Contents lists available at SciVerse ScienceDirect

Applied Mathematics and Computation

journal homepage: www.elsevier.com/locate/amc

Bifurcation from double eigenvalue for nonlinear equation with third-order nondegenerate singularity

Qiang Zhang^{a,b,*}, Dongming Yan^{b,c}, Zhigang Pan^{b,d}

^a School of Computer Science, Civil Aviation Flight University of China, Guanghan, Sichuan 618307, PR China

^b Department of Mathematics, Sichuan University, Chengdu, 610064, PR China

^c School of Mathematics and Statistics, Zhejiang University of Finance and Economics, Hangzhou, 310018, PR China

^d College of Mathematics, Southwest Jiaotong University, Chengdu, 610031, PR China

ARTICLE INFO

Keywords: Nonlinear equation Bifurcation Eigenvalue Lyapunov–Schmidt Singularity

ABSTRACT

In this paper, the steady state bifurcation from a double eigenvalue for nonlinear equation with singularity being second-order fully degenerate and third-order nondegenerate is investigated. By the normalized Lyapunov–Schmidt reduction method, the precise criteria for the existence and nonexistence of bifurcation and the topological properties of regular bifurcated branches are obtained.

© 2013 Elsevier Inc. All rights reserved.

1. Introduction

Let X_1 and X be two banach spaces, and $X_1 \subset X$ be a dense and compact inclusion. The main objective of this article is to give the precise criteria for the existence and nonexistence of bifurcation and the topological properties of regular bifurcated branches for the following nonlinear equation:

$$L_{\lambda}u + G(u,\lambda) = 0$$

where $L_{\lambda} = -A + B_{\lambda} : X_1 \rightarrow X$,

 $A: X_1 \subset X$ a linear homeomorphism,

 $B_{\lambda}: X_1 \to X$ a linear compact operator depending continuously on $\lambda \in \mathbf{R}$,

 $G(\lambda): X_1 \to X$ a C^{∞} operator depending continuously on $\lambda \in \mathbf{R}$, satisfying

 $G(u, \lambda) = G_2(u, \lambda) + G_3(u, \lambda) + o(||u||_{X_1}^3),$

where $G_2: X_1 \times X_1 \rightarrow X$ is a two-multiple linear mapping,

 $G_3: X_1 \times X_1 \times X_1 \rightarrow X$ is a three-multiple linear mapping, and $G_2(u, \lambda) = G_2(u, u, \lambda)$, $G_3(u, \lambda) = G_3(u, u, u, \lambda)$.

The bifurcation theory for nonlinear eigenvalue problems was initiated by Krasnoselskii [3] and Rabinowitz [4]. They give discussion of this problem and obtain the Krasnoselskii theorem and Rabinowitz global bifurcation theorem respectively. All these results prove the existence of a steady state bifurcation when the parameter λ crosses an eigenvalue of the linearized problem with odd multiplicity, but the existence of bifurcation when the parameter crosses an eigenvalue with even multiplicity remains unknown. For some other results concerning eigenvalue bifurcation, see [2,5,6,8] and references therein.

In [9], Ma and Wang establish the existence of bifurcation when the parameter λ crosses an eigenvalue with even multiplicity under additional condition that the singularity be even-order nondegenerate. However, there is no precise criteria for the existence of bifurcation from eigenvalues with even multiplicity if the singularity be odd-order nondegenerate.

0096-3003/\$ - see front matter @ 2013 Elsevier Inc. All rights reserved. http://dx.doi.org/10.1016/j.amc.2013.06.024







^{*} Corresponding author at: School of Computer Science, Civil Aviation Flight University of China, Guanghan, Sichuan 618307, PR China. *E-mail addresses*: zqcs007@163.com (Q. Zhang), goldendays123@gmail.com (Z. Pan).

On the other hand, it is interesting to find that there exists bifurcation from double eigenvalue for many equations from science and engineering, of which the singularities are second-order fully degenerate and third-order nondegenerate.

In this paper, we consider the bifurcation of (1) from a double eigenvalue under assumption that the singularity be second-order fully degenerate and third-order nondegenerate. By the normalized Lyapunov–Schmidt reduction method [10], the precise criteria for the existence and nonexistence of bifurcation and the topological properties of regular bifurcated branches are obtained. At the end of this article, as an example to show how to apply our results in specific problems, we apply our results to the stationary equation of the Swift–Hohenberg equation.

