeier](#page--1-0) [\(1975\)](#page--1-0), but [Owen](#page--1-1) [\(1988](#page--1-1)[,](#page--1-2) [1990](#page--1-2)[,](#page--1-3) [1991,](#page--1-3) [2001\)](#page--1-4) formally established it as a nonparametric analogue of parametric likelihood, providing an effective way for interval estimation and goodness-of-fit test with appealing data-driven and range respecting features. [DiCiccio](#page--1-5) [et al.](#page--1-5) [\(1991\)](#page--1-5) and [Chen](#page--1-6) [and](#page--1-6) [Cui](#page--1-6) [\(2007\)](#page--1-6) further showed that EL is generally Bartlett correctable and thus leads to more accurate inferential procedures than some other commonly used ones such as the bootstrap. The EL method has been extended and applied in many fields in statistics and econometrics such as estimating equations [\(Qin,](#page--1-7) [1993;](#page--1-7) [Qin](#page--1-8) [and](#page--1-8) [Lawless,](#page--1-8) [1994\)](#page--1-8), quantile and density estimation [\(Chen](#page--1-9) [and](#page--1-9) [Hall,](#page--1-9) [1993;](#page--1-9) [Hall](#page--1-10) [and](#page--1-10) [Presnell,](#page--1-10) [1999;](#page--1-10) [Chen,](#page--1-11) [1997;](#page--1-11) [Zhang,](#page--1-12) [1997,](#page--1-12) [1998\)](#page--1-12), generalized linear model [\(Kolaczyk,](#page--1-13) [1994\)](#page--1-13), survival analysis [\(Murphy](#page--1-14) [and](#page--1-14) [van](#page--1-14) [der](#page--1-14) [Vaart,](#page--1-14) [1997;](#page--1-14) [Adimari,](#page--1-15) [1997\)](#page--1-15), nonparametric regression [\(Qin](#page--1-16) [and](#page--1-16) [Tsao,](#page--1-16) [2005\)](#page--1-16), goodness-of-fit measure [\(Baggerly,](#page--1-17) [1998\)](#page--1-17), inference in the presence of nuisance parameters [\(Lazar](#page--1-18) [and](#page--1-18) [Mykland,](#page--1-18) [1999\)](#page--1-18), marginal and conditional likelihood [\(Qin](#page--1-19) [and](#page--1-19) [Zhang,](#page--1-19) [2005\)](#page--1-19), finite population inference [\(Chen](#page--1-20) [and](#page--1-20) [Qin,](#page--1-20) [1993;](#page--1-20) [Chen](#page--1-21) [and](#page--1-21) [Wu,](#page--1-21) [2002\)](#page--1-21), specification tests [\(Kitamura,](#page--1-22) [2001;](#page--1-22) [Kitamura](#page--1-23) [et al.,](#page--1-23) [2004\)](#page--1-23), generalized methods of moments [\(Imbens,](#page--1-24) [2002\)](#page--1-24), local polynomial fitting [\(Zhang](#page--1-25) [and](#page--1-25) [Liu,](#page--1-25) [2003\)](#page--1-25), and dual likelihood [\(Bravo,](#page--1-26) [2004\)](#page--1-26).

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## A B S T R A C T

We consider the empirical likelihood method for estimation of distribution and quantile functions where side information is incorporated through moment conditions. We systematically study the asymptotic properties of the estimators, such as the uniform strong laws of large numbers and weak convergence over classes of functions. Two Monte Carlo examples are also given to illustrate the practical utility of the method.

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In many situations of practical interest, there usually exists some side information about the otherwise unknown distribution of the sample. This information may come from preliminary studies or be directly implied by an assumed theoretical model. For example, we might know that the distribution function is symmetric around a constant which can either be specified or unknown. Intuitively, the side information ''symmetry'' should be utilized when it comes to estimate the distribution function. An attractive feature of the EL method is that it can effectively incorporate such information through the moment functions. For the problem where the information about distribution function *F* and a parametric vector  $\theta$  associated with *F* are available in the form of some unbiased estimating functions, [Qin](#page--1-8) [and](#page--1-8) [Lawless](#page--1-8) [\(1994\)](#page--1-8) formally established the asymptotic normality of the EL estimators of *F* and θ.When the side information does not involve an unknown parameter vector, [Chen](#page--1-20) [and](#page--1-20) [Qin](#page--1-20) [\(1993\)](#page--1-20) and [Zhang](#page--1-12) [\(1997\)](#page--1-12) proposed the EL-based estimator of the quantile function and established its large sample properties.

