

The Maslov index for Lagrangian pairs on  $\mathbb{R}^{2n}$ P. Howard<sup>a,\*</sup>, Y. Latushkin<sup>b</sup>, A. Sukhtayev<sup>c</sup><sup>a</sup> Mathematics Department, Texas A&M University, College Station, TX 77843, USA<sup>b</sup> Mathematics Department, University of Missouri, Columbia, MO 65211, USA<sup>c</sup> Mathematics Department, Indiana University, Bloomington, IN 47405, USA

## ARTICLE INFO

## Article history:

Received 1 August 2016

Available online 28 February 2017

Submitted by P. Exner

## Keywords:

Eigenvalues

Maslov index

Morse index

Schrödinger operators

## ABSTRACT

We discuss a definition of the Maslov index for Lagrangian pairs on  $\mathbb{R}^{2n}$  based on spectral flow, and develop many of its salient properties. We provide two applications to illustrate how our approach leads to a straightforward analysis of the relationship between the Maslov index and the Morse index for Schrödinger operators on  $[0, 1]$  and  $\mathbb{R}$ .

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## 1. Introduction

With origins in the work of V.P. Maslov [16] and subsequent development by V.I. Arnol'd [1], the Maslov index on  $\mathbb{R}^{2n}$  is a tool for determining the nature of intersections between two evolving Lagrangian subspaces (see Definition 1.1). As discussed in [6], several equivalent definitions are available, and we focus on a definition for Lagrangian pairs based on the development in [4] (using the definition of spectral flow introduced in [17]). We note at the outset that the theory associated with the Maslov index has now been extended well beyond the simple setting of our analysis (see, for example, [4,7,8,10]); nonetheless, the Maslov index for Lagrangian pairs on  $\mathbb{R}^{2n}$  is a useful tool, and a systematic development of its properties is certainly warranted.

As a starting point, we define what we will mean by a *Lagrangian subspace* of  $\mathbb{R}^{2n}$ .

**Definition 1.1.** We say  $\ell \subset \mathbb{R}^{2n}$  is a Lagrangian subspace if  $\ell$  has dimension  $n$  and

$$(Jx, y)_{\mathbb{R}^{2n}} = 0,$$

for all  $x, y \in \ell$ . Here,  $(\cdot, \cdot)_{\mathbb{R}^{2n}}$  denotes Euclidean inner product on  $\mathbb{R}^{2n}$ , and

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$$J = \begin{pmatrix} 0 & -I_n \\ I_n & 0 \end{pmatrix},$$

with  $I_n$  the  $n \times n$  identity matrix. We sometimes adopt standard notation for symplectic forms,  $\omega(x, y) = (Jx, y)_{\mathbb{R}^{2n}}$ . Finally, we denote by  $\Lambda(n)$  the collection of all Lagrangian subspaces of  $\mathbb{R}^{2n}$ , and we will refer to this as the *Lagrangian Grassmannian*.

A simple example, important for intuition, is the case  $n = 1$ , for which  $(Jx, y)_{\mathbb{R}^2} = 0$  if and only if  $x$  and  $y$  are linearly dependent. In this case, we see that any line through the origin is a Lagrangian subspace of  $\mathbb{R}^2$ . As a foreshadowing of further discussion, we note that each such Lagrangian subspace can be identified with precisely two points on the unit circle  $S^1$ .

More generally, any Lagrangian subspace of  $\mathbb{R}^{2n}$  can be spanned by a choice of  $n$  linearly independent vectors in  $\mathbb{R}^{2n}$ . We will generally find it convenient to collect these  $n$  vectors as the columns of a  $2n \times n$  matrix  $\mathbf{X}$ , which we will refer to as a *frame* for  $\ell$ . Moreover, we will often write  $\mathbf{X} = \begin{pmatrix} X \\ Y \end{pmatrix}$ , where  $X$  and  $Y$  are  $n \times n$  matrices.

Given any two Lagrangian subspaces  $\ell_1$  and  $\ell_2$ , with associated frames  $\mathbf{X}_1 = \begin{pmatrix} X_1 \\ Y_1 \end{pmatrix}$  and  $\mathbf{X}_2 = \begin{pmatrix} X_2 \\ Y_2 \end{pmatrix}$ , we can define the complex  $n \times n$  matrix

$$\tilde{W} = -(X_1 + iY_1)(X_1 - iY_1)^{-1}(X_2 - iY_2)(X_2 + iY_2)^{-1}, \quad (1.1)$$

which we will see in Section 3 is unitary. (We will also verify in Section 3 that  $(X_1 - iY_1)$  and  $X_2 + iY_2$  are both invertible, and that  $\tilde{W}$  is independent of the choice of frames we take for  $\ell_1$  and  $\ell_2$ .) Notice that if we switch the roles of  $\ell_1$  and  $\ell_2$  then  $\tilde{W}$  will be replaced by  $\tilde{W}^{-1}$ , and since  $\tilde{W}$  is unitary this is  $\tilde{W}^*$ . We conclude that the eigenvalues in the switched case will be complex conjugates of those in the original case.

**Remark 1.2.** We use the tilde to distinguish the  $n \times n$  complex-valued matrix  $\tilde{W}$  from the Souriau map (see equation (3.8) below), which is a related  $2n \times 2n$  matrix often—as here—denoted  $W$ . The general form of  $\tilde{W}$  appears in a less general context in [9,12]. For the special case  $\mathbf{X}_2 = \begin{pmatrix} 0 \\ I \end{pmatrix}$  (associated, for example, with Dirichlet boundary conditions for a Sturm–Liouville eigenvalue problem) we see that

$$\tilde{W} = (X_1 + iY_1)(X_1 - iY_1)^{-1}, \quad (1.2)$$

which has been extensively studied, perhaps most systematically in [2] (particularly Chapter 10). If we let  $\tilde{W}_D$  denote (1.2) for  $\mathbf{X}_1 = \begin{pmatrix} 0 \\ I \end{pmatrix}$  and for  $j = 1, 2$  set

$$\tilde{W}_j = (X_j + iY_j)(X_j - iY_j)^{-1},$$

then our form for  $\tilde{W}$  can be viewed as the composition map

$$-\tilde{W}_1 \tilde{W}_D (\tilde{W}_2 \tilde{W}_D)^{-1} = -\tilde{W}_1 (\tilde{W}_2)^{-1}. \quad (1.3)$$

For a related observation regarding the Souriau map see Remark 3.3.

Combining observations from Sections 2 and 3, we will establish the following theorem (cf. Lemma 1.3 in [4]).

**Theorem 1.3.** Suppose  $\ell_1, \ell_2 \subset \mathbb{R}^{2n}$  are Lagrangian subspaces, with respective frames  $\mathbf{X}_1 = \begin{pmatrix} X_1 \\ Y_1 \end{pmatrix}$  and  $\mathbf{X}_2 = \begin{pmatrix} X_2 \\ Y_2 \end{pmatrix}$ , and let  $\tilde{W}$  be as defined in (1.1). Then

$$\dim \ker(\tilde{W} + I) = \dim(\ell_1 \cap \ell_2).$$

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