



# Canonical polygons for the hyperbolic structures on the torus with a single cone point <sup>☆</sup>



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## ABSTRACT

Let  $T_0$  be the once-punctured torus and  $\theta$  a real number with  $0 < \theta < 2\pi$ . Let  $\tilde{\rho}$  be a representation of  $\pi_1(T_0)$  to  $SL(2, \mathbb{R})$  which sends the peripheral loop to an elliptic element with trace  $-2\cos(\theta/2)$ . Let  $\rho$  be the  $PSL(2, \mathbb{R})$ -representation induced from  $\tilde{\rho}$ , and assume it satisfies Bowditch's Q-condition. In this paper, we construct a certain polyhedron, which is obtained as a variation of Jorgensen's theory to cone manifolds, and construct a complete cone hyperbolic structure on the 3-dimensional cone manifold obtained as the product of the torus with a single cone point and  $\mathbb{R}$  which induces  $\rho$  as the holonomy representation.

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## 1. Introduction

In the famous unfinished manuscript [4], Jorgensen characterized the combinatorial structures of the Ford domains for quasifuchsian punctured torus groups. The characterization seems to work even if we replace the “puncture” with an elliptic point of finite order (as mentioned in [7]). In fact, Jorgensen [5] constructed such an example, and constructed a hyperbolic structure on a closed surface bundle over  $S^1$ ; to be precise, the structure constructed there is “doubly degenerate” and hence it should be thought of as a limit of quasifuchsian structures. This paper is devoted to the study in an early stage for the project to establish a variant of Jorgensen's theory for the torus with a single cone point.

Let  $T$  be the torus and  $v$  a point in  $T$ , and set  $\Sigma = \{v\} \times \mathbb{R} \subset T \times \mathbb{R}$ . Let  $\theta$  be a real number with  $0 < \theta < 2\pi$ . We denote the triplet  $(T, \{v\}, \theta)$  (resp.  $(T \times \mathbb{R}, \Sigma, \theta)$ ) by  $T_\theta$  (resp.  $M_\theta$ ). Set  $T_0 = T - \{v\}$  and  $M_0 = T \times \mathbb{R} - \Sigma$ . A *cone hyperbolic structure* on  $M_\theta$  is a metric which is locally isometric to the hyperbolic

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space on  $M_0$ , and each point in  $\Sigma$  has a neighborhood which is isometric to a *standard ball of angle  $\theta$*  with center corresponding to the point. (See Subsection 2.2 for the definition of standard balls of angle  $\theta$ . We refer to [2, Definition 3.9] for a general definition of standard balls.) Then the projection to the first factor induces an isomorphism from  $\pi_1(M_0)$  to  $\pi_1(T_0)$ . We denote the group by  $G$ , and fix a pair of generators  $A_0$  and  $B_0$  represented by simple closed curves on  $T_0$  intersecting transversely at a point. Associated with a cone hyperbolic structure on  $M_\theta$ , we have a smooth hyperbolic structure on  $M_0$ , and hence can define the *holonomy representation*  $\rho : G \rightarrow PSL(2, \mathbb{C})$ . Then  $\rho$  maps the commutator  $[A_0, B_0]$  to a  $\theta$ -rotation, namely,  $\text{tr } \rho([A_0, B_0]) = \pm 2 \cos(\theta/2)$ . Let  $\tilde{\mathcal{R}}_\theta$  be the  $SL(2, \mathbb{C})$ -representation space of  $G$  consisting of the elements  $\tilde{\rho}$  satisfying  $\text{tr } \tilde{\rho}([A_0, B_0]) = -2 \cos(\theta/2)$ , and  $\mathcal{R}_\theta$  the  $PSL(2, \mathbb{C})$ -representation space of  $G$  obtained from the elements of  $\tilde{\mathcal{R}}_\theta$  by post-composing the canonical surjection  $SL(2, \mathbb{C}) \rightarrow PSL(2, \mathbb{C})$ . In this paper, we study the *real slice*  $\mathcal{R}_\theta^{\mathbb{R}}$  of  $\mathcal{R}_\theta$ . To be more specific, let  $\tilde{\mathcal{R}}_\theta^{\mathbb{R}}$  be the subset of  $\tilde{\mathcal{R}}_\theta$  consisting of the conjugacy classes of representations into  $SL(2, \mathbb{R})$ , and  $\mathcal{R}_\theta^{\mathbb{R}}$  the corresponding subset of  $\mathcal{R}_\theta$ .

The character variety for  $\tilde{\mathcal{R}}_\theta$  is studied by Goldman [6] and Tan–Wong–Zhang [8,9] from the viewpoint of dynamics of the action of the mapping class group on the character variety. In their study Tan–Wong–Zhang introduced *Bowditch’s  $Q$ -condition (BQ-condition)* for the characters, and showed that the characters satisfying the BQ-condition satisfy a variation of McShane’s identity.

The following is the main theorem of this paper.

**Theorem 1.1.** *For  $\rho \in \mathcal{R}_\theta^{\mathbb{R}}$ ,  $\rho$  satisfies the BQ-condition if and only if there is a polyhedron  $Eh \subset \mathbb{H}^3$  and its side pairing with the following properties:*

1. *The polyhedron  $Eh$  is the geometric dual of a 1-dimensional simplicial complex induced from the associated sequence of elliptic generators.*
2. *By gluing the pairs of faces of  $Eh$  by the side pairing, we obtain a complete cone hyperbolic structure on  $M_\theta$  whose holonomy representation is equal to  $\rho$ .*

**Remark 1.2.**

1. In [6], Goldman gave a characterization for the connected components of the real character variety for  $\mathcal{R}_\theta$ , and then constructed a cone hyperbolic structures on  $T_\theta$  for any character corresponding to an indefinite bilinear form. Then Tan–Wong–Zhang [8,9] studied the character variety by using generalized Markoff maps, where they showed a certain condition for a real character to satisfy the BQ-condition. The proof of Theorem 1.1 depends on their results.
2. Yamashita in collaboration with Tan made a series of experiments on the character variety, in which he examined when a character satisfies the BQ-condition (cf. [10]). On the other hand, we can generalize the condition for polyhedra used in Theorem 1.1 for non-real representations. A polyhedron is said to be *good* if it satisfies the condition. The author made a series of experiments when a representation has a good fundamental polyhedron. Based on the results of experiments, Yamashita and the author proposed a conjecture: A representation in  $\mathcal{R}_\theta$  has a good fundamental polyhedron if and only if it satisfies the BQ-condition. Theorem 1.1 is a partial affirmative answer to the conjecture.

## 2. Preliminaries

### 2.1. Hyperbolic space

Throughout this paper, we use the upper half space model for the hyperbolic spaces  $\mathbb{H}^2$  and  $\mathbb{H}^3$ , and identify the group of orientation-preserving isometries of  $\mathbb{H}^2$  (resp.  $\mathbb{H}^3$ ) with  $PSL(2, \mathbb{R}) = SL(2, \mathbb{R})/\{\pm I\}$  (resp.  $PSL(2, \mathbb{C}) = SL(2, \mathbb{C})/\{\pm I\}$ ). Then the boundary at infinity  $\partial\mathbb{H}^2$  (resp.  $\partial\mathbb{H}^3$ ) is naturally identified

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