

Contents lists available at ScienceDirect Journal of Mathematical Analysis and Applications





On a class of singular second-order Hamiltonian systems with infinitely many homoclinic solutions



David G. Costa*, Hossein Tehrani

Dept. of Math. Sciences, University of Nevada Las Vegas, Box 454020, Las Vegas, NV 89154-4020, USA

ARTICLE INFO

Article history: Received 16 May 2013 Available online 24 October 2013 Submitted by W. Sarlet

Keywords: Singular Hamiltonian system Homoclinic solution Periodic coefficients Category theory Strong-Force condition

ABSTRACT

We show existence of infinitely many homoclinic orbits at the origin for a class of singular second-order Hamiltonian systems

 $\ddot{u} + V_u(t, u) = 0, \quad -\infty < t < \infty.$

We use variational methods under the assumption that V(t, u) satisfies the so-called "Strong-Force" condition.

© 2013 Elsevier Inc. All rights reserved.

0. Introduction

The search for periodic as well as homoclinic and heteroclinic solutions of Hamiltonian systems has a long and rich history. In this paper we are particularly interested in homoclinic solutions of singular second-order Hamiltonian systems with time-periodic potentials. We refer the interested reader to the book [1] of Ambrosetti and Coti Zelati for results on the literature of periodic solutions for such singular systems.

Second-order Hamiltonian systems are systems of the form

 $\ddot{u} + V_u(t, u) = 0, \quad t \in \mathbb{R}, \ u \in \mathbb{R}^N.$

Loosely speaking, they are the Euler-Lagrange equations of the functional

$$I(u) = \int L(t, u, \dot{u}) \, dt,$$

where the integration is taken over a finite interval [0, T] or all reals \mathbb{R} and the *Lagrangian* has the form

$$L(t, u, \dot{q}) = \frac{1}{2} |\dot{u}|^2 - V(t, u).$$

Clearly, when the potential V(t, u) is *T*-periodic in *t*, it is natural to look for *T*-periodic solutions of (*HS*) as critical points of the functional I(u) over a suitable space of *T*-periodic functions. Also, in such a case, one can look for homoclinic solutions at the origin (i.e., solutions of (*HS*) satisfying $u(t), \dot{u}(t) \rightarrow 0$) as limits of *kT*-periodic solutions (*subharmonic solutions*) as $k \rightarrow \infty$ (see [17]) or, alternatively, as critical points of the functional I(u) over a suitable space of functions on the whole space \mathbb{R} (typically, $H^1(\mathbb{R}, \mathbb{R}^N)$).

* Corresponding author. E-mail addresses: costa@unlv.nevada.edu (D.G. Costa), tehranih@unlv.nevada.edu (H. Tehrani). (HS)

⁰⁰²²⁻²⁴⁷X/\$ – see front matter © 2013 Elsevier Inc. All rights reserved.

http://dx.doi.org/10.1016/j.jmaa.2013.10.056

For singular systems, one assumes that $V \in C^1(\mathbb{R} \times \mathbb{R}^N \setminus S)$ and $\lim_{u \to S} |V(t, u)| = \infty$ for some $S \subset \mathbb{R}^N$. Although the study of singular systems is perhaps as old as the Kepler classical problem in mechanics,

$$\ddot{u} + \frac{u}{|u|^3} = 0$$

(and, also, the N-body problem), the interest in such problems was renewed by the pioneering papers [13] of Gordon in 1975 and [14] of Rabinowitz in 1978. In [13] the notion of Strong-Force is introduced to deal with singular problems, while in [14] the use of variational methods is brought into the study of periodic solutions of Hamiltonian systems.

The present paper is concerned with existence of homoclinic solutions for second-order Hamiltonian systems

$$\ddot{u} + V_u(t, u) = 0,$$

where $-\infty < t < \infty$, $u = (u_1, u_2, \dots, u_N) \in \mathbb{R}^N$ and the potential $V : \mathbb{R} \times \mathbb{R}^N \setminus \{q\} \to \mathbb{R}$ has a singularity $0 \neq q \in \mathbb{R}^N$. We recall that a homoclinic solution of (HS) is a solution such that $u(t) \in \mathbb{R}^N \setminus \{q\}$ for all $t \in \mathbb{R}$ and

$$u(t), \dot{u}(t) \to 0 \text{ as } t \to \pm \infty.$$

Throughout the paper we will be considering the following assumptions on V(t, u):

