# Classification of linear mappings between indefinite inner product spaces 

Juan Meleiro ${ }^{\text {a }}$, Vladimir V. Sergeichuk ${ }^{\text {b,* }}$, Thiago Solovera ${ }^{\text {a }}$, André Zaidan ${ }^{\text {a }}$<br>${ }^{\text {a }}$ Instituto de Matemática e Estatística, Universidade de São Paulo, Brazil<br>${ }^{\text {b }}$ Institute of Mathematics, Tereshchenkivska 3, Kiev, Ukraine

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#### Abstract

Let $\mathcal{A}: U \rightarrow V$ be a linear mapping between vector spaces $U$ and $V$ over a field or skew field $\mathbb{F}$ with symmetric, or skew-symmetric, or Hermitian forms $\mathcal{B}: U \times U \rightarrow \mathbb{F}$ and $\mathcal{C}: V \times V \rightarrow \mathbb{F}$. We classify the triples $(\mathcal{A}, \mathcal{B}, \mathcal{C})$ if $\mathbb{F}$ is $\mathbb{R}$, or $\mathbb{C}$, or the skew field of quaternions $\mathbb{H}$. We also classify the triples $(\mathcal{A}, \mathcal{B}, \mathcal{C})$ up to classification of symmetric forms and Hermitian forms if the characteristic of $\mathbb{F}$ is not 2 .


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## 1. Introduction

We consider a triple

$$
\begin{equation*}
\mathcal{A}: U \rightarrow V, \quad \mathcal{B}: U \times U \rightarrow \mathbb{F}, \quad \mathcal{C}: V \times V \rightarrow \mathbb{F} \tag{1}
\end{equation*}
$$

consisting of a linear mapping $\mathcal{A}$ and two forms $\mathcal{B}$ and $\mathcal{C}$ on finite-dimensional vector spaces $U$ and $V$ over a field or skew field $\mathbb{F}$ of characteristic not 2. Each of the forms $\mathcal{B}$ and $\mathcal{C}$ is either symmetric or skew-symmetric if $\mathbb{F}$ is a field, or both the forms are Hermitian with respect to a fixed nonidentity involution in $\mathbb{F}$.

A canonical form of the triple of matrices of (1) over a field $\mathbb{F}$ of characteristic not 2 was obtained in the deposited manuscript [22] up to classification of Hermitian forms over finite extensions of $\mathbb{F}$. The aim of this paper is to give a detailed exposition of this result and extend it to triples (1) over a skew field of characteristic not 2 . We give canonical matrices of $(1)$ over $\mathbb{R}, \mathbb{C}$, and the skew field of quaternions $\mathbb{H}$.

Other canonical matrices of (1) with nonsingular forms $\mathcal{B}$ and $\mathcal{C}$ over the fields $\mathbb{R}$ and $\mathbb{C}$ were given by Mehl, Mehrmann, and Xu [14-16], and by Bolshakov and Reichstein [2].

Following [22], we represent the triple (1) by the graph

in which $\varepsilon=+$ if $\mathcal{B}$ is symmetric or Hermitian and $\varepsilon=-$ if $\mathcal{B}$ is skew-symmetric; $\delta=+$ if $\mathcal{C}$ is symmetric or Hermitian and $\delta=-$ if $\mathcal{C}$ is skew-symmetric.

Choosing bases in $U$ and $V$, we give (1) by the triple $(A, B, C)$ of matrices of $\mathcal{A}, \mathcal{B}$, and $\mathcal{C}$. Changing bases, we can reduce it by transformations

$$
\begin{equation*}
(A, B, C) \mapsto\left(S^{-1} A R, R^{\star} B R, S^{\star} C S\right), \tag{3}
\end{equation*}
$$

in which $R$ and $S$ are nonsingular and

$$
M^{\star \imath}=M^{\top} \quad \text { or } \quad M^{\hat{\imath}}=\widetilde{M}^{\top}
$$

with respect to a fixed involution $a \mapsto \tilde{a}$ in $\mathbb{F}$. Thus, we consider the canonical form problem for matrix triples under transformations (3). We represent the matrix triple $(A, B, C)$ by the graph

$$
\begin{array}{ll}
m_{i}^{m} \underbrace{}_{n}\left(\begin{array}{l}
\text { ® }
\end{array}\right. & m:=\operatorname{dim} U,  \tag{4}\\
& n:=\operatorname{dim} V .
\end{array}
$$

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[^0]:    * Corresponding author.

    E-mail addresses: juan.meleiro@me.com (J. Meleiro), sergeich@imath.kiev.ua (V.V. Sergeichuk), thiago.solovera.nery@usp.br (T. Solovera), andre.zaidan@gmail.com (A. Zaidan).

