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# Physics instruction induces changes in neural knowledge representation during successive stages of learning

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35 30 ABSTRACT

Incremental instruction on the workings of a set of mechanical systems induced a progression of changes in the 15 neural representations of the systems. The neural representations of four mechanical systems were assessed be- 16 fore, during, and after three phases of incremental instruction (which first provided information about the sys-  $rac{1}{2}7$ tem components, then provided partial causal information, and finally provided full functional information). In 18 14 participants, the neural representations of four systems (a bathroom scale, a fire extinguisher, an automobile braking system, and a trumpet) were assessed using three recently developed techniques: (1) machine learning 🛱 and classification of multi-voxel patterns; (2) localization of consistently responding voxels; and (3) representa- 21 tional similarity analysis (RSA). The neural representations of the systems progressed through four stages, or 22 states, involving spatially and temporally distinct multi-voxel patterns: (1) initially, the representation was pri-23 marily visual (occipital cortex); (2) it subsequently included a large parietal component; (3) it eventually became 24 cortically diverse (frontal, parietal, temporal, and medial frontal regions); and (4) at the end, it demonstrated a 25 strong frontal cortex weighting (frontal and motor regions). At each stage of knowledge, it was possible for a clas-26 sifier to identify which one of four mechanical systems a participant was thinking about, based on their brain ac- 27 tivation patterns. The progression of representational states was suggestive of progressive stages of learning: 28 (1) encoding information from the display; (2) mental animation, possibly involving imagining the components 29 moving; (3) generating causal hypotheses associated with mental animation; and finally (4) determining how a 30 person (probably oneself) would interact with the system. This interpretation yields an initial, cortically- 31 grounded, theory of learning of physical systems that potentially can be related to cognitive learning theories 32 by suggesting links between cortical representations, stages of learning, and the understanding of simple 33 systems. 34

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# 3840 Introduction

41 Just knowing what some mechanical system accomplishes is often sufficient. Sometimes it is enough to know that when you aim a fire ex-42tinguisher and squeeze the handle, a fire-suppressing fluid sprays onto 43the fire. But how does it work? Learning how a mechanical device works 44 45through instruction is a critical part of many jobs. Understanding the psychological and neural processes that occur during such learning 46 can now be studied with brain imaging to reveal how new technical 47 48 knowledge is built up in the brain in the course of instruction.

A main aim of this research was to show how the neural representa tions of specific technical knowledge change as a result of acquiring new
information. Of course, there are many other types of changes in the
brain following training or instruction that have been reported. There

http://dx.doi.org/10.1016/j.neuroimage.2014.12.086 1053-8119/© 2015 Published by Elsevier Inc. are three critical differences between prior investigation of brain chang- 53 es due to learning and this research, measured here are: (1) changes in 54 representation as opposed to structural changes; (2) changes due to 55 instruction-based learning as opposed to training, specifically in the sci- 56 ence domain of the physics of mechanical systems; and (3) changes in 57 the neural representation of acquired knowledge as opposed to activa- 58 tion changes during a performance of a task. 59

For example, structural brain changes due to training have been 60 observed in the cortical responses of multiple units in cats (Merzenich, 61 1975), rats (Kilgard and Merzenich, 1998), and adult monkeys 62 (Recanzone et al., 1993). At a more molar level, learning-based changes 63 in grey and white matter have been observed in human participants 64 (see Fields, 2011; Lövdén et al., 2013; Thomas and Baker, 2013; Zatorre 65 et al., 2012 for reviews). For example, gray and white matter changes 66 were observed when people were trained in juggling (Draganski et al., 67 2004). Evidence that structural changes occur with training also comes 68 from visuo-motor tasks, working memory tasks, and aerobics. Many of 69 these studies involve tasks in which learning occurs as an effect of repeat-70 ed training trials rather than being due to learning from instruction (as 71 might occur in a classroom).

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73 A number of tasks have shown brain-based changes in activation 74 patterns due to training or instruction-based learning. Typically, these 75tasks examine brain changes in activation, in which it may be difficult 76 to separate new representations from learned processes. Examples of tasks that examine activation in training-based learning include artifi-77 cial grammars (Petersson, Folia, & Hagoort, 2012), perceptual category 03 learning (Poldrack et al., 2001), and motor learning (Toni, Krams, 05 04 Turner, & Passingham, 1998). Instruction-based learning tasks such as 80 81 algebra (Anderson et al., 2012 have also resulted in activation changes. 82 One study demonstrated both activation changes and white matter 83 changes as a result of both instruction and repeated training in word decoding in children with dyslexia (Meyler et al., 2008; Keller & Just, Q7 Q6 2009). Unlike these previous studies, here we look not for changes in 85 86 tissues or in regional activation, but in the neural representations of specific concepts using recent methods that can identify the nature of the 87 information that is being coded by a given fMRI activation pattern. 88

The neural changes in our study were assessed in terms of the multi-89 90 voxel fMRI-measured activation pattern that occurs when participants think about how a particular mechanical system works. More precisely, 91 the study assessed how their neural representation of a system changed 92as they learned more about its workings. The change in knowledge 93 94 about specific mechanical systems should produce measureable chang-95es in the neural representations of those systems. Furthermore, the changes may be directly related to the content of the instruction, such 96 that instruction that describes shared properties between systems 97 may increase their neural similarity. 98

Participants were taught with a series of successive increments of in-99 100 formation about mechanical systems. The first level of explanation provided information about the components of the mechanical systems. 101 The second increment included limited functional information. The 102third increment of explanation included the entire functional and causal 103 104 sequence of the components of the mechanical systems. Each of these 105instructional steps should result in discernable neural changes. More specifically, the progressive deepening of the explanations of the sys-106 tems might be expected to produce increasing involvement of cortical 107 systems implementing higher-level psychological processes, and un-108 109 changing involvement of lower level perceptual systems that process 110 the visual stimulus.

