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### One-Dimensional Model of a Suspension Bridge: Revision of Uniqueness Results

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#### Abstract

This paper brings a revision of the so far known uniqueness result for a one-dimensional damped model of a suspension bridge. Using standard techniques, however with finer arguments, we provide a significant improvement and extension of the allowed interval for the stiffness parameter.

Keywords: suspension bridge, beam equation, unique weak solution

2000 MSC: 35B10, 35D05, 70K30

#### 1. Introduction

We consider a nonlinear one-dimensional model of a suspension bridge introduced by Lazer and McKenna [7] and studied later in many papers (e.g., [1, 2, 3, 4, 5, 6, 8]):

$$mu_{tt} + EIu_{xxxx} + bu_t + \kappa u^+ = h(x, t),$$
  

$$u(0, t) = u(L, t) = u_{xx}(0, t) = u_{xx}(L, t) = 0,$$
  

$$u(x, t + 2\pi) = u(x, t), -\infty < t < +\infty, x \in (0, L).$$
(1)

or its rescaled form, respectively,

$$u_{tt} + \alpha^2 u_{xxxx} + \beta u_t + ku^+ = h(x, t),$$
  

$$u(0, t) = u(\pi, t) = u_{xx}(0, t) = u_{xx}(\pi, t) = 0,$$
  

$$u(x, t + 2\pi) = u(x, t), -\infty < t < +\infty, x \in (0, \pi).$$
(2)

This model represents the bridge as a damped beam with simply supported ends, subject to a periodic external force and to the nonlinear restoring force of cables hanging on a solid frame. The displacement u(x,t) is measured as positive in the downward direction and the cables are taken as one-sided springs obeying Hooke's law, with a restoring force proportional to the displacement if they are stretched, and with no restoring force if they are compressed. We recall that  $u^+(x,t) = \max\{0, u(x,t)\}$  is the positive part of u(x,t) and k (or  $\kappa$ , respectively) can be interpreted as the stiffness of the cables. The meaning of other parameters can be found, e.g., in [2]. Evidently, only  $\alpha > 0$ ,  $\beta > 0$  and k > 0 make sense from the physical point of view, however, for the sake of generality, we will deal with  $k \in \mathbb{R}$  throughout the text.

The aim of this paper is to revise the original result of [9], which says that for sufficiently small |k|, the problem (2) admits a unique solution for any right-hand side. Using the same techniques, however with finer arguments, we provide a significant improvement and extension of the allowed values of k. This means that even for a more pronounced asymmetry, the system possesses a unique solution for any loading and no bifurcations can occur.

#### 2. Abstract setting

Let us denote by  $\Omega = (0, \pi) \times (0, 2\pi)$  the considered domain and by  $H = L^2(\Omega, \mathbb{R})$  the real Hilbert space equipped with the standard scalar product and the corresponding norm. Further, we denote by  $\mathcal{D}$ 

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