

Short Note

# Correcting mesh-based force calculations to conserve both energy and momentum in molecular dynamics simulations

Robert D. Skeel<sup>a,\*</sup>, David J. Hardy<sup>b</sup>, James C. Phillips<sup>b</sup>

<sup>a</sup> Department of Computer Science, Purdue University, 305 North University Street, West Lafayette, IN 47907-2107, USA

<sup>b</sup> Beckman Institute, University of Illinois at Urbana-Champaign, 405 North Mathews Avenue, Urbana, IL 61801, USA

Received 18 February 2007; accepted 14 March 2007

Available online 24 March 2007

PACS: 31.15.-p; 61.20.Ja

Keywords: Molecular dynamics; Ewald sum; Force fields

The high cost of evaluating forces in molecular dynamics makes it necessary to use approximations. The most effective approximations for nonbonded 2-body interactions, such as particle–particle particle–mesh, particle–mesh Ewald, and multilevel summation, split the potential into a short-range part which is evaluated directly and a long-range part which is interpolated from a mesh. This results in a force that, though still conservative, is not translation-invariant, resulting in drift in the linear momentum. A common remedy is to apply a uniform correction to all forces to conserve linear momentum, but this results in a force that is not conservative. Described here is a mass-weighted correction, based on the simple idea of constraining the center of mass, which does yield a conservative force.

Consider a system of  $N$  particles with masses  $m_i$  and positions  $\vec{r}_i = \vec{r}_i(t)$ ,  $i = 1, 2, \dots, N$ , which evolve in time  $t$  as dictated by Newton's second law of motion

$$m_i \ddot{\vec{r}}_i = \vec{F}_i(\mathbf{R}, \dot{\mathbf{R}}, t), \quad (1)$$

where  $\mathbf{R}$  denotes  $\vec{r}_1, \vec{r}_2, \dots, \vec{r}_N$ . Often linear momentum  $\sum_i m_i \dot{\vec{r}}_i$  is conserved, which is equivalent to  $\sum_i \vec{F}_i = \vec{0}$ . In particular, a translation-invariant potential energy function

$$U(\vec{r}_1 + \vec{d}, \dots, \vec{r}_N + \vec{d}) = U(\vec{r}_1, \dots, \vec{r}_N)$$

yields forces  $\vec{F}_i = -\nabla_i U(\mathbf{R})$  that sum up to zero.

For a computer simulation the cost of evaluating forces can be very high. In particular, 2-body nonbonded interactions require  $\mathcal{O}(N^2)$  operations unless approximations are used. The most efficient approximations are obtained with methods such as particle–particle particle–mesh [1], particle–mesh Ewald (PME) [2], and multilevel summation [3–5], which split the potential into a short-range part calculated directly and a long-range

\* Corresponding author. Tel.: +1 765 494 9025; fax: +1 765 494 0739.

E-mail addresses: [skeel@cs.purdue.edu](mailto:skeel@cs.purdue.edu) (R.D. Skeel), [dhardy@ks.uiuc.edu](mailto:dhardy@ks.uiuc.edu) (D.J. Hardy), [jim@ks.uiuc.edu](mailto:jim@ks.uiuc.edu) (J.C. Phillips).

URLs: <http://bionum.cs.purdue.edu> (R.D. Skeel), <http://www.ks.uiuc.edu/~dhardy/> (D.J. Hardy), <http://www.ks.uiuc.edu/~jim/> (J.C. Phillips).

part interpolated from a mesh. The use of a mesh yields an approximation  $U^a(\mathbf{R})$  to the long-range part of the potential energy which is not translation-invariant. This leads not only to a violation of Newton's third law but causes particles to exert forces on themselves [6]! (Methods based on a hierarchical clustering of interactions, such as the fast multipole method [7], do not have this problem; however, they compute forces that are not conservative [8] and appear to be otherwise less efficient for molecular dynamics [9,4], though these studies are based on older versions of the methods.)

