

to left is constant:

$$H_{ij} = H_{i-1,j+1} \quad (1)$$

First, we fill the first row and the last column of \mathbf{H} with the complex numbers of the time-domain signal [2,25]. Fig. 1A shows a simple 4×3 matrix \mathbf{H} where the time-domain digitised data are the series $[a, b, c, d, e, f]$ coloured in red. The remaining matrix elements are filled according to Eq. (1). Second, \mathbf{H} is decomposed [1,26] as shown in Fig. 1B where the singular-value matrix Σ consists of three positive values Σ_1, Σ_2 and Σ_3 . Third, we zero the weakest singular value Σ_3 . Fourth, we construct a new 4×3 matrix with this reduced number of singular value (N_{SVD}) matrix as shown Fig. 1C; however, this new matrix is not of Hankel structure. Finally, we restore this matrix to Hankel one by averaging the elements of each descending diagonal from right to left as shown Fig. 1D. The denoised time-domain signal is provided by the first row and the last column of this matrix, which are coloured in red in Fig. 1D. If the corresponding spectrum is still too noisy, we repeat the procedure to the denoised time-domain signal by keeping the number of singular values smaller than or equal to the previous case. Cadzow [2] used Toeplitz matrix [27]

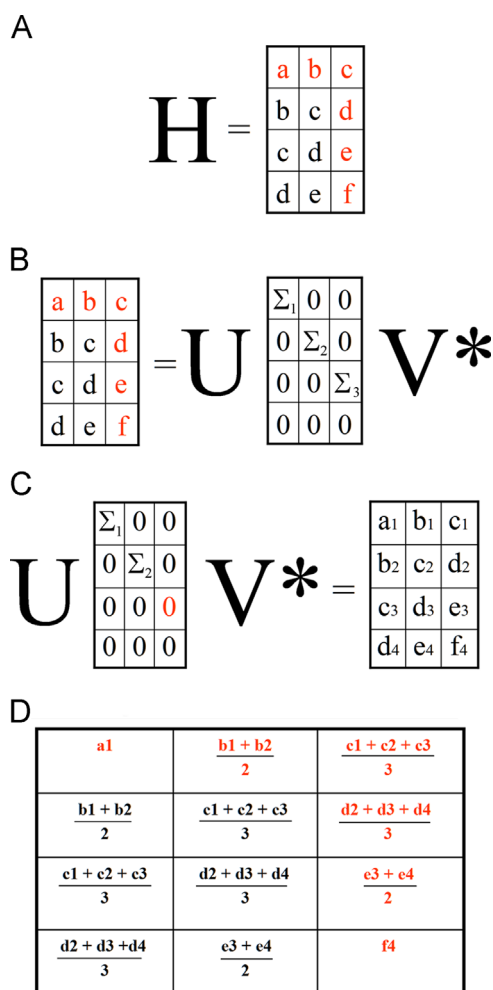


Fig. 1. Cadzow enhancement procedure: (A) 4×3 Hankel matrix \mathbf{H} containing the digitised noisy time-domain signal series $[a, b, c, d, e, f]$ in its first row and its last column; (B) decomposition of \mathbf{H} where the three singular values are Σ_1, Σ_2 and Σ_3 ; (C) the time-domain signal series is denoised by zeroing the smallest singular value Σ_3 ($N_{SVD}=2$) then a new 4×3 Hankel matrix is recomposed; (D) the matrix elements resulting from (c) are averaged so that the matrix is of Hankel structure; the denoised time-domain signal series is located in its first row and its last column. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

instead of Hankel one in his presentation, in which each descending diagonal from left to right is constant.

From a practical point of view, an $m \times n$ Hankel complex matrix represents a free induction decay (FID) whose size is $N=m+n-1$. The number of columns n of \mathbf{H} should be much larger than the optimum number of singular values, because the enhanced signal strongly depends on n and N [1].

As we also want to improve the time-domain signals of quadrupole nuclei [28], which usually have asymmetric line shapes, we proceed in another way as shown the flow chart in Fig. 2. The problem is that the optimum number of singular values cannot be guessed. We first apply the line broadening (LB) processing to decrease the noise [4]. After the decomposition of \mathbf{H} , it is simpler to start with the first singular value, which has the

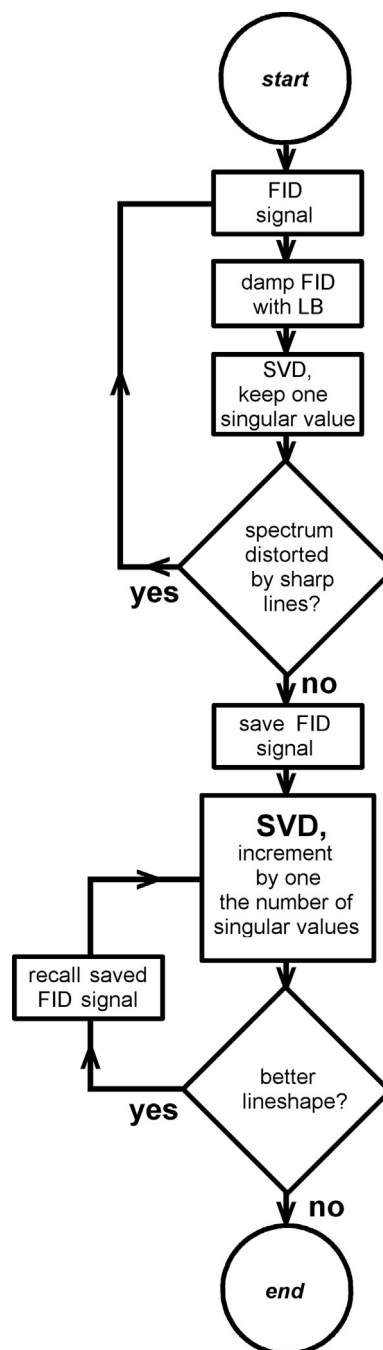


Fig. 2. Flow chart for SVD denoising time-domain signal, free induction decay (FID) for short.

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