In this paper, we systematically study the asymptotic properties of the EL-based estimators of distribution and quantile functions in the presence of side information which may involve an unknown parameter vector. For the EL-based estimator of the distribution function, we establish the uniform strong laws of large numbers and weak convergence, over classes of functions, i.e. the P-Glivenko–Cantelli and P-Donsker classes respectively. The latter allows us to construct nonparametric confidence bands for the distribution function and its related functionals. The EL-based estimator of the quantile function is obtained by direct inversion and the asymptotic results parallel to those of the distribution function are







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established. Two Monte Carlo examples are also given to illustrate that for distribution and quantile functions, the estimation accuracy can generally be improved by incorporating the side information. The rest of the paper is organized as follows. In Section [2,](#page-1-0) we study the EL-based estimation of the distribution function, in the presence of side information. Under the same setting, we consider the EL-based quantile estimation in Section [3.](#page--1-27) Section [4](#page--1-28) provides two Monte Carlo examples to illustrate the results. All the technical proofs are relegated to the [Appendix.](#page--1-29)

### <span id="page-1-0"></span>**2. The EL-based estimation of the distribution function**

Let  $X_1, \ldots, X_n$  be *d*-dimensional independent and identically distributed random vectors with an unknown distribution function *F* and a parameter  $\theta$  associated with *F* which takes values in a compact parameter space  $\Theta \subseteq R^q$ . Denote the true values of *F* [and](#page--1-8)  $\theta$  by  $F_0$  and  $\theta_0$  respectively. As in [Qin](#page--1-8) and [Lawless](#page--1-8) [\(1994\)](#page--1-8), suppose that the side information involves an unknown parameter vector  $\theta$  and can be summarized in the form of  $r \geq q$ unbiased moment functions  $g_j(x, \theta), j = 1, 2, ..., r$ , such that  $Eg(X, \theta_0) = 0$ , where the expectation is for the distribution of *X* at the true parameter  $\theta_0$  when no confusion appears, and  $g(X, \theta) = (g_1(X, \theta), g_2(X, \theta), \dots, g_r(X, \theta))^T$ . Let  $w_1, w_2, \dots, w_n$ be non-negative empirical weights allocated to the observations. The EL incorporating the side information as proposed in [Qin](#page--1-8) [and](#page--1-8) [Lawless](#page--1-8) [\(1994\)](#page--1-8) is  $L(\theta) = \prod_{i=1}^{n} w_i(\theta)$  which maximizes

$$
\prod_{i=1}^{n} w_i \text{ subject to } w_i \ge 0, \qquad \sum_{i=1}^{n} w_i = 1, \text{ and}
$$

$$
\sum_{i=1}^{n} w_i g(X_i, \theta) = 0;
$$

which are given by

$$
w_i(\theta) = \frac{1}{n} \frac{1}{1 + t_n^T(\theta)g(X_i, \theta)},
$$

and  $t_n(\theta) = (t_{n,1}(\theta), \ldots, t_{n,r}(\theta))^T$  are solutions of

$$
\sum_{i=1}^n \frac{g(X_i, \theta)}{1 + t_n^T(\theta)g(X_i, \theta)} = 0.
$$

Write  $\Omega = E[g(X_1, \theta_0)g(X_1, \theta_0)^T]$ ,  $L = E[\partial g(X_1, \theta_0)/\partial \theta]$ , and  $A(x) = E[g(X_1, \theta_0)I(X_1 \leq x)]$ . Let  $I(\cdot)$  be the indicator function. Without any side information, distribution function can be efficiently estimated by the empirical distribution function  $F_n(x) =$  $\sum_{i=1}^{n} I(X_i \leq x)/n$ , where the inequality is meant component- $\sum_{i=1}^{n} I(X_i \leq x)/n$ , where the mequality is meant component-<br>wise. The asymptotic variance of  $\sqrt{n}(F_n(x) - F_0(x))$  is  $\sigma^2(x) =$  $F_0(x)(1-F_0(x))$ . When  $\theta_0$  is known, the EL estimator of distribution function is defined as

