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## Sensitive dependence on parameters of continuous-time nonlinear dynamical systems



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#### a r t i c l e i n f o

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#### A B S T R A C T

The sensitive dependence of periodicity and chaos on parameters is investigated for three-dimensional nonlinear dynamical systems. Previous works have found that noninvertible low-dimensional maps present power-law exponents relating the uncertainty between periodicity and chaos to the precision on the system parameters. Furthermore, the values obtained for these exponents have been conjectured to be universal in these maps. However, confirmation of the observed exponent values in continuoustime systems remain an open question. In this work, we show that one of these exponents can also be found in different classes of three-dimensional continuous-time dynamical systems, suggesting that the sensitive dependence on parameters of deterministic nonlinear dynamical systems is typical.

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#### **1. Introduction**

The final asymptotic behavior of nonlinear dynamical systems can be severely affected by small perturbations in their control parameters [\[1\].](#page--1-0) The so-called parameter sensitivity has been experimentally observed in different areas of knowledge [\[2–5\].](#page--1-0) The cause of this sensitivity is the existence of bifurcation sets in parameters spaces that, regardless of any scale, provoke several topological changes in the system dynamics. One of the most drastic example is the conversion of stable periodic into chaotic behavior, or viceversa. The parameter sensitivity in this case dramatically limits the ability of someone surely set the parameters of a system to oscillate either in a chaotic or in a periodic behavior.

Following works studying the sensitivity of multiple attractors on the initial conditions and parameters  $[6,7]$ , the sensitive dependence of periodicity and chaos on parameters has been first addressed in 1985 by Grebogi et al.  $[8]$ . The authors have defined a scaling exponent,  $\alpha$ , such that for  $\alpha$  lower than 1, the system asymptotic solutions, periodic and chaotic, are regarded to be sensitive dependent on the system's parameters. By varying the unique parameter of an one-dimensional discrete-time system, the quadratic map, the authors have found the scaling exponent  $\alpha$  to be equal to 0.413(5), indicating the parameter sen-sitivity in this system. Also, in 1985 [\[9\],](#page--1-0) J.D. Farmer has proposed a different coarse-grained measure to quantify the parameter de-

<http://dx.doi.org/10.1016/j.chaos.2017.03.043> 0960-0779/© 2017 Elsevier Ltd. All rights reserved. pendence of periodicity and chaos, and use it to confirm sensitive dependence on parameters in the quadratic and sine maps. In these works this exponent reflects the topology of the boundary between parameter regions leading to chaotic and periodic be-havior. On the other hand, Hunt et al. [\[10\]](#page--1-0) have theoretically estimated the scaling exponent,  $\alpha$ , but only based on the topological properties of the boundaries between parameter regions describing large chaotic attractors (to be defined subsequently) and parameter regions describing periodic orbits of the quadratic map. In their analyses, they have found the scaling exponent  $\alpha$  to be equal to 0.51(3). This value of  $\alpha$  obtained by Hunt et al. indicates a low parameter sensitivity when only large chaotic attractors are considered. This issue has been addressed in 2014 by Joglekar et al.  $[11]$ , who found a general relationship between the two scaling exponent values previously defined. Moreover, they conjecture that these two values for the scaling exponent,  $\alpha$ , are universal for onedimensional quadratic maps.

However, a question that remains open at this point is whether these scaling exponents also apply to higher-dimensional systems, such the ones whose the dynamics is described by continuoustime equations, and more than one parameter is available to induce sensitivity.

In this work, we address the sensitive dependence on parameters of periodicity and chaos in two-dimensional parameters sets of continuous-time dynamical systems. Specifically, we quantify the sensitive on parameters of these systems by calculating the fraction of parameters that changes their corresponding asymptotic dynamical behavior under a given perturbation. We observe that

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**Fig. 1.** Typical two-dimensional  $a \times b$  parameter set of nonlinear dynamical systems. The white color indicates the parameters leading to periodicity (periodic windows). The gray color indicates parameters corresponding to chaos via perioddoubling bifurcation, and black color indicates parameters corresponding to chaos outside the windows (large chaotic attractors). The magnification shows a sequence of periodic windows immersed in a parameter region of chaos via period-doubling.

such fraction of uncertain parameters scales as a power-law with the magnitude of the perturbation, and therefore, yields the scaling exponent,  $\alpha$ . Moreover, we verify that the scaling exponent value, measured considering any chaotic attractor, is roughly the same within the three different classes of continuous-time systems here investigated, agreeing with the value obtained for the onedimensional, sine, and quadratic maps. This result suggests that the scaling exponent  $\alpha$  is a universal measure for the sensitive dependence of periodicity and chaos on parameters of nonlinear dynamical systems.

