



# An easy method to accelerate an iterative algebraic equation solver



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## ABSTRACT

This article proposes to add a single function calls to an iterative algebraic equation solver with an order  $n$  convergence rate, and to raise (for  $n > 1$ ) the order of convergence to  $2n - 1$ .

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## 1. Introduction

Newton's method for finding the root for  $f(x) = 0$  is very widely used, both directly and as a conceptual basis for the development of further methods. There is a large literature on schemes to generalize the method to various higher orders. In particular, Kung and Traub [1] demonstrated that an equation solver with  $n$  functional calls can achieve an order of convergence  $2^n - 1$ . However it is believed that no equation solver that achieves this order has been constructed for  $n > 4$ .

Many of the existing fast equation solvers are skillfully constructed (for recent examples, see [4–6]) but we consider the simplicity of implementation. In this paper a simple idea is proposed which is to add a single extra function evaluation to an arbitrary one-point iterative equation solver of convergence order  $n$ , and thereby to accelerate the original scheme to an order of convergence  $2n - 1$ . Furthermore, it can be shown that with each additional call of the derivatives, the order of convergence is raised by  $n - 1$  more (see Appendix A).

## 2. The order of convergence

An iterative equation solver for a set of algebraic equations  $\vec{F}(\vec{x}) = 0$  is said to have an order of convergence  $n$  when

$$|\vec{x}_{k+1} - \vec{x}_k| = O(|\vec{x}_k - \vec{x}_{k-1}|^n)$$

at the  $k$ th iteration. An almost equivalent definition is that

$$|\vec{F}(\vec{x}_{k+1})| = O(|\vec{x}_{k+1} - \vec{x}_k|^n)$$

in the case when the Jacobian of the system is *non-zero* at the solution. The order of convergence of an iterative solver is a measurement of how fast it converges to the true solution.

The proposed new scheme accelerates an iterative solver with  $n$ th-order convergence. With a single additional call of the function itself, the order of convergence can be raised from  $n$  to  $2n - 1$ .

There are two steps with this method and we demonstrate the procedure here for the case  $n = 3$  with the well-known Halley's method [3]. Let  $x_k$  be the  $k$ th estimate for the root. One solves the equation (assuming  $f'' \neq 0$ )

$$f(x_k) + f'(x_k)\delta + \frac{1}{2}f''(x_k)\delta^2 = 0, \quad (1)$$

and the two roots are explicitly expressed as

$$\delta = -\frac{1}{f''(x_k)} \left( f'(x_k) \pm \sqrt{f'(x_k)^2 - 2f(x_k)f''(x_k)} \right).$$

To recover Newton's method [2] when the quadratic term vanishes, we pick only one root and it can be written as

$$\delta = \frac{\text{sgn}(f'(x_k))}{f''(x_k)} \left( \sqrt{(f'(x_k))^2 - 2f(x_k)f''(x_k)} - |f'(x_k)| \right).$$

The above step uses three functional calls. Note that a Taylor series for  $f(x + \delta)$  at  $x = x_k$  using Eq. (1) implies

$$f(x_k + \delta) = O(\delta^3). \quad (2)$$

The next step uses one more function call to gain two more orders of convergence. One adds a term  $f(x_k + \delta)$  to Eq. (1), and solves

$$f(x_k + \delta) + f(x_k) + f'(x_k)\Delta + \frac{1}{2}f''(x_k)\Delta^2 = 0. \quad (3)$$

The solution is similar to that obtained in the first step:

$$\Delta = \frac{\text{sgn}(f'(x_k))}{f''(x_k)} \left( \sqrt{(f'(x_k))^2 - 2(f(x_k + \delta) + f(x_k))f''(x_k)} - |f'(x_k)| \right).$$

Finally, let  $x_{k+1} = x_k + \Delta$  for completion of the current iteration cycle.

One computes only four function values  $f(x_k)$ ,  $f'(x_k)$ ,  $f''(x_k)$ , and  $f(x_k + \delta)$ . However, the above scheme is fifth order convergent as shown next.

From a Taylor expansion one obtains

$$f(x_k + \Delta) = f(x_k) + f'(x_k)\Delta + \frac{1}{2}f''(x_k)\Delta^2 + \frac{1}{6}f'''(x_k)\Delta^3 + O(\Delta^4).$$

The sum of the first three terms in the right-hand side is equal to  $-f(x_k + \delta)$  from Eq. (3); thus  $f(x_k + \Delta) = -f(x_k + \delta) + f'''(x_k)\Delta^3/6 + O(\Delta^4)$ . However, from Eq. (1) and the Taylor expansion of  $f(x_k + \delta)$ , the above estimate becomes

$$f(x_k + \Delta) = \frac{1}{6}f'''(x_k)(\Delta^3 - \delta^3) + O(\Delta^4 - \delta^4) = (\Delta - \delta)O(\Delta^2, \delta^2). \quad (4)$$

By subtracting Eq. (1) from Eq. (3) one arrives at

$$(\Delta - \delta)(f'(x_k) + O(\delta)) = -f(x_k + \delta) = O(\delta^3). \quad (5)$$

It tells us that  $\Delta$  and  $\delta$  are of the same order and

$$(\Delta - \delta) = O(\delta^3).$$

One easily sees from Eq. (4) and Eq. (5) that

$$f(x_{k+1}) = f(x_k + \Delta) = O(\Delta^5).$$

Therefore the method is *fifth-order* convergent; however it employs only *four* function values. The proof above can be generalized for arbitrary  $n$ .

If  $f'(x) = 0$  at the solution, Newton's method either fails or converges slowly. The rapidly-converging scheme described above is more stable. However, the order of convergence is reduced from *five* to *four* because when  $f' = 0$ , Eq. (5) gives  $(\delta - \Delta) = O(\delta^2)$  instead of  $O(\delta^3)$ . In practice if  $x_k$  is not close to the solution, the term under the square root  $(f'(x_k))^2 - 2f(x_k)f''(x_k)$  can become negative and break the iteration. In this case this term can be set to zero to keep the computation going.

If  $f'$  is finite at the solution, because  $f \rightarrow 0$  when  $x_k$  is close to the solution,  $x^*$ , the term in the square root will be non-negative when sufficiently close to convergence; if  $f' = 0$  at the solution, setting this term to zero (if it becomes negative) would give  $\delta = -f'(x_k)/f''(x_k)$ , which is similar to a Newton-method by L'Hospital's rule.

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