- (A) V(t, u) = a(t)W(u), with $a \in C(\mathbb{R})$ a *T*-periodic function such that $a_0 \leq a(t) \leq a_\infty$ for some $a_0, a_\infty > 0$;
- (*H*₁) $W \in C^2(\mathbb{R}^N \setminus \{q\}, \mathbb{R})$ for some $q \in \mathbb{R}^N \setminus \{0\}$;
- $\begin{array}{l} (H_{2}) \ W(0) = W_{u}(0) = 0, \ W(u) < W(0) = 0 \ \text{for } u \neq 0, \ \text{and} \ -\alpha_{0}I \leqslant W_{uu}(0) \leqslant -\alpha_{1}I \ \text{for some} \ \alpha_{0}, \alpha_{1} > 0; \\ (H_{3}) \ \lim_{u \to q} W(u) = -\infty \ \text{and} \ \text{there exists} \ U \in C^{1}(\mathbb{R}^{N} \setminus \{q\}, \mathbb{R}) \ \text{such that} \ \lim_{u \to q} |U(u)| = \infty \ \text{and} \ W(u) \leqslant -|\nabla U(u)|^{2} \ \text{for} \end{array}$ $0<|u-q|\leqslant r;$
- (*H*₄) There exists $U_{\infty} \in C(\mathbb{R}^N \setminus B_{R_0}, \mathbb{R})$ such that $\lim_{|u| \to \infty} |U_{\infty}(u)| = \infty$ and $W(u) \leq -|\nabla U_{\infty}(u)|^2$ for u large.

Note that by our assumptions, W has a strict global maximum at u = 0 which by (H_2) is an unstable equilibrium of (HS). Furthermore (H_3) , (H_4) concern the behavior of W close to the singularity and at infinity. In fact, (H_3) indicates that the potential W satisfies the Strong-Force condition mentioned earlier (used by Gordon in [13]) which governs the rate at which W(x) approaches $-\infty$ as $x \to q$. A typical example is $W(x) = |x-q|^{-\alpha}$ ($\alpha \ge 2$) in a neighborhood of q. On the other hand (H_4) allows W to go to zero at infinity although at a slow rate. This condition will be satisfied if, for example, $\lim_{|x|\to\infty} |x|^{\beta} W(x) \neq 0$ for some $\beta \in (0, 2]$.

In the case of autonomous singular Hamiltonian systems, the first result on existence of a homoclinic orbit using variational methods were obtained by Tanaka [21] under essentially the same assumptions as above. In [21] Tanaka used a minimax argument from Bahri and Rabinowitz [2] in order to get approximating solutions of the boundary value problems

$$\ddot{u} + V'(u) = 0, \quad t \in (-m, m), \qquad u(-m) = u(m) = 0$$

as critical points of the corresponding functionals, and obtained uniform estimates to show that those solutions converged weakly to a nontrivial homoclinic solution of (HS). Regarding multiplicity of homoclinics, still in the autonomous singular case, early results were obtained by Caldiroli [6], who showed existence of two homoclinic orbits, and by Bessi [4], who used Lyusternik–Schnirelmann category to prove the existence of N-1 distinct homoclinics for potentials satisfying a pinching condition (see also 1] and 22 for multiplicity results in case of smooth Hamiltonians). Different kinds of multiplicity results were obtained in [3,7] (still for conservative systems) by exploiting the topology of $\mathbb{R}^N \setminus S$, the domain of the potential, when the set *S* is such that the fundamental group of $\mathbb{R}^N \setminus S$ is nontrivial.

In the case of planar autonomous systems more extensive existence and multiplicity results were obtained. Indeed, under essentially the same conditions as above with N = 2. Rabinowitz showed in [16] that (HS) has at least a pair of homoclinic solutions by exploiting the topology of the plane and minimizing the energy functional on classes of sets with a fixed winding number around the singularity q (see also [5] for results in the case of two singularities). The result in [16] was substantially improved in [8] where, using the same idea, the authors show that a nondegeneracy variational condition introduced in [16] is in fact necessary and sufficient for the minimum problem to have a solution in the class of sets with winding number greater than 1 and, therefore, proved a result on existence of infinitely many homoclinic solutions.

On the other hand, in the case of T-periodic time dependent Hamiltonians in \mathbb{R}^N , existence of infinitely many homoclinic orbits was obtained for smooth Hamiltonians by using a variational procedure due to Séré in [18] and [19] for first order systems, and in [9] and [10] for second-order equations. In the case N = 2, using these ideas, Rabinowitz [15] constructed infinitely many multibump homoclinic solutions for V(t, u) of the form a(t)W(u), with a(t) being almost periodic and W(u)satisfying (A), $(H_1)-(H_4)$.

Our work here on homoclinic solutions of time-periodic singular equations was motivated by earlier works on periodic solutions of such equations as well as by [10], where homoclinic solutions in \mathbb{R}^N are considered in the case of second-order smooth Hamiltonians. As already mentioned, the main tool in [10] is a minimax procedure of Séré which leads to construction of infinitely many multibump homoclinics. By contrast, our approach to the singular problem uses category theory in order to obtain infinitely many homoclinics. In fact, we consider the action functional I on the full space $\Lambda = H^1(\mathbb{R}, \mathbb{R}^N \setminus \{q\})$ and use the fact that $Cat_A(A) = \infty$ (cf. Proposition 1.7) to generate a sequence of candidates to critical levels of *I*:

Download English Version:

https://daneshyari.com/en/article/6418555

Download Persian Version:

https://daneshyari.com/article/6418555

Daneshyari.com