



Diffusion limits for the $(MAP_t/Ph_t/\infty)^N$ queueing network



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ABSTRACT

In this paper, we prove strong approximations for the $(MAP_t/Ph_t/\infty)^N$ queueing network. These strong approximations allow us to derive fluid and diffusion limits for the queue length processes of the network. This extends recent work that provides fluid and diffusion limits in the single station setting.

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1. Introduction

Queueing networks are very useful for analyzing and approximating real stochastic systems. Many queueing networks assume that the arrivals to the network follow a Poisson process. This is a natural assumption when there is no dependence or correlation between arrivals. However, an independence assumption is not warranted in many applications. Stochastic models for describing the dynamics of internet data traffic in telecommunication networks are notoriously difficult since they have dependencies. One example of this is when a user downloads a file from the internet; the arrival of the first packet often indicates that more packets are going to arrive subsequently. Despite the assertions of the Palm–Khintine theorem, which asserts that the superposition of a large number of renewal processes will converge to a Poisson process, it is well known in the teletraffic literature that arrival traffic is not renewal.

There are many applications and scenarios where data traffic is not renewal, see for example [9,8]. To this end, we construct a queueing network where the arrivals are not Poisson and are constructed from Markovian Arrival Processes (MAP's). MAP's, unlike phase type distributions, allow one to consider non-renewal processes for the arrival process and offer more flexibility when

modeling arrival traffic. One main reason that the MAP is a generalization of a phase type distribution is that the MAP is not restarted independently of its past history. In a MAP, unlike phase type distributions, the next interarrival time is dependent on the exit state of the Markov chain and this feature allows one to capture *memory* into the arrival process.

For the analysis of queues involving the MAP and phase-type distributions, the matrix-geometric method (MGM) introduced in [16] is frequently used. We, however, cannot escape from state space explosion when we have a large number of states and servers. [14] propose the partial-moment differential equations for the analysis of $Ph_t/Ph_t/\infty$ queues and [15] extend the result to the $[Ph_t/Ph_t/\infty]^N$ networks. [5] use phase-type distributions for approximating small-size $G_t/G_t/n_t + G_t$ queues.

In this paper, we study the $(MAP_t/Ph_t/\infty)^N$ queueing network. As a result, we extend recent work by [23,11], which only considers the single station setting. To this end, we prove strong approximations for the $(MAP_t/Ph_t/\infty)^N$ queueing network and extend the Poisson process representation to the network setting. These strong approximations not only allow us to derive fluid and diffusion limits for the queueing network, but also they provide us with simple differential equations that can be integrated numerically to approximate the sample path behavior of the mean and variance of the queueing network. Lastly, there are already many useful algorithms available for fitting phase-type distributions and MAP's from data such as [2,7,1,3] and there we can exploit this feature to approximate very complicated arrival processes that arise in practice.

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1.1. Main contributions of paper

The contributions of this work can be summarized as follows.

- We derive a Poisson process representation for the $(MAP_t/Ph_t/\infty)^N$ queueing network and prove strong approximations for the network.
- Using strong approximations for Poisson processes, we develop fluid and diffusion limits for the $(MAP_t/Ph_t/\infty)^N$ queueing network to understand the sample path mean and variance dynamics of the network.

1.2. Organization of paper

The remainder of this paper is organized as follows. Section 2 describes the construction of a MAP and phase type distributions. Section 3 builds a mathematical model for describing the dynamics of the system for the $(MAP_t/Ph_t/\infty)^N$ queueing network via time-changed Poisson processes. Using the Poisson representation in Section 3, we also prove the fluid and diffusion limits for the $(MAP_t/Ph_t/\infty)^N$ queueing network. Finally, Section 4 concludes and offers suggestions for future research.

2. Markovian Arrival Processes (MAP's)

In this section, we give a brief description of MAP's. The reader should review Section 2 of [11] and Chapter 11 of [1] for a more extensive discussion on MAP's and their versatility in stochastic modeling and queueing theory.

In order to define a MAP, we will follow the construction given in [4]. We first consider an irreducible continuous time Markov chain (CTMC) with h transient states. At the end of a sojourn in state i , that is exponentially distributed with parameter λ_i , there are two possible events that can happen. The first possibility corresponds to an event or arrival and the CTMC can visit state j (including $j = i$) with probability p_{ij} . The second possible event corresponds to no arrival and the CTMC can visit state j ($j \neq i$) with probability q_{ij} . Therefore, the CTMC is able to go from state i to state i through an arrival. Then, we define matrices \mathcal{D}_0 where $[\mathcal{D}_0]_{ij} = d_{ij}^0$ and \mathcal{D}_1 where $[\mathcal{D}_1]_{ij} = d_{ij}^1$ where $d_{ii}^0 = -\lambda_i$, $1 \leq i \leq h$; $d_{ij}^0 = \lambda_i \cdot q_{ij}$, $j \neq i$, $1 \leq i, j \leq h$; $d_{ij}^1 = \lambda_i p_{ij}$, $1, \leq i, j \leq h$, with $(\sum_{j=1}^h p_{ij} + \sum_{j \neq i} q_{ij}) = 1$, for $1 \leq i \leq h$. In our description of the MAP, we have suppressed its dependence on time. However, all of our results apply to the time varying setting when the parameters are locally integrable with respect to time and therefore, we suppress time for notational convenience.