In parameters sets of nonlinear dynamical systems, the sensitive dependence of periodicity and chaos can be investigated by the way that their corresponding parameter subsets are arranged. The parameters leading to chaos is interwoven with continuous sets of parameters leading to periodic stable behavior, called periodic windows. Periodic windows are parameter sets, which in this work is assumed to contain parameter sets corresponding to a periodic orbit and its eventual bifurcated harmonic solutions. On the other hand, we consider complex structures, i.e., regions of parameter sets that contain scale-free accumulations of periodic windows and also parameters corresponding to chaos. More specifically, as a system parameter is varied, the periodic trajectory with the lowest period, *p*, appearing for a parameter inside a periodic window, undergoes a cascade of period-doubling bifurcations resulting in a "small" *p*-band chaotic attractor. Subsequently, such chaotic attractor goes through an interior crisis, at which the complex structures, containing chaos and periodicity, terminates giving place to a large chaotic attractor that is larger than the *p*-band chaotic one (small chaotic attractor) [\[11,12\].](#page--1-0) Furthermore, the chaotic regions describing attractors that become chaotic via period-doubling occurring inside a complex structure is also interwoven with other highorder complex structures that also contain parameters leading to chaos appearing via period-doubling cascades. The parameter region describing small chaotic attractors inside a lower-order complex structure becomes a region describing large chaotic attractors surrounding higher-order one. This hierarchical arrangement is repeated over and over again in all scales of parameter sets, generating the sensitive dependence on parameters in deterministic dynamical systems.

In Fig. 1, we show a typical complex structure commonly observed in the two-dimensional parameter sets of several systems [\[13–22\].](#page--1-0) The white regions are periodic windows and represent parameters leading to periodic solutions, gray represents the parameters leading to the small *p*-band chaotic attractors, and black represents the parameters leading to large chaotic attractors. Thus, in Fig. 1, one can see a complex structure that is formed by the white and gray color while the regions outside the complex structure is black. Since this complex structure has the terminator boundary curve at a border collision crisis (upper part), it is a primary complex structure. The inset box whose amplification can be seen in the upper right corner shows other periodic windows lying on a region dominated by multi-band chaotic attractors, the gray region. Each one of these cascading higher-order periodic windows forms a higher-order complex structure, if its neighboring multiband chaotic attractors are taken into consideration. Our analysis to measure the scaling exponent will be made considering such regions, where cascades of periodic windows accumulates into a primary complex structure.

In the last 20 years, the complex structures shown in Fig. 1 have been numerically observed in parameter sets of a large numbers of systems ranging from discrete-time biological oscillator to continuous-time lasers and chemical reactions models [\[13–22\].](#page--1-0) Furthermore, more recently, such periodic arrangements are being observed in parameter sets of electronic circuits in lab experiments [\[23–27\],](#page--1-0) increasing the interest in the sensitive dependence on parameters.

#### **2. Results**

Our numerical results are based on simulations of three different classes of continuous-time dynamical systems. In our calculations, we address parameter sets composed by sequences of highorder complex structure  $[28]$ , as in the inset of Fig. 1, sequences occur for parameters inside a complex structure in the border with the large chaotic attractors located outside the complex structure. In our computations, we consider chaotic attractors of all sizes, and we did not consider systems for which the parameters spaces are Riddled or Wada as discussed in Refs [\[29,30\].](#page--1-0)

To represent the class of oscillators for which the Shilnikov theorem can be applied [\[31–36\],](#page--1-0) we consider the Rössler oscillator. This system is described by the following set of nonlinear differential equations:

$$
\dot{x} = -y - z,
$$

$$
\dot{y} = x + ay,\tag{1}
$$

 $\dot{z} = (b + z)x - cz.$ 

and we study the parameter plane  $a \times c$ . The other parameter *b* of Eq. (1) is fixed at  $b = 0.3$  [\[17\].](#page--1-0)

The class of nonlinear forced oscillators are represented by the Morse oscillator which is governed by the following nonlinear differential equation [\[37\]:](#page--1-0)

$$
\ddot{x} + d\dot{x} + 8e^{-x}(1 - e^{-x}) = 2.5\cos(\omega t),
$$
 (2)

and we study the parameter plane  $\omega \times d$ .

We also work with a loss-modulated  $CO<sub>2</sub>$  laser described by a rate-equation with a time-dependent parameter:

$$
\dot{u} = \frac{1}{\tau} (z - k(t))u,
$$
  
\n
$$
\dot{z} = (z_0 - z)\gamma - uz,
$$
\n(3)

where  $k(t) = k_0(1 + a\cos 2\pi f t)$ . We study the  $a \times f$  parameter plane. All other parameters are fixed:  $\tau = 3.5 \times 10^9$  *s*,  $\gamma = 1.978 \times$  $10^5$  *s*<sup>−1</sup>, *z*<sub>0</sub> = 0.175, and  $k_0$  = 0.1731 [\[15\].](#page--1-0)

We numerically integrate Eq. from (1) to (3) using a Fourthorder Runge Kutta method and obtain the two-dimensional parameter spaces of those systems. In those parameters sets, we select  $N = 3.0 \times 10^4$  pairs of random parameters, say  $(a_0, b_0)$ , uniformly space distributed and compute the largest Lyapunov exponents of the trajectory of the considered systems for these random parameters to determine if the correspondent state is periodic ( $\lambda < 0$ )

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