Accepted Manuscript

Dividing traffic cluster into parts by signal control

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PII: S0378-4371(17)30921-4
DOI: https://doi.org/10.1016/j.physa.2017.09.029
Reference: PHYSA 18634

To appear in: *Physica A*

Received date : 1 May 2017

Please cite this article as: T. Nagatani, Dividing traffic cluster into parts by signal control, *Physica A* (2017), https://doi.org/10.1016/j.physa.2017.09.029

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Research Highlights

We presented the nonlinear-map model for the motion of vehicles controlled by the signals.

We studied the breakup process of a traffic cluster into smaller groups by controlling signals.

We explored the dependence of the breakup on both cycle time and vehicular speed.

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