



Comments on a new class of nonlinear conjugate gradient coefficients with global convergence properties



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ABSTRACT

In Rivaie et al. (2012) [1], an efficient CG algorithm has been proposed for solving unconstrained optimization problems. However, due to a wrong inequality (3.3) used in Rivaie et al., the proof of Theorem 2 and the global convergence Theorem 3 are not correct. We present the necessary corrections, then the proposed method in Rivaie et al. still converges globally. Finally, we report some numerical comparisons.

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1. Introduction

Due to low memory requirements and strong global convergence property, nonlinear conjugate gradient methods are efficient for solving the following unconstrained optimization problem,

$$\min f(x), \quad x \in R^n, \quad (1.1)$$

where $f: R^n \rightarrow R$ is a continuously differentiable function, especially if the dimension n is large.

The iterates of conjugate gradient methods for solving (1.1) are obtained by

$$x_{k+1} = x_k + \alpha_k d_k. \quad (1.2)$$

where α_k is a steplength. The steplength α_k is computed by carrying out some line search, and d_k is the search direction defined by

$$d_k = \begin{cases} -g_k, & \text{if } k = 1, \\ -g_k + \beta_k d_{k-1}, & \text{if } k \geq 2, \end{cases} \quad (1.3)$$

where β_k is a scalar, g_k is gradient of $f(x)$ at x_k . Varieties of this method differ in the way of selecting β_k .

In the recent paper [1], Rivaie et al. proposed a new class of nonlinear conjugate gradient coefficients which is called RMIL method. The parameter β_k in RMIL method is computed as follows

$$\beta_k^{\text{RMIL}} = \frac{g_k^T (g_k - g_{k-1})}{\|d_{k-1}\|^2} = \frac{g_k^T (g_k - g_{k-1})}{\|d_{k-1}\|^2}. \quad (1.4)$$

By using the following exact line search,

$$f(x_k + \alpha_k d_k) = \min_{\alpha \geq 0} f(x_k + \alpha d_k), \quad (1.5)$$

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the search direction d_k satisfies the sufficient descent condition:

$$g_k^T d_k = -\|g_k\|^2, \quad \forall k \geq 0. \tag{1.6}$$

Numerical comparisons show that this computational scheme outperforms some other conjugate gradient methods. However, due to a wrong inequality (3.3) used in Rivaie et al. [1], the proof of Theorem 2 and the global convergence Theorem 3 is not correct. In what follows, the necessary corrections will be presented.

2. Comments on the convergence of RMIL algorithm

Here, we firstly point out a wrong inequality used in Rivaie et al. [1], namely inequality (3.3) about β_k^{RMIL} , which plays a key role in global convergence analysis of Theorem 2 and Theorem 3.

In order to make the convergence proof easier, Rivaie et al. [1] first provided an upper bound for the coefficient β_k^{RMIL} . At (3.2) in [1], Rivaie et al. defined

$$\beta_{k+1}^{RMIL} = \frac{g_{k+1}^T (g_{k+1} - g_k)}{\|d_k\|^2} = \frac{\|g_{k+1}\|^2 - g_{k+1}^T g_k}{\|d_k\|^2}, \tag{2.1}$$

and stated that

$$0 \leq \beta_{k+1}^{RMIL} \leq \frac{\|g_{k+1}\|^2}{\|d_k\|^2}. \tag{2.2}$$

Since the sign of $g_{k+1}^T g_k$ in (2.1) cannot be identified as positive or negative, we can not obtain (2.2) ((3.3) in [1]). However, in the proof of Theorem 2 and Theorem 3 in [1], the inequality (2.2) ((3.3) in [1]) plays a critical role in global convergence analysis.

In order to accomplish the global convergence analysis of the RMIL method, we present a RMIL+ coefficient as follows

$$\beta_{k+1}^{RMIL+} = \begin{cases} \frac{g_{k+1}^T (g_{k+1} - g_k)}{\|d_k\|^2}, & \text{if } 0 \leq g_{k+1}^T g_k \leq \|g_{k+1}\|^2, \\ 0, & \text{otherwise.} \end{cases} \tag{2.3}$$

It is obvious that β_{k+1}^{RMIL+} satisfies (2.2) ((3.3) in [1]).

Following the same proof as Theorem 2 and Theorem 3 in [1], we can get global convergence with exact line searches.

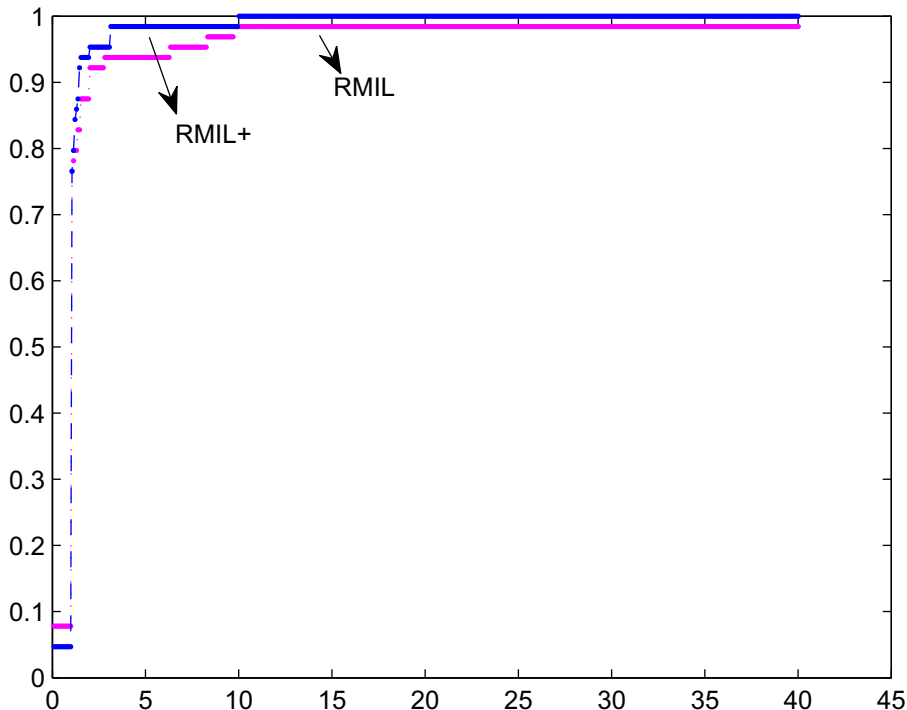


Fig. 1. Performance profiles with respect to CPU time.

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