

Analysis of the 1D heat conduction problem for a single fin with temperature dependent heat transfer coefficient – Part II. Optimum characteristics of straight plate and cylindrical pin fins

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Abstract

An exact hypergeometric implicit solution of the 1D steady-state heat conduction problem for a straight fin of constant cross-section is used to calculate the dependence of the main dimensionless fin parameters, specifically, base thermal conductance G and thermo-geometrical fin parameter N on T_e , the ratio of the fin tip to fin base temperature excesses. The straight plate fin (SPF) and cylindrical pin fin (CPF) with an insulated tip (INT) and non-insulated tip (NINT) are optimized. The local heat transfer coefficient (HTC) is assumed to vary as power function of the local fin excess temperature with arbitrary value of exponent n in the range of $-0.5 \leq n \leq 5$. Every curve from G vs T_e set at given n for a fin with an INT is shown to have a single global maximum $G = G_{\text{opt}}^*$ at $T_e = T_{e,\text{opt}}^*$ and corresponding $N = N_{\text{opt}}^*$, i.e. the main optimum parameters depend only on exponent n . Every curve from G vs T_e set for a fin with a NINT depends, in addition, on the complex fin tip parameter B_{ω} . These curves have the local maximum and minimum points. As B_{ω} increases these points approach each other and at $B_{\omega} = B^{**}$ merge. The corresponding curve G vs T_e has the only inflection point. The main optimum parameters of a fin with an INT and inflection point parameters of a fin with a NINT are approximated by general homographic function of n . Each main optimum parameter of a fin with a NINT is expressed as a product of the corresponding parameter of this fin with an INT and a correction factor approximated by the generalized closed-form formula. The results of the study are presented in form of dimensionless explicit relations, tables and plots which are well suited for the thermal design of optimum fins.

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1. Introduction

Authors of the fundamental book “Extended Surface Heat Transfer” [1] have pointed out that there are three types of optimizations that pertain to extended surface design and analysis. The first type of optimization involves for longitudinal fins, radial fins, and spines the finding of the profile shape that yields maximum heat flow (or thermal conductance in terms of present study) for a specified mass of a fin (the direct optimization problem) or minimum mass for a specified heat flow or thermal conductance

of a fin (the inverse optimization problem). The second type of optimization is, in essence, a variant of the first one for a fin with given shape of profile. For example, optimization of longitudinal fins of constant thickness or the straight plate fins (SPF) and cylindrical spines or cylindrical pin fins (CPF) will be considered in the present paper. The optimization problems of this type are considered in the most publications in available technical literature. The third type of optimization consists in application of the mentioned optimization types to an array of fins in which each fin is operating in an optimum manner.

The paper by Aziz [2] contain a review on optimum dimensions of extended surfaces (mostly, single fins of different shape) losing heat by pure convection to the