With the above construction, a MAP is described by the two $h \times h$ matrices \mathcal{D}_0 and \mathcal{D}_1 . The matrix \mathcal{D}_0 corresponds to transitions where there is no arrival and \mathcal{D}_1 corresponds to the transitions that generate an actual arrival. With this construction, it is also obvious that this is more general than the renewal process with phase type inter-event time distributions. Dependence between arrivals is created by the fact that when an arrival is generated, then the Markov chain can re-enter the same state, however, when no arrival is generated, it cannot re-enter the same state. Now that we have defined a MAP, it is now important to understand how the MAP is a generalization of some well known stochastic arrival processes.

2.1. Phase-type distributions

A very special case of MAP's is the phase type distribution. Unlike MAP's, phase type distributions can only approximate renewal processes with arbitrary precision. A phase-type distribution with

h phases can be viewed as the time taken from an initial state to an absorbing state of a continuous time Markov chain with the following infinitesimal generator matrix:

$$Q = \begin{pmatrix} 0 & \mathbf{0} \\ \mathbf{s} & \mathbf{S} \end{pmatrix},$$

where $\mathbf{0}$ is a $1 \times h$ zero vector, \mathbf{s} is an $h \times 1$ vector, and \mathbf{S} is an $h \times h$ matrix. Note $\mathbf{s} = -\mathbf{S}\mathbf{e}$ where \mathbf{e} is an $h \times 1$ vector of ones. The matrix \mathbf{S} and the initial distribution β which is a $1 \times h$ vector identify the phase-type distributions.

We assume that our phase-type distributions for the service times have an initial distribution, β and infinitesimal generator matrix, Q_s . The number of phases in S_s is h_s and the matrix S_s and vector s_s can be expressed as:

$$S_s = \begin{pmatrix} \mu_{11} & \cdots & \mu_{1h_s} \\ \vdots & \vdots & \vdots \\ \mu_{h_s 1} & \cdots & \mu_{h_s h_s} \end{pmatrix}, \quad s_s = (\mu_{10}, \dots, \mu_{h_s 0})', \quad (2.1)$$

where the μ_{il} 's agree with the definition of the infinitesimal generator matrix Q_s . For notational consistency, we use a term *phase* to indicate the state of CTMC for both the MAPs and phase-type distributions throughout this paper.

3. Poisson construction of $(MAP_t/Ph_t/\infty)^N$ network

With the MAP's and phase-type distributions described in Section 2, we now build a mathematical queueing model to describe the dynamics of the $(MAP_t/Ph_t/\infty)^N$ queueing network. To this end, we need to provide the primitives of the queueing network. The network consists of N stations. For station m in the network, we assume that the external arrivals are generated by a MAP, $U_{jm}(\cdot)$, $j \in \{1, \dots, h_{A,m}\}$, where $h_{A,m}$ is the number of phases of the MAP. Similarly for service, given that we are in station m , we assume that the initial distribution for the phase-type service distribution is given by $\beta_m = (\beta_{1m}, \dots, \beta_{h_s,m})$. We let $X_{im}(t)$ denote the number of customers in phase i , $i \in \{1, \dots, h_{S,m}\}$, of the phase-type service distribution at time $t \geq 0$. After a customer in station m is served, the customer moves to station i with probability p_{mi} and leaves the network with probability $p_{m0} = 1 - \sum_{i=1}^N p_{mi}$. Lastly, we assume that the queueing network starts with no customers. Fig. 3.1 illustrates an example of a $(MAP_t/Ph_t/\infty)^N$ queueing network with two stations.

Thus, in the infinite-server setting, we have the following Poisson process representation for the $(MAP_t/Ph_t/\infty)^N$ queueing network,

$$U_{jm}(t) = \underbrace{U_{jm}(0)}_{\text{Initial Value of Token}} + \underbrace{\sum_{k \neq j}^{h_{A,m}} \Pi_{kjm}^{A0} \left(\int_0^t d_{kjm}^{A0} U_{km}(s) ds \right)}_{\text{MAP in station } m \text{ moves from state } k \text{ to } j \text{ (no arrival generated)}} + \underbrace{\sum_{k=1}^{h_{A,m}} \sum_{i=1}^{h_{S,m}} \Pi_{kjm}^{A1} \left(\int_0^t d_{kjm}^{A1} \beta_{im} U_{jm}(s) ds \right)}_{\text{MAP in station } m \text{ moves from state } k \text{ to } j \text{ (arrival generated)}} - \underbrace{\sum_{k \neq j}^{h_{A,m}} \Pi_{jkm}^{A0} \left(\int_0^t d_{jkm}^{A0} U_{jm}(s) ds \right)}_{\text{MAP in station } m \text{ moves from state } j \text{ to } k \text{ (no arrival generated)}}$$

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