2. Preliminaries

2.1. Normalized Lyapunov-Schmidt reduction

Let the eigenvalues (counting multiplicity) of L_{λ} be given by $\{\beta_1(\lambda), \beta_2(\lambda), \ldots\}$ with $\beta_i(\lambda) \in \mathbf{R}$ ($i = 1, 2, \ldots$) such that

$$\beta_{1}(\lambda) = \beta_{2}(\lambda) \begin{cases} < 0, \ \lambda < \lambda_{0}, \\ = 0, \ \lambda = \lambda_{0}, \\ > 0, \ \lambda > \lambda_{0}, \end{cases}$$

$$\beta_{i}(\lambda_{0}) \neq 0, \quad \forall j \ge 3,$$

$$(2)$$

and $\{e_1(\lambda), e_2(\lambda), \ldots\}, \{e_1^*(\lambda), e_2^*(\lambda), \ldots\}$ be the eigenvectors of L_{λ} and L_{λ}^* , respectively, corresponding to $\beta_i(\lambda)$, such that

$$L_{\lambda_0} e_k(\lambda) = 0, \quad L_{\lambda_0}^* e_k^*(\lambda) = 0, \quad k = 1, 2,$$

$$< e_i(\lambda), e_i^*(\lambda) >= \delta_{ij}, \quad \forall i, j.$$
(3)

By the Spectral Theorem (see [10]), in the neighborhood of $\lambda = \lambda_0$, X_1 and X can be decomposed into

$$\begin{cases} X_1 = E_1^{\lambda} \oplus E_2^{\lambda}, \\ X = E_1^{\lambda} \oplus \overline{E}_2^{\lambda}, \\ E_1^{\lambda} = span\{e_1(\lambda), e_2(\lambda)\}, \\ E_2^{\lambda} = \{u \in X_1 | < u, e_i^*(\lambda) >= 0, \quad i = 1, 2\}, \end{cases}$$

and L_{λ} can be decomposed into

$$\left\{egin{array}{ll} L_\lambda = \mathcal{L}_\lambda^0 \oplus \mathcal{L}_\lambda \ \mathcal{L}_\lambda^0 : E_\lambda^1 o E_\lambda^1, \ \mathcal{L}_\lambda : E_\lambda^2 o \overline{E}_\lambda^2. \end{array}
ight.$$

Since $u \in X_1$, there exists $x \in E_1^{\lambda}$, $y \in E_2^{\lambda}$, such that u = x + y,

$$x = x_1 e_1 + x_2 e_2$$

$$y=\sum_{j=1}^{\infty}y_je_j,$$

(1) can be rewritten as follows

 $\beta_1 x_1 + \langle G_2(x+y) + G_3(x+y), e_1 \rangle + o(\|x+y\|_{X_1}^3) = 0,$ (4)

$$\beta_2 x_2 + \langle G_2(x+y) + G_3(x+y), e_2 \rangle + o(||x+y||_{X_1}^2) = 0,$$
(5)

$$\beta_j y_j + \langle G_2(x+y) + G_3(x+y), e_j \rangle + o(\|x+y\|_{X_1}^3) = 0, \quad j \ge 3.$$
(6)

Definition 2.1 (*Ma and Wang* [10]). Assume (2) holds true. The steady state solution u = 0 of (1) is called *k*th-order nondegenerate, if $x = (x_1, ..., x_r) = 0$ is an isolated singular point of the following system of *r*-dimensional algebraic equations

$$\sum_{j_1\ldots j_k=1}^r a^i_{j_1\ldots j_k} x_{j_1}\ldots x_{j_k} = 0, \quad 1 \leqslant i \leqslant r,$$

where $a_{j_1...j_k}^i = \langle G_k(e_{j_1},...,e_{j_k}), e_i^* \rangle_X$, *r* is the geometric multiplicity of the eigenvalue $\beta_1(\lambda_0)$.

Download English Version:

https://daneshyari.com/en/article/6421938

Download Persian Version:

https://daneshyari.com/article/6421938

Daneshyari.com