



# Minimal wave speed for a class of non-cooperative reaction–diffusion systems of three equations

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## Abstract

In this paper, we study the traveling wave solutions and minimal wave speed for a class of non-cooperative reaction–diffusion systems consisting of three equations. Based on the eigenvalues, a pair of upper–lower solutions connecting only the invasion-free equilibrium are constructed and the Schauder’s fixed-point theorem is applied to show the existence of traveling semi-fronts for an auxiliary system. Then the existence of traveling semi-fronts of original system is obtained by limit arguments. The traveling semi-fronts are proved to connect another equilibrium if natural birth and death rates are not considered and to be persistent if these rates are incorporated. Then non-existence of bounded traveling semi-fronts is obtained by two-sided Laplace transform. Then the above results are applied to some disease-transmission models and a predator–prey model.

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## 1. Introduction

In this paper, we will study the following reaction–diffusion system:

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$$\begin{cases} \frac{\partial}{\partial t} u_1 = d_1 \Delta u_1 + f(u_1) - g_1(u), \\ \frac{\partial}{\partial t} u_2 = d_2 \Delta u_2 + g_2(u) - \delta_2 u_2, \\ \frac{\partial}{\partial t} u_3 = d_3 \Delta u_3 + g_3(u) - \delta_3 u_3, \end{cases} \quad (1.1)$$

where

$$x \in \mathbb{R}^n, \quad u_i = u_i(x, t), \quad i = 1, 2, 3, \quad u = (u_1, u_2, u_3), \quad \Delta = \sum_{j=1}^n \frac{\partial^2}{\partial x_j^2},$$

and all the parameters are positive. The unknowns  $u_i, i = 1, 2, 3$  denote the densities of population, virus, etc. We first present some basic biological assumptions on functions  $f(u_1)$  and  $g_i(u), i = 1, 2, 3$ . Some notations are first needed to give these assumptions. Define

$$\begin{aligned} \mathbb{R}_+^3 &:= \{(u_1, u_2, u_3) : u_1 > 0, u_2 > 0, u_3 > 0\}, \\ g_{i,j}(u) &:= \frac{\partial g_i(u)}{\partial u_j}, \quad g_{i,jk}(u) := \frac{\partial^2 g_i(u)}{\partial u_j \partial u_k}, \quad i, j, k = 1, 2, 3. \end{aligned}$$

Then the first three assumptions are as follows.

- (A1)  $f(\cdot) \in C^1([0, \infty))$ ,  $g_i(\cdot) \in C^2(\text{cl}(\mathbb{R}_+^3))$ ,  $i = 1, 2, 3$ , where  $\text{cl}(\mathbb{R}_+^3)$  denotes the closure of  $\mathbb{R}_+^3$ .  
 (A2) (I) Either  $f(u_1) \equiv 0$  or  $f(u_1)$  satisfies

$$f(K) = 0, \quad f'(K) < 0, \quad f(u_1)(u_1 - K) < 0 \text{ for } u_1 \in (0, K) \cup (K, +\infty),$$

and  $f'(0) > 0$  if  $f(0) = 0$ .

- (II)  $g_i(u) > 0, g_i(u_1, 0, 0) = 0$  and  $g_1(0, u_2, u_3) = 0$  for  $u \in \mathbb{R}_+^3, i = 1, 2, 3$ .  
 (A3) (I)  $g_{i,j}(u) \geq 0, g_{2,3}(u_1, 0, 0) > 0, g_{3,2}(u_1, 0, 0) > 0, i, j = 1, 2, 3$  for  $u \in \mathbb{R}_+^3$ .  
 (II)  $g_{i,j1}(u) \geq 0, i, j = 2, 3, g_{2,21}(u) + g_{2,31}(u) > 0, u \in \mathbb{R}_+^3$ . The Hessian matrices  $\mathcal{H}[g_i(u_1, \cdot)](u), i = 1, 2, 3$  are negative semi-definite for  $u \in \mathbb{R}_+^3$ , where

$$\mathcal{H}[g_i(u_1, \cdot)](u) := \begin{bmatrix} g_{i,22}(u) & g_{i,23}(u) \\ g_{i,32}(u) & g_{i,33}(u) \end{bmatrix}.$$

**Remark 1.1.** From (A1) it follows that  $g_{i,jk}(u), i, j, k = 2, 3$  are bounded in a small neighborhood  $\mathcal{U}$  of the equilibrium  $E_0(K, 0, 0)$ . In this paper we always suppose (A1)–(A3) are satisfied.

It follows from (A2) and (A3) that the interaction between  $u_2$  and  $u_3$  is cooperative and that both of  $u_2$  and  $u_3$  have negative or non-positive effects on  $u_1$ . System (1.1) is consequently non-cooperative or non-monotonic. If  $f(u_1) = d(K - u_1)$  or  $f(u_1) \equiv 0$ , system (1.1) can serve as an SIR model with two progression stages [23, model (16)], an SEIR model [25] or a virus

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