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## Generalization of Roth's solvability criteria to systems of matrix equations

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#### Abstract

W.E. Roth (1952) proved that the matrix equation AX - XB = C has a solution if and only if the matrices  $\begin{bmatrix} A & C \\ 0 & B \end{bmatrix}$  and  $\begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix}$  are similar. A. Dmytryshyn and B. Kågström (2015) extended Roth's criterion to systems of matrix equations  $A_i X_{i'} M_i - N_i X_{i''}^{\sigma_i} B_i = C_i$  (i = 1, ..., s) with unknown matrices  $X_1, \ldots, X_t$ , in which every  $X^{\sigma}$  is  $X, X^{\top}$ , or  $X^*$ . We extend their criterion to systems of unknown matrices. We also prove an analogous criterion for systems of quaternion matrix equations.

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Keywords: Systems of matrix equations, Sylvester equations, Roth's criteria

#### 1. Introduction

Roth [15] proved that the matrix equation AX - XB = C (respectively, AX - YB = C) over a field has a solution if and only if the matrices  $\begin{bmatrix} A & C \\ 0 & B \end{bmatrix}$  and  $\begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix}$  are similar (respectively, equivalent); see also [8, Section 4.4.22] and [11, Section 12.5].

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