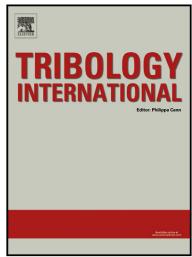
Author's Accepted Manuscript

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www.elsevier.com/locate/triboint

PII: S0301-679X(15)00305-9

DOI: http://dx.doi.org/10.1016/j.triboint.2015.07.014

Reference: JTRI3749

To appear in: Tribology International

Received date: 31 January 2015 Revised date: 27 June 2015 Accepted date: 15 July 2015

Cite this article as: Satoru Maegawa, Fumihiro Itoigawa, Takashi Nakamura, Effect of normal load on friction coefficient for sliding contact between rough rubber surface and rigid smooth plane, *Tribology International*, http://dx.doi.org/10.1016/j.triboint.2015.07.014

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Effect of normal load on friction coefficient for sliding contact between rough rubber surface and rigid

smooth plane

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Abstract

This study focused on the normal load dependence of the friction coefficient for the sliding friction of a rubber

material with a rough surface. A developed friction tester was used to visualize the real contact regions

distributed within the transparent contact interface between poly-dimethyl siloxane (PDMS) and glass surfaces.

Based on experimental results, an adhesion friction model was developed to explain the normal load dependence

of the friction coefficient. This model provides a simple technique that can roughly but easily estimate the real

contact area and shear stress without in situ observation of the contact interface.

Keywords: Friction coefficient, Normal load, Rubber, Real contact area

The friction model is an important subject in the design stage of mechanical systems involving contacting

surfaces. An accurate friction model contributes to the development of numerical simulations; it can promote the

primary performance of intended systems and avoid problems such as the occurrence of friction-induced

vibrations. However, modeling the friction is not easy because the friction force depends on a number of system

parameters such as the sliding speed, normal load, surface roughness, and contact configuration [1, 2].

Understanding the contact mechanism is imperative to establish an accurate model of sliding systems. For

conventional metallic materials, a number of theories considering the elastic, plastic, and elasto-plastic

deformations of contacting asperities have been established to explain the contact mechanism by theoretically

predicting the total area of real contact regions [3-8]. Some of these theories describe the total area of real

contact regions A_{real} as linearly increasing with the normal load W, i.e., $A_{\text{real}} \propto W$. Therefore, assuming that the

friction force F can be derived as the product of the total area of contact $A_{\rm real}$ and the shear strength τ , the

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