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Nomenclature

| | | | |
|------------------------|---|------------------------------------|---|
| a, a_e | given constants in the heat transfer equation for the lateral surfaces and tip surface of a fin ($\text{W m}^{-2} \text{K}^{-(n+1)}$) | N | dimensionless thermo-geometrical fin parameter, $l\sqrt{h_b P/(kA)}$ |
| a_p | profile area of the SPF (m^2) | n | given exponent in the heat transfer equation for a fin |
| A | fin cross-sectional area (m^2) | P | perimeter of the fin cross-section (m) |
| A_p, \hat{A}_p | dimensionless profile area of the SPF (whole and reduced), $A_p = a_p(h_b/k)^2$; $\hat{A}_p = A_p/2$ | r | radius of the CPF (m) |
| B, B_ω | general designation for given Biot number or fin base conductance G_z (or G_c) of the SPF (or CPF), $B_\omega = B \cdot f(\omega)$ | Q_{bz}, Q_b | heat flow dissipated by the SPF (or CPF), (W m^{-1} , (W)) |
| Bi, Bi_l, Bi_a, Bi_v | dimensionless Biot numbers based on the thickness (radius), height, profile area (or volume) of the SPF (or CPF), respectively | t | fin temperature (K) |
| E_f | extension factor of the total fin heat transfer surface, F/A | T | dimensionless fin temperature excess, ϑ/ϑ_b |
| $f(\omega)$ | power function of the tip heat transfer ratio with different value of p for every given parameter B of the SPF (or CPF), $f(\omega) = \omega^p$ | T_e | dimensionless fin tip temperature excess, ϑ_e/ϑ_b |
| F | whole heat transfer area of a fin (m^2) | v | volume of the CPF (m^3) |
| $C_{i,i=1,3}$ | numerical coefficients of the homographic function in Eq. (16) | V, \hat{V} | dimensionless total and reduced volume of the CPF, $V = v(h_b/k)^3$, $\hat{V} = V/(4\pi)$ |
| g_b | fin base thermal conductance, Q_b/ϑ_b (W K^{-1}) | x | space coordinate (m) |
| g_l | thermal conductance of a fin with insulated lateral surfaces, kA/l (W K^{-1}) | X | dimensionless space coordinate, x/l |
| G | dimensionless thermal conductance of the SPF (or CPF), $G = \hat{G}_z/(Bi_a^2/2)^{1/3}$ (or $G = \hat{G}_c/[Bi_v^3/(4\pi)]^{3/5}$), respectively | Y | general denotation of the dimensionless dependent variable that have to be optimized |
| G_b | dimensionless fin base thermal conductance, g_b/g_l | z | width of the SPF (m) |
| G_c, \hat{G}_c | dimensionless total and reduced thermal conductance of the CPF, $G_c = g_b(h_b/k^2)$, $\hat{G}_c = G_c/(4\pi)$ | Greek symbols | |
| G_{cV} | dimensionless thermal conductance of the CPF per unit volume, G_c/V | $\beta_{\omega,B}$ | dimensionless complex parameter of heat transfer on the fin tip, B_ω/B^{**} |
| G_z, \hat{G}_z | dimensionless total and reduced thermal conductance of the SPF, $G_z = g_b/(zk)$; $\hat{G}_z = G_z/2$ | δ | fin thickness (m) |
| G_{zA_p} | dimensionless thermal conductance of the SPF per unit profile area, G_z/A_p | ϑ | local temperature excess of a fin over the ambient medium, $t - t_a$ (K) |
| h, h_e | heat transfer coefficient for the lateral and tip surfaces of a fin ($\text{W m}^{-2} \text{K}^{-2}$) | $\xi_{Y,B}$ | correction factor to determine the required optimum value, $Y_{\text{opt}}/Y_{\text{opt}}^*$ |
| K | fin augmentation factor (effectiveness), g_b/g_p | ψ | fin aspect ratio (fin height to half-thickness or half-radius ratio), Bi_l/Bi |
| k | thermal conductivity of the fin material ($\text{W m}^{-1} \text{K}^{-1}$) | ω | ratio of heat transfer coefficients on the tip and lateral surfaces of a fin, $h_e/h_{x=0}$ |
| l | fin height (m) | Subscripts and superscripts | |
| | | b, e | refer to the fin base and fin tip (for $X = 1$ and $X = 0$, respectively) |
| | | opt | refer to optimum values |
| | | * | refer to the fin with an insulated tip |
| | | ** | refer to the inflection point of G vs T_e curve for the fin with a non-insulated tip at $\omega = 1$ and maximum allowable B value (B^{**}) |

surroundings. The review covers straight (longitudinal) fins, annular (radial) fins and spines of different profile shapes. The optimum dimensions for each shape are given both in terms of the given volume of material as well as in terms of the given heat dissipation. The effects of tip heat loss, variable heat transfer coefficient, internal heat generation, and temperature dependent thermal conductivity of fin material on the optimum dimensions have been discussed.

The direct analytical solution of the optimization problem for a single CPF with an insulated tip and uniform heat transfer coefficient on the cylindrical surface is obtained by Sonn and Bar-Cohen in [3]. Authors have expressed the heat flow Q_b dissipated by a cylindrical spine in terms of its diameter d . The values of fin volume and fin base temperature excess ϑ_b are given. Thermal conductivity of the fin material k and heat transfer coefficient h over the whole fin surface are assumed to be constant. Differentiating Q_b

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