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Reactive surface of glass particles under aqueous corrosion

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Abstract

Glass dissolution rates are normalized to the glass surface area in contact with solution, and experiments are very often carried out using crushed and sieved materials whose size is narrowed between an upper and a lower value. Surface area of such particles could be determined by gas adsorption or geometric considerations. Although crushed particles cannot be assimilated with simple geometric shapes, rates normalized with—spheres of the same size—geometric surface area are underestimated but are close to those found for polished monoliths. Overestimation of the reactive surface when using gas adsorption measurements is discussed. © 2017 The Authors. Published by Elsevier B.V. This is an open access article under the CC BY-NC-ND license

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1. Introduction

With the choice of geological repository for nuclear waste glasses, many countries are driven to study aqueous dissolution of glass to assess long-term behavior of glass canisters. Many experimental protocols meant to study glass dissolution mechanisms and kinetics involve particles. Two main methods are currently used to measure their surface area: gas adsorption with application of the BET model¹ or geometrical measurement—assuming glass particles as smooth and non-porous spheres.

Surface areas measured by gas adoption (S_{BET}) are systematically higher than geometric surface areas (S_{geo}) by a factor of 1.6 to 4.5^{2,3}. This gap raise a persisting debate in the community about the best way to evaluate the "reactive surface" of glass particles, defined here as the relevant glass/water interfacial area.

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The quantification of this surface is important for the description and the modeling of interfacial processes such as glass dissolution. This surface area has also a direct influence on the normalized alteration rates measured during leaching tests (commonly expressed in $g \cdot m^{-2} \cdot d^{-1}$). Previous studies²⁻⁵ concluded that alteration rates normalized to S_{geo} are closer—than those normalized to S_{BET} —to those measured on polished monoliths. However, crushed glass particles are not spherical and their surface irregularities are not taken into account in S_{geo} calculation. Improving the methodology for reactive surface measurement and understanding the difference between S_{BET} and S_{geo} is the objective of this experimental study.

2. Materials and methods

2.1. Glass samples

Two glasses (Table 1) were used in the present study: the international nuclear reference glass (ISG glass) and Type S SiLibeads[®] glass beads (Sigmund Lindner) whose geometry is mastered and produced from soda lime glass by a thermal rounding process. ISG glass powders were obtained by successive crushing and sieving steps. Rectangular monoliths of these two glasses were cut and polished using SiC abrasive papers before a final polishing involving diamond suspensions of 6 μ m, 3 μ m and 1 μ m.

Table 1. International Simple Glass (ISG) and Type S glass compositions expressed in oxide weight percent.

ISG glass	SiO ₂	B_2O_3	Na ₂ O	Al_2O_3	CaO	ZrO ₂
Oxide wt%	56.2±1.5	17.3±0.9	12.2±0.7	6.1±0.8	5.0±0.6	3.3±0.5
Type S glass	SiO ₂	Na ₂ O	CaO	MgO	Al_2O_3	
Oxide wt%	72.5±0.9	13.0±0.8	9.1±0.3	4.2±0.1	0.6±0.2	

2.2. Solid analyses

Surface area measurements. S_{BET} was measured by Kr adsorption on sample surface (Micromeritics ASAP 2020). The estimation of the amount of gas needed to form a monolayer on the solid surface was estimated by the BET model¹. S_{geo} was calculated assuming a spherical geometry for smooth non-porous glass particles with normally distributed sizes: $S_{\text{geo}} = 3/(\rho \cdot R)$ where ρ is the glass density and R the average radius of the particles. S_{geo} of monoliths was determined using a digital caliper (their surface area is far too low to perform S_{BET} measurements).

Atomic Force Microscopy (AFM). A Multimode 8 and Nanoscope V controller (Veeco, Santa Barbara, CA) was used in Tapping Mode (free amplitude ≈ 1 V with RTESP antimony (n) doped silicium tips, K = 40 N·nm⁻¹, $f_0 = 300$ kHz, Bruker) or PeakForce Mode (force ≈ 100 pN with a SNL silicon tip on Nitride lever, K = 0.35 N·nm⁻¹, Bruker). Measured topography data were processed by NanoScope Analysis software v1.40 to calculate the difference ΔS between the analyzed region's three dimensional surface area and its two-dimensional, footprint area.

Leaching tests and solution analysis. Glass initial dissolution rates (r_0) were determined by static leaching tests at 90°C. The leaching solution consisted of a KOH solution giving a pH_{90°C} of 10 ± 0.1, continuously stirred and always sufficiently diluted ([Si] < 3 mg·L⁻¹). Dissolved silica concentrations—used for r_0 calculations—were determined photometrically (Merck Spectroquant[®] Silicate Test, Cary[®] 50 Scan UV-Vis spectrophotometer) with a method analogous to ASTM D859-10.

3. Results and discussion

3.1. SBET VS Sgeo

For ISG crushed glass particles, the $S_{\text{BET}}/S_{\text{geo}}$ ratio is 2.6 ± 0.2 (Table 2), showing the difference between a smooth, non-porous sphere and a glass particle with a complex shape and presenting surface features accessible to gas atoms. For Type S beads—highly spherical sample (sphericity values of 0.92 to 0.97^6)—this ratio is reduced to 1.7 ± 0.4 (Table 2), but still higher than 1. This indicates that glass surface present defects accessible to gas atoms, increasing S_{BET} . The difference between S_{BET} and S_{geo} can thus be explained by the existence of a "shape factor" F_s

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