



Exponential and fixed-time synchronization of Cohen–Grossberg neural networks with time-varying delays and reaction-diffusion terms[☆]



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ABSTRACT

This paper is devoted to the global exponential and fixed-time synchronization of delayed reaction-diffusion Cohen–Grossberg neural networks. Adaptive controllers are designed such that the addressed system can realize global exponential synchronization goal under the framework of inequality techniques, Lyapunov method as well as some suitable assumptions. Furthermore, as corollaries, the corresponding conclusion is provided to ensure the delayed Cohen–Grossberg neural networks without reaction-diffusion term can reach fixed-time synchronization goal. In addition, the settling time of fixed-time synchronization can be adjusted to desired values regardless of initial conditions, which is more reasonable. Finally, two numerical examples and its simulations are given to show the effectiveness of the obtained results.

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1. Introduction

As one of the most popular and typical neural networks, Cohen–Grossberg system was initially proposed in 1983 [1], which contains some well-known neural network models as its special cases, such as cellular NNs, Hopfield NNs, and bidirectional associative memory NNs. In the past few decades, this kinds of system have received increasing interesting due to its wide application in classification, pattern formation, association memories, parallel computation and solving optimization problems. Such applications heavily rely on its dynamical behaviors, thus, the qualitative analysis of its dynamical behaviors is a necessary step for the practical design and application of neural networks [2–9].

In the course of studying neural networks, it is found that the diffusion phenomena could not be ignored in neural networks and electric circuits once electrons transport in a nonuniform electromagnetic field. For example, the multilayer

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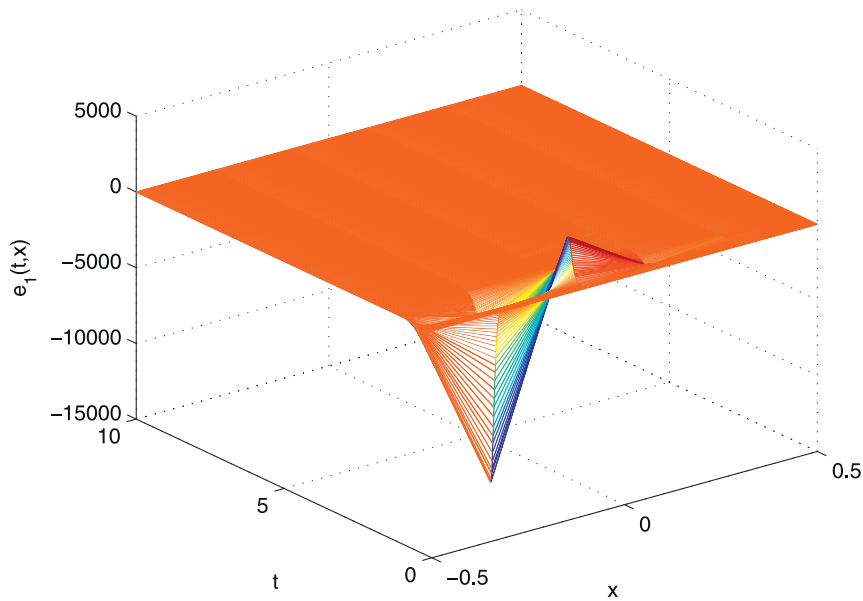


Fig. 1. Synchronization errors $e_1(t, x)$ between systems (1) and (4) under the adaptive controller (8).

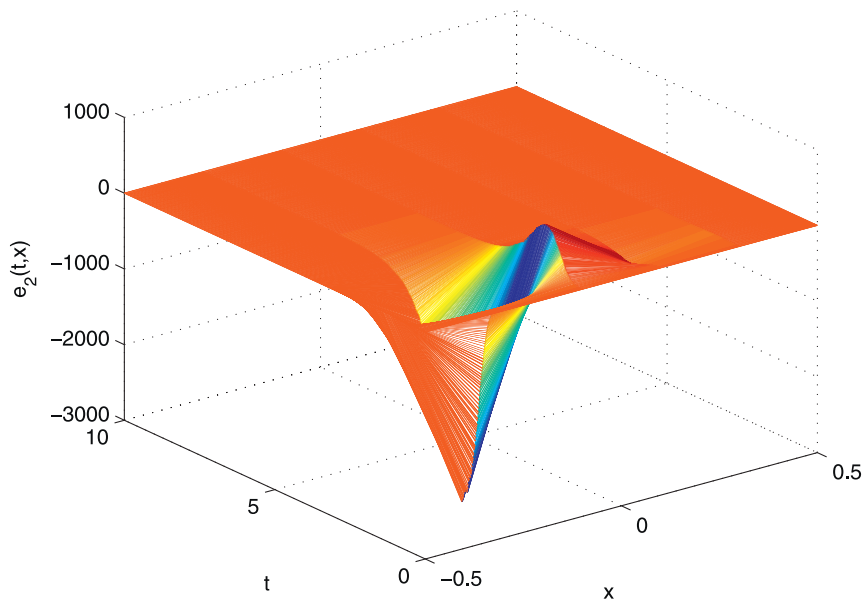


Fig. 2. Synchronization errors $e_2(t, x)$ between systems (1) and (4) under the adaptive controller (8).

cellular neural networks (MCNNs) are arrays of nonlinear and simple computing elements characterized by local interactions between cells, therefore, the paradigm are well suited to describe locally interconnected simple dynamical systems showing a lattice-like structure [10]. In other words, the whole structure and dynamic behavior of MCNNs are seriously dependent on the evolution time of each variable and its position (space), as well as its interactions deriving from the space-distributed structure of whole networks. So, it is essential to consider the state variables varying with time and space variables. On the other hand, there are a large number of reaction-diffusion phenomena in nature and many discipline fields, especially in chemistry and biology fields. Thus, it is natural to consider the states of the neurons vary in space as well as in time [11–16].

Synchronization, which means that two or more systems share a common dynamical behavior, and this common behavior can be induced by coupling or by external force. In the real world, synchronization phenomenon is very important in consideration of its potential applications in many different areas including secure communication, biology systems, optics, and information processing [17–29]. By means of impulsive control technique, the corresponding lag synchronization

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