Failure to conserve linear momentum is at best a nuisance, since it means that even if the center of mass is initially at rest, it will start moving as the simulation progresses. A common remedy [2,10,11] is to subtract out the average net force  $(1/N)\sum_k \vec{F}_k^a$  from each force  $\vec{F}_i^a$ . However, the resulting force is not conservative even if the original approximate force is conservative. For a conservative force, the Jacobian matrix of  $\vec{F}_i$  with respect to  $\vec{r}_j$  must equal the transpose of the Jacobian matrix of  $\vec{F}_j$  with respect to  $\vec{r}_i$ . However, such is not the case for the adjusted force  $\vec{F}_i^a(\mathbf{R}) - (1/N)\sum_k \vec{F}_k^a(\mathbf{R})$ , whose Jacobian matrix with respect to position  $\vec{r}_j$  is given by

$$\frac{\partial}{\partial \vec{r}_j} \left( \vec{F}_i^a - \frac{1}{N} \sum_k \vec{F}_k^a \right) = -\overleftrightarrow{\mathcal{H}}_{ij}^a + \frac{1}{N} \sum_k \overleftrightarrow{\mathcal{H}}_{kj}^a,$$

where  $\overleftrightarrow{\mathcal{H}}_{ij}^a$  is the  $(i, j)$ th  $3 \times 3$  block of the Hessian of the potential energy function  $U^a$ .

The negative effect of this simple force correction on conservation of energy is observed in [12, p. 30]. A system of 216 rigid SPC waters is simulated for 10 ns in a cube of side length 18.7 Å. PME is used with a  $18 \times 18 \times 18$  grid, a direct sum cutoff of 8 Å, and the Verlet integrator with a 2 fs time step. The use of the force correction produces a drift of  $-0.14$  kcal/mol amidst fluctuations of  $\pm 0.05$  kcal/mol. Without the force correction the drift is not discernible.

A mass-weighted correction to the force is conservative, however. Assume that the initial linear momentum is zero:

$$\sum_i m_i \dot{\vec{r}}_i(0) = 0$$

(which is attained by subtracting a constant velocity from each velocity). Denote the displacement of the center of mass by

$$\vec{g}(\mathbf{R}) = \frac{1}{m_{\text{tot}}} \sum_k m_k (\vec{r}_k - \vec{r}_k(0)),$$

where  $m_{\text{tot}} = \sum_k m_k$ , and conservation of linear momentum is equivalent to the holonomic constraint

$$\vec{g}(\mathbf{R}) = 0.$$

This can be combined with the equations of motion (1) by adding constraint forces

$$m_i \ddot{\vec{r}}_i = \vec{F}_i(\dots) + \frac{m_i}{m_{\text{tot}}} \vec{\lambda},$$

where  $\vec{\lambda}$  is a set of Lagrange multipliers and its coefficient is obtained from the Jacobian matrix of  $\vec{g}(\mathbf{R})$  with respect to  $\vec{r}_i$ . Eliminating  $\vec{\lambda}$  (by twice differentiating the constraints and substituting in the equations of motion) leads to

$$m_i \ddot{\vec{r}}_i = \vec{F}_i(\dots) - \frac{m_i}{m_{\text{tot}}} \sum_k \vec{F}_k(\dots).$$

A direct proof that the corrected force is conservative is obtained by defining a corrected potential energy function

$$U^c(\mathbf{R}) = U^a(\vec{r}_1 - \vec{g}(\mathbf{R}), \dots, \vec{r}_N - \vec{g}(\mathbf{R})).$$

This is translation-invariant, and the use of a potential leads to conservative forces

$$\begin{aligned} \vec{F}_i^c(\vec{r}_1, \dots, \vec{r}_N) &= -\nabla_i U^c(\vec{r}_1, \dots, \vec{r}_N) \\ &= \vec{F}_i^a(\vec{r}_1 - \vec{g}(\mathbf{R}), \dots, \vec{r}_N - \vec{g}(\mathbf{R})) - \frac{m_i}{m_{\text{tot}}} \sum_k \vec{F}_k^a(\vec{r}_1 - \vec{g}(\mathbf{R}), \dots, \vec{r}_N - \vec{g}(\mathbf{R})). \end{aligned} \quad (2)$$

Download English Version:

<https://daneshyari.com/en/article/522113>

Download Persian Version:

<https://daneshyari.com/article/522113>

[Daneshyari.com](https://daneshyari.com)