



Geologic CO₂ sequestration monitoring design: A machine learning and uncertainty quantification based approach

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HIGHLIGHTS

- Filtering-based data assimilation method is developed to perform monitoring design.
- Machine learning is used to reduce computational cost of data assimilation process.
- Uncertainty reduction is chosen as the metric to quantify the VOI of monitoring data.

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ABSTRACT

Monitoring is a crucial aspect of geologic carbon dioxide (CO₂) sequestration risk management. Effective monitoring is critical to ensure CO₂ is safely and permanently stored throughout the life-cycle of a geologic CO₂ sequestration project. Effective monitoring involves deciding: (i) where is the optimal location to place the monitoring well(s), and (ii) what type of data (pressure, temperature, CO₂ saturation, etc.) should be measured taking into consideration the uncertainties at geologic sequestration sites. We have developed a filtering-based data assimilation procedure to design effective monitoring approaches. To reduce the computational cost of the filtering-based data assimilation process, a machine-learning algorithm: Multivariate Adaptive Regression Splines is used to derive computationally efficient reduced order models from results of full-physics numerical simulations of CO₂ injection in saline aquifer and subsequent multi-phase fluid flow. We use example scenarios of CO₂ leakage through legacy wellbore and demonstrate a monitoring strategy can be selected with the aim of reducing uncertainty in metrics related to CO₂ leakage. We demonstrate the proposed framework with two synthetic examples: a simple validation case and a more complicated case including multiple monitoring wells. The examples demonstrate that the proposed approach can be effective in developing monitoring approaches that take into consideration uncertainties.

1. Introduction

Geologic CO₂ sequestration (GCS) is being considered as an important technology to reduce anthropogenic greenhouse gas emissions to the atmosphere [1–9]. Many potential reservoirs have been proposed to store anthropogenic CO₂ emissions, such as depleted oil or gas reservoirs, coal beds, deep oceans and deep saline formations [10–13]. The isolation of CO₂ from the environment is imperative for a GCS project not only for the project to successfully store CO₂, but also due to the fact that CO₂ leakage is a threat to the environment, the groundwater resources and human health [14–16]. CO₂ leakage may occur through improperly plugged and abandoned wellbores or through natural fractures or faults [1,17–19]. Given that depleted oil or gas reservoirs with significant numbers of abandoned wellbores are

attractive locations for GCS [10,20–27], potential leakage through abandoned wellbores becomes a primary concern.

To ensure that large-scale GCS is safe and effective, a risk management strategy is generally used to minimize and mitigate risks during CO₂ injection and post-injection periods of a storage site [28–30]. Monitoring is an essential aspect of GCS risk management. To effectively monitor for CO₂ leakage, several monitoring technologies have been developed, including near-surface measurements of soil CO₂ flux and tracer [31,32], pressure monitoring [33–35], shallow groundwater chemistry monitoring [36,37], and micro-seismic and cross-well seismic survey [32,38]. A few studies have been conducted to evaluate the performance of different monitoring strategies or perform monitoring optimization for CO₂ storage sites. Next, we provide a discussion of some of the most relevant work in order to put the methodology introduced in this paper in context.

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Nomenclature

Symbols

| | |
|---------------|---|
| d_i | i th individual data point that would be obtained if the monitoring design were implemented |
| \tilde{d}^j | j th data vector corresponding to each \tilde{m}^j |
| \hat{d}^k | k th data vector corresponding to each \hat{m}^k |
| D | data that would be measured for a particular monitoring program |
| D^j | j th realization of D |
| e^j | j th realization of the vector of measurement errors |
| E_d | expectation with respect to all realizations of D |
| l_d | number of data realizations |
| l_{mc} | number of Monte Carlo samples |
| m | uncertain input parameter |
| \tilde{m}^j | j th model realization generated from prior probability density function of m |
| \hat{m}^k | k th Monte Carlo sample |
| M_c | cumulative CO ₂ leakage |
| n_d | number of data points in the data vector D |
| $O(m)$ | ROM vector for data |
| $P(M_c)$ | prior probability density function of M_c |
| $P(M_c D^j)$ | posterior probability density function of M_c |

| | |
|-----------|--------------------------------------|
| P_{10} | 10th percentile |
| P_{90} | 90th percentile |
| P_{acc} | acceptance probability |
| U | amount of uncertainty |
| U_R | uncertainty reduction |
| τ | threshold for