Despite the absence of prior neuroimaging investigations of mechan-111 ical systems, previous research in the brain bases of general cognitive 112 processes does provide guidance as to which cortical systems might be 113 114 involved. A set of eight potential cognitive processes, which have previously been associated with cortical systems, are postulated to correspond 115 to regions or small sets of regions (networks) involved in understanding 116 how mechanical systems work. These eight processes (and postulated 117 cortical systems) consist of: (1) mental animation (bilateral parietal: 118 119Boronat et al., 2005), (2) causal reasoning (right temporo-parietal and medial prefrontal: Mason and Just, 2011), (3) embodied cognition (pre-120 and post-central: Rueschemeyer et al., 2010), (4) semantic knowledge 121 (left temporal: Price, 2000), (5) language in context (bilateral inferior 122frontal: Mestres-Missé et al., 2008), (6) biological/goal-directed motion 123124(right temporal: Pelphrey et al., 2003), (7) rule learning (middle and su-125perior frontal: Bunge, 2004), and (8) visual processing (occipital cortex). The contributions of these various systems might be expected to shift as 126127the instruction and learning progresses.

The goal of this study was to examine the changes in the neural rep-128129resentation over the course of learning and instruction, rather than establishing the correspondence between cognitive functions and brain 130regions. We developed several hypotheses concerning changes in repre-131 sentation. First, prior to instruction, during the first exposure to only the 132diagram and label, the hypothesis is that the participating regions 133 would be primarily visual in nature, loading on the occipital cortex. Sub-134 sequent neural representations should involve relatively less occipital 135participation. Second, following the introduction of causality informa-136 tion, the representation could be expected to be distributed across a 137 138 large set of systems including causal inference related regions (medial frontal and right temporo-parietal) for inferring causal relations 139 among the components' motions. Third, bilateral parietal, particularly 140 the intraparietal sulcus, should increase in participation once compo- 141 nents of the mechanical systems are introduced as a result of imagining 142 components moving with respect to each other. Intuitively imagining 143 the components moving may be a part of mental animation (Hegarty, 144 1992). These hypotheses provide a starting point for examining the 145 changing involvement of cortical systems during learning. 146

Several recently developed methods for assessing neural knowledge 147 representations were used in the study. One of these was the machine 148 learning and classification of the multi-voxel activation patterns associat- 149 ed with each of the mechanical systems (Just et al., 2010; Mitchell et al., 150 2008). A related method analyzed the locations of the types of voxels 151 whose activation levels were modulated in a consistent way by the differ- 152 ent mechanical systems (Just et al., 2010). A third method used represen- 153 tational similarity analysis to assess how similarly-described systems 154 became neurally more similar (Connolly et al., 2012). These methods 155 can be used to converge on an account of how the neural representations 156 change as instruction and knowledge cumulate. 157

#### Materials and methods

**Participants** 

Fourteen college students (6 females, all right handed and native 160 speakers of English) between the ages of 18 and 26 years (M = 21.57; 161 SD = 2.79) participated and were included in all of the analyses (no 162) subjects were excluded). Each participant gave signed informed con- 163 sent approved by the Carnegie Mellon University Institutional Review 164 Board. Each participant received 5 minutes of practice with the experi- 165 mental paradigm on a single training item (that was not included in the 166 experimental stimuli) before performing the task in the scanner. In a 167 debriefing session, all participants responded positively when asked if 168 they felt they had gained an understanding of how the mechanical sys- 169 tems worked. Additionally, when they were asked if they had "prior 170 knowledge of how any of the systems worked" only one participant 171 said he had a very basic understanding of the systems. This participant's 172 data did not differ from the others' so it was retained in the analysis 173

#### Experimental design

In the scanner, participants were taught how four familiar devices 175 work (a bathroom scale, a fire extinguisher, car brakes, and a trumpet). 176 The systems were selected to vary across some potentially interesting 177 dimensions (e.g., manipulation by hand versus foot, being composed 178 of different types of mechanical components) as well as meeting two 179 criteria: (1) amenability of the explanation to segmentation into succes- 180 sive stages; (2) informal assessment that students who were not in sci- 181 ence or engineering would be unlikely to know how the system worked. 182

The experimental design consisted of the four items presented in 183 two types of blocks: thinking (or "test") blocks and explanation (or 184 "training") blocks. The experimental design and timing of all events 185 (presentations, blocks and scans) are shown in Fig. 1. In the thinking 186 blocks, which provide the main data for this study, participants were 187 presented with each of the four items and asked to "Think about how 188 this mechanical system might function." The explanation blocks cumu- 189 latively described how the components of each system work together to 190 cause the system to function. During the explanation blocks, subjects 191 were asked to read each sentence and "Think about the functioning of 192 each stage of the mechanical system." 193

In the thinking blocks, each stimulus item consisted of a realistic pic- 194 ture of the system above a schematic diagram and a verbal label for the 195 system, as shown in Fig. 2A. In a thinking block, the mechanical systems 196 were presented in six presentations (i.e., repetitions) of the four sys- 197 tems. The presentation order of the mechanical systems in each block 198 was randomized using a Latin square design with an additional 199

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