$$
\hat{F}_n(x) = \sum_{i=1}^n w_i(\theta_0) I(X_i \le x),
$$

with the associated EL process  $\sqrt{n}(\hat{F}_n(\cdot) - F_0(\cdot))$ . When  $\theta_0$  is unknown, it can be estimated by the maximum empirical likelihood estimate  $\tilde{\theta}_n = \arg \max L(\theta)$ . The corresponding EL estimator of distribution function and the associated EL process are then

$$
\tilde{F}_n(x) = \sum_{i=1}^n w_i(\tilde{\theta}_n) I(X_i \le x) \text{ and}
$$
  

$$
\sqrt{n}(\tilde{F}_n(\cdot) - F_0(\cdot)), \text{ respectively.}
$$

It is natural to estimate  $F_0$  by  $\tilde{F}_n$  or  $\hat{F}_n$  since the  $w_i$ s are the weights that the EL distribution places on the observations *Xi*s. As noted by a referee, alternatively, for any given *x*, write  $\tau = F(x)(\tau_0 = F_0(x))$  is the true value) and use the EL method to estimate  $\pi = (\tau, \theta)$ . The moment functions for  $\pi$  are  $m(X, \pi) = (I(X \leq x) - \tau, g(X, \theta)^T)^T$ . It is easy to see that the maximum empirical likelihood estimate of  $\pi$  is  $(\tilde{F}_n(x), \tilde{\theta}_n)$  when  $\theta_0$  is unknown. As shown in [Qin](#page--1-8) [and](#page--1-8) [Lawless](#page--1-8) [\(1994\)](#page--1-8), the asymptotic variance of  $\sqrt{n}(\tilde{F}_n(x) - F_0(x))$  is Lawless (1994), the asymptotic variance of  $\sqrt{n}(\tilde{F}_n(x) - F_0(x))$  is  $\tilde{\sigma}^2(x) = F_0(x)(1 - F_0(x)) - A(x)^T(\Omega^{-1} - U)A(x)$ , where *U* is given in [Theorem 1.](#page--1-30) When  $\theta_0$  is known,  $L = 0$  and the asympgiven in Theorem 1. When  $\sigma_0$  is known,  $L = 0$  and the asymptotic variance of  $\sqrt{n}(\hat{F}_n(x) - F_0(x))$  reduces to  $\hat{\sigma}^2(x) = F_0(x)(1 F_0(x)$ ) − *A*(*x*)<sup>*T*</sup>  $\Omega^{-1}A(x)$ . The asymptotic variances are equal to the efficiency bounds for  $\tau$ , as derived for the general GMM case by [Chamberlain](#page--1-31) [\(1987\)](#page--1-31) and thus  $\tilde{F}_n$  and  $\hat{F}_n$  are semiparametrically efficient. This shows that the weights  $w_i(\tilde{\theta}_n)$  and  $w_i(\theta_0)$  are optimal although they are both of order  $1/n(1 + o_p(1))$  the same as those of the NPMLE. When  $A(x) \neq 0$ ,  $\hat{\sigma}^2(x) < \sigma^2(x)$  and this indicates that there is always an efficiency gain in incorporating the side information when  $\dot{\theta_0}$  is known. When  $\theta_0$  is unknown, however, there could be no efficiency gain for some *x*. As illustrated in the first example of Section [4,](#page--1-28) when the side information is ''symmetry'' and the underlying distribution is the Laplace distribution, there is no efficiency gain in estimating  $F_0(\theta_0)$  where  $\theta_0$  is the unknown symmetry center.

Below we introduce some notations before the statements of our results. Let  $\mu$  be a dominating measure for  $F_0$  (For example we may take  $\mu$  be the Lebesgue measure  $\lambda$  if  $F_0$  is continuous, the counting measure *C* if  $F_0$  is discrete, or  $\mu = \lambda |A + C| A^c$  if  $F_0$ is continuous on  $A$  and discrete on  $A<sup>c</sup>$ ). For ease of exposition we assume  $F_0$  is on  $R^1$ , the case  $F_0$  being on  $R^d$  ( $d > 1$ ) is similar. Let  $f = dF/d\mu$  be the Radon–Nikodym derivative of  $F_0$  with respect to  $\mu$ , and

$$
\tilde{f}_n(x) = \frac{\tilde{F}_n(x + c_n) - \tilde{F}_n(x - c_n)}{2c_n},
$$

$$
\hat{f}_n(x) = \frac{\hat{F}_n(x + c_n) - \hat{F}_n(x - c_n)}{2c_n},
$$

with  $c_n \to 0$ ,  $nc_n \to \infty$ . Define  $f_n(x)$  accordingly using  $F_n(x)$ . Note that  $\tilde{f}_n(\cdot)$ ,  $\hat{f}_n(\cdot)$  and  $f_n(\cdot)$  are proper densities for each *n*. Now let  $\tilde{\mathcal{P}}_n$ ,  $\hat{\mathcal{P}}_n$  and  $\mathcal{P}_n$  be the corresponding (random) probability measures for  $\tilde{f}_n(\cdot)$ ,  $\hat{f}_n(\cdot)$  and  $f_n(\cdot)$ . We will establish contiguity among these probability measures.

Let  $\tilde{P}_n$ ,  $\hat{P}_n$ ,  $P_n$  and P be the (random) probability measures induced by  $\tilde{F}_n$ ,  $\hat{F}_n$ ,  $F_n$  and  $F_0$  respectively. For a function  $h : R^d \mapsto R$ , define  $\tilde{P}_n h = \sum_{i=1}^n w_i(\tilde{\theta}_n)h(X_i)$ ,  $Ph = Eh(X_1)$ ,  $\tilde{G}_n h = \sqrt{n}(\tilde{P}_n h - \tilde{P}_n)$  $P(h) = \sqrt{n}(\sum_{i=1}^{n} w_i(\tilde{\theta}_n)h(X_i) - Eh(X_1))$ , and  $\mathbb{G}_n h = \sqrt{n}(P_n h - Ph) =$  $\overline{n}(\sum_{i=1}^n n^{-1}h(X_i) - Eh(X_1))$ . For any given *h* satisfying some regularity condition, it can be shown that  $\tilde{P}_n h \to Ph$  (a.s.) and  $\tilde{G}_n h \stackrel{D}{\to}$  $N(0, \tilde{\sigma}_h^2)$ , where  $\tilde{\sigma}_h^2 = Ph^2 - (Ph)^2 - P(g_0^Th)(\tilde{\Omega}^{-1} - U)P(g_0h)$ and  $g_0(x) = g(x, \theta_0)$ . By contrast,  $\mathbb{G}_n h \stackrel{D}{\rightarrow} N(0, \sigma_h^2)$  with  $\sigma_h^2 =$ *Ph*<sup>2</sup> − (*Ph*)<sup>2</sup>. Hence when it comes to estimate *Ph*, incorporating the side information *g* reduces the asymptotic variance by the amount  $P(g_0^Th)(\Omega^{-1} - U)P(g_0h)$ . For a given space H, let  $l^{\infty}(\mathcal{H})$  be the set of functions *z* on *H* with  $\sup_{h \in |Z(h)|} < \infty$ . We aim to establish the uniform strong laws of large numbers and weak convergence of empirical likelihood process as random elements indexed by a class of functions  $\mathcal H$ , in the space  $l^\infty(\mathcal H)$ , which may not be measurable. Accordingly, the resultant convergence results are in [t](#page--1-32)he sense of the outer measure *P* <sup>∗</sup> of *P* [\(van](#page--1-32) [der](#page--1-32) [Vaart](#page--1-32) [and](#page--1-32) [Well](#page--1-32)[ner,](#page--1-32) [1996;](#page--1-32) hereafter VW). When  $H$  is measurable, the results are automatically in the sense of the measure *P* itself. For any probability measure *Q*, let  $||Q||_{\mathcal{H}}$  = sup{ $|Qh|$  :  $h \in \mathcal{H}$ }. Define for any vector  $k = (k_1, \ldots, k_d)$  of *d* integers and a function  $h: \mathcal{X} \mapsto R$ ,  $D^k h(x) = \frac{\partial^{|k|} h(x)}{\partial x_1^{k_1} \cdots \partial x_d^{k_d}}$ , where X is a subset of *R*<sup>d</sup> and  $|k| = k_1 + \cdots + k_d$ . Let

$$
||h||_s = \max_{|k| \leq s} \sup_{x \in \mathcal{X}} |D^k h(x)| + \max_{|k| = s} \sup_{x, y \in \mathcal{X}} |D^k h(x) - D^k h(y)|
$$

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