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Experimental validation of improved 3D SBP positioning algorithm in PET applications using UW Phase II Board

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7 Abstract

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Continuous scintillator-based detectors have been considered as a competitive and cheaper approach than highly pixelated discrete crystal positron emission tomography (PET) detectors, despite the need for algorithms to estimate 10 3D gamma interaction position. In this work, we report on the implementation 11 of a positioning algorithm to estimate the 3D interaction position in a contin-12 uous crystal PET detector using a Field Programmable Gate Array (FPGA). 13 The evaluated method is the Statistics-Based Processing (SBP) technique that 14 requires light response function and event position characterization. An algo-15 rithm has been implemented using the Verilog language and evaluated using a 16 data acquisition board that contains an Altera Stratix III FPGA. The 3D SBP 17 algorithm was previously successfully implemented on a Stratix II FPGA using 18 simulated data and a different module design. In this work, improvements were 19 made to the FPGA coding of the 3D positioning algorithm, reducing the total 20 memory usage to around 34%. Further the algorithm was evaluated using ex-21 perimental data from a continuous miniature crystal element (cMiCE) detector 22 module. Using our new implementation, average FWHM (Full Width at Half 23 Maximum) for the whole block is $1.71 \pm 1 \text{ mm}$, $1.70 \pm 1 \text{ mm}$ and $1.632 \pm 5 \text{ mm}$ 24 for x, y and z directions, respectively. Using a pipelined architecture, the FPGA 25 is able to process 245,000 events per second for interactions inside of the central 26 area of the detector that represents 64% of the total block area. The weighted 27 average of the event rate by regional area (corner, border and central regions) is 28

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