



Blocking unions of arborescences



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ABSTRACT

Given a digraph $D = (V, A)$ and a positive integer k , a subset $B \subseteq A$ is called a k -arborescence, if it is the disjoint union of k spanning arborescences. When also arc-costs $c : A \rightarrow \mathbb{R}$ are given, minimizing the cost of a k -arborescence is well-known to be tractable. In this paper we take on the following problem: what is the minimum cardinality of a set of arcs the removal of which destroys every minimum c -cost k -arborescence. Actually, the more general weighted problem is also considered, that is, arc weights $w : A \rightarrow \mathbb{R}_+$ (unrelated to c) are also given, and the goal is to find a minimum weight set of arcs the removal of which destroys every minimum c -cost k -arborescence. An equivalent version of this problem is where the roots of the arborescences are fixed in advance. In an earlier paper (Bernáth and Pap, 2013) we solved this problem for $k = 1$. This work reports on other partial results on the problem. We solve the case when both c and w are uniform—that is, find a minimum size set of arcs that covers all k -arborescences. Our algorithm runs in polynomial time for this problem. The solution uses a result of Bárász et al. (2005) saying that the family of so-called in-solid sets (sets with the property that every proper subset has a larger in-degree) satisfies the Helly-property, and thus can be (efficiently) represented as a subtree hypergraph. We also give an algorithm for the case when only c is uniform but w is not. This algorithm is only polynomial if k is not part of the input.

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1. Introduction

Given a hypergraph on ground set S with hyperedge set \mathcal{E} , a **transversal** of \mathcal{E} is an inclusionwise minimal subset of S that intersects every member of \mathcal{E} . The set of transversals of \mathcal{E} is also called the **blocker** of \mathcal{E} . Our problems can be viewed as finding a minimum transversal of a certain hypergraph, or more generally, finding a minimum weight transversal, if weights of the elements of S are also given. The problem of finding a minimum (weight) transversal of \mathcal{E} will also be called **the blocking problem for \mathcal{E}** . Notice the difference

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between the terms *minimal* and *minimum*: minimal means inclusionwise minimal, while minimum means minimum size.

Let $D = (V, A)$ be a digraph with vertex set V and arc set A . A **spanning arborescence** is a subset $B \subseteq A$ that is a spanning tree in the undirected sense, and every node has in-degree at most one. Thus there is exactly one node, the **root node**, with in-degree zero. Equivalently, a spanning arborescence is a subset $B \subseteq A$ with the property that there is a root node $r \in V$ such that $\varrho_B(r) = 0$, and $\varrho_B(v) = 1$ for $v \in V - r$, and B contains no cycle. (Here $\varrho_B(v)$ denotes the number of arcs in B entering node v .) We will also call a spanning arborescence an **arborescence** for short, when the set of nodes is obvious from the context. If $r \in V$ is the root of the spanning arborescence B then B is said to be an **r -rooted arborescence**.

Given also a positive integer k , a subset $B \subseteq A$ is called a **k -arborescence**, if it is the arc-disjoint union of k spanning arborescences. In the special case when every arborescence has the same root r , we call B an **r -rooted k -arborescence**.

Given $D = (V, A)$, k and a cost function $c : A \rightarrow \mathbb{R}$, it is well known how to find a **minimum cost r -rooted k -arborescence** in polynomial time, and to find a **minimum cost k -arborescence** just as well. See [1, Chapter 53.8] for a reference, where several related problems are considered. The existence of an r -rooted k -arborescence is characterized by Edmonds' Disjoint Arborescence Theorem ([Theorem 2](#)), while the existence of a k -arborescence is characterized by a theorem of Frank [2] (see [Theorem 3](#)). Frank also gave a linear programming description of the convex hull of k -arborescence, generalizing Edmonds' linear programming description of the convex hull of r -rooted k -arborescences. The problem of finding a minimum cost k -arborescence may also be solved with the use of these results, either via a reduction to minimum cost r -rooted k -arborescences, or by applying a weighted matroid intersection algorithm directly.

In this paper we consider the following blocking problems, and actually, we will prove that these problems are polynomial time equivalent.

Problem 1 (Blocking Optimal k -Arborescences). Given a digraph $D = (V, A)$, a positive integer k , a cost function $c : A \rightarrow \mathbb{R}$ and a nonnegative weight function $w : A \rightarrow \mathbb{R}_+$, find a subset H of the arc set such that H intersects every minimum c -cost k -arborescence, and $w(H)$ is minimum.

Here the expression “intersects” simply means that the two have non-empty intersection. We remark that it is quite easy to see that [Problem 1](#) is polynomially equivalent with the version where the root is also given in advance, that is, the problem of blocking optimal r -rooted k -arborescences.

Problem 2 (Blocking Optimal r -Rooted k -Arborescences). Given a digraph $D = (V, A)$, a node $r \in V$, a positive integer k , a cost function $c : A \rightarrow \mathbb{R}$ and a nonnegative weight function $w : A \rightarrow \mathbb{R}_+$, find a subset H of the arc set such that H intersects every minimum c -cost r -rooted k -arborescence, and $w(H)$ is minimum.

In [Section 4](#) we will show that the two problems are polynomial time equivalent. However, if c is constant then [Problems 1](#) and [2](#) are *not* easily seen to be equivalent: at least we did not find such reductions (find more details in [Section 5](#)). Thus it is important to distinguish between these two versions, if c is constant.

[Problems 1](#) and [2](#) can be viewed as hypergraph blocking problems. The ground set of the hypergraph is the arc set A of a digraph for both problems, and the family of hyperedges is the family of minimum c -cost k -arborescences for [Problem 1](#), and the family of minimum c -cost r -rooted k -arborescences for [Problem 2](#).

In our previous paper [3] we have solved [Problems 1](#) and [2](#) in the special case when $k = 1$. Our conjecture is that both problems are also polynomial time solvable when k is not fixed. The main result of this paper is that both problems are polynomial time solvable when k is part of the input, and both c and w are constant—that is, when H is required to intersect *every* k -arborescence and we want to minimize $|H|$. Our

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