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# Thermal constriction phenomenon in fretting: Theory and implications<sup>☆</sup>

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## ABSTRACT

Contact temperature in fretting has a significant effect on the process. Since direct temperature measurement is impossible, analytical models are required to estimate the friction-induced temperature rise for the optimization of the system performance. The objective of this work is to present models for the micro and macro thermal constriction phenomena in fretting. The effect of the process parameters is examined. The analysis showed that the contact temperature rise can be quite significant when the contact pressure-to-hardness ratio is high and when the material thermal conductivity is low. The paper is concluded with recommendations for future work.

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## 1. Introduction

Due to the nature of engineering surfaces, the real contact area is a very small fraction of the apparent area of contact, giving rise to “thermal constriction (or spreading) phenomenon”. This phenomenon results in a steep temperature gradient in the subsurface layer, and possibly a significant rise in the contact temperature [1–4]. The friction-induced temperature rise in the fretting zone has far reaching effect on the oxidation process, the material microstructure, as well as its physical and mechanical properties. The effect of temperature on fretting has been investigated by many investigators [5–9]. The existence of transition temperature(s), at which the wear rate changes significantly, was observed in these studies. Therefore, proper laboratory simulation of fretting wear/fatigue tests requires that the contact temperature due to friction heating and external sources in the specimens and the original components to be identical [10].

The disturbed temperature field around the contact asperity is contained within a very shallow subsurface layer of the order of 50–100 μm, and changes rapidly within one-quarter of the oscillation cycle, which is typically of the order of 10 ms [2,11]. This demonstrates that with the physical dimensions and the response time of temperature sensing elements, the desired spatial and temporal resolutions cannot be achieved for direct measurement of the contact temperature. Presently, the contact

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temperature can only be estimated using analytical models and computer simulation tools. Such predictions are essential at the design and operation stages for the optimization of the fretting tribo-system parameters and its performance. To predict the response behavior of a real fretting tribo-system (of a complicated geometry, and realistic thermal boundary conditions), the division of frictional heat, and the thermal characteristic of the whole system should be considered. This can only be achieved using numerical methods, e.g., finite element and finite difference, similar to the work done to solve the heat transfer process in sliding tribo-systems [12–15]. In the analyses presented in [12,13], the thermal constriction resistance for constant, uniform heat flow in static contact was used. Ling and Pu [12] noted, however, that more detailed analysis of the thermal constriction resistance requires additional work. The only missing link in following this approach is the lack of qualitative understanding and quantitative modeling of the thermal constriction phenomenon.

This paper presents an overview of an analytical approach to formulate the thermal constriction phenomenon in fretting, in terms of the micro- and macroscopic features of the surface topography, the applied external load, the amplitude and frequency of oscillation, and the material properties. Since the temperature rise is directly proportional to the heat flow rate, the partitioning of the frictional heat between contacting solids has to be defined a priori. Satisfying the requirement for the continuity of the average contact temperature and the conservation of energy, a model for the heat partition coefficient is also presented. The debatable question on whether or not the contact temperature in fretting is high is addressed, considering a wide range of materials and applied loads. The paper is concluded with

**Nomenclature**

$a$	amplitude of oscillation, $\mu\text{m}$	$\bar{R}$	average radius of the randomly distributed micro-contact areas, m
$A_a$	apparent contact area, $\text{m}^2$	$S$	spacing between two neighboring micro-contacts, m
$A_c$	contact area, $\text{m}^2$	$t$	time, s
$A_{cn}$	contour contact area, $\text{m}^2$	$t_s$	distance between micro-contact contacts, m
$A_{hfc}$	cross-sectional area of the HFC, $\text{m}^2$	$u$	separation between the median plane of the equivalent rough surface and the smooth semi-infinite body, m
$A_{mic}$	micro-contact area, $\text{m}^2$	$v$	instantaneous relative velocity between contacting solids, $\text{m s}^{-1}$
$A_r$	real contact area, $\text{m}^2$	$V$	volume of the lumped body, $\text{m}^3$
$AR$	aspect ratio of the rectangular micro-contact area, $AR = H_x/H_y$	$x, y, z$	Cartesian coordinate system
$c_p$	material specific heat, $\text{J kg}^{-1} \text{K}^{-1}$	$\bar{x}, \bar{y}, \bar{z}$	dimensionless position coordinates, $\bar{x} = x/L$ , $\bar{y} = y/L$ , $\bar{z} = z/L$
$C_{th}$	thermal capacitance, $\text{J K}^{-1}$	$\mathbf{X}_{th}$	capacitive reactance component of the thermal impedance $\mathbf{Z}_c$ , $\text{K W}^{-1}$
$C$	the distributed electrical capacitance per unit length, $\text{F m}^{-1}$	$\mathbf{Z}_c$	thermal constriction impedance, $\text{K W}^{-1}$
$d$	distance, m	$\mathbf{Z}_{mac}$	macroscopic thermal constriction impedance, $\text{K W}^{-1}$
$e_x, e_y$	the eccentric position of the contact asperity with respect to the center of the HFC, m	$\mathbf{Z}_{mic}$	microscopic thermal constriction impedance, $\text{K W}^{-1}$
$e^*$	dimensionless eccentricity parameter, defined by Eq. (44), m	$\mathbf{Z}_{mic,t}$	total microscopic thermal constriction impedance of all HFC's, $\text{K W}^{-1}$
$\mathbf{E}(\dots)$	expected value	$\mathbf{Z}_{interface}$	overall thermal constriction impedance of the interface, $\text{K W}^{-1}$
$f$	frequency of oscillation, $\text{s}^{-1}$		
$f(h)$	Gaussian distribution of asperity height ( $h$ )	<i>Greek symbols</i>	
$F(t_s)$	probability density function of the distance $t_s$ between micro-contacts above the asperity height ( $h$ )	$\alpha$	material thermal diffusivity, $\text{m}^2 \text{s}^{-1}$
$Fo$	Fourier modulus, $Fo = \alpha/f\delta^2$ ; $Fo_{mic} = \alpha/f\delta_{mic}^2$ and $Fo_{mac} = \alpha/f\delta_{mac}^2$	$\Delta\beta$	included angle of a circular sector element, radian
$H$	hardness, $\text{N m}^{-2}$	$\gamma$	ratio of the contour area relative to the average micro-contact area
$H_x, H_y$	length and height of the rectangular heat flow channel, m	$\delta$	characteristic length of the heat source under consideration (Eq. (29)), m
$k$	material thermal conductivity, $\text{W m}^{-1} \text{K}^{-1}$	$\varepsilon^2$	constriction ratio, $\varepsilon^2 = A_r/A_a$
$L$	half the length of the side of an asperity of a square cross-section, $\mu\text{m}$	$\eta$	parameter defined in Eq. (28)
$L_{mac}$	half the length of the side of the contour area, $\mu\text{m}$	$\theta$	temperature rise, K
$ m $	mean absolute slope of the surface asperities, radian	$\theta_c$	contact temperature, K
$M$	number of micro-contacts within the contour area $A_{cn}$	$\theta_{c,max}$	maximum contact temperature of the micro-contact area, K
$n_{hfc}$	linear density of heat flow channels within the contour area, $n_{hfc} = \sqrt{M}/2L_{mac}$	$\theta_d$	temperature deviation in the thermally disturbed zone, K
$N_{nr}$	number of discrete heat sources in the near region	$\theta_i$	interface temperature under perfect contact conditions, K
$p_a$	applied pressure, $\text{N m}^{-2}$	$\theta_m$	mean temperature of the cross-section of the HFC at the contact plane, $z=0$ , K
$p_m$	flow pressure of the softer material, $\text{N m}^{-2}$	$\dot{\theta}$	rate of change of temperature, $\text{K s}^{-1}$
$q$	heat flux, $\text{W m}^{-2}$	$\bar{\theta}$	average temperature rise, K
$q_f$	instantaneous heat flux over the micro-contact area, $\text{W m}^{-2}$	$\Delta\bar{\theta}_c$	average contact temperature of the micro-contact area, K
$\bar{q}_f$	average heat flux over the micro-contact area during the fretting cycle, $\text{W m}^{-2}$	$\Delta\theta_c$	'pseudo' temperature drop at the contact interface, K
$q_e$	effective uniform heat flux, $q_e = \varepsilon^2 q_f$ , $\text{W m}^{-2}$	$\Delta\bar{\theta}_m$	temperature drop due to the material resistance in the thermally disturbed zone, K
$q_{fr}$	uniform heat flux over the far region, $q_e = \varepsilon^2 q_f$ , $\text{W m}^{-2}$	$\Theta$	dimensionless temperature parameter, $\Theta = (\theta k/q_f L)$
$q_{ihs}$	image heat source, $q_{ihs} = q_f$ , $\text{W m}^{-2}$	$\mu$	coefficient of friction
$q_o$	amplitude of the sinusoidal heat source, $\text{W m}^{-2}$	$\xi$	heat partitioning coefficient
$q_{shs}$	source heat source, $q_{shs} = q_f$ , $\text{W m}^{-2}$	$\rho$	mass density, $\text{kg m}^{-3}$
$q_{sin}$	sinusoidal uniform heat flux, $\text{W m}^{-2}$	$\Phi$	standard deviation of surface asperity heights, m
$Q$	total heat flow rate, W	$\varsigma$	parameter defined in Eqs. (40) and (41)
$Q_f$	total frictional heat flow rate over the contour contact area, W	$\tau$	period of reciprocation, s
$r$	radius of circular sector element, m	$N$	phase difference between the heat flow and the temperature at any point, radian
$R'$	the distributed electrical resistance per unit length, $\Omega \text{m}^{-1}$	$\Phi(\bar{R})$	probability density function of the size of the micro-contact areas
$\mathbf{R}_c$	thermal constriction resistance, $\text{K W}^{-1}$	$P$	constriction parameter for concentric contact
$\mathbf{R}_{th}$	resistive component of the thermal impedance $\mathbf{Z}_c$ , $\text{K W}^{-1}$	$P^*$	constriction parameter for eccentric contact
$\mathcal{R}$	radius of the equivalent circular heat source, m	$\omega$	circular frequency of reciprocation, $\omega = 2\pi f$ , $\text{s}^{-1}$
$\mathfrak{R}$	radius of the randomly distributed micro-contact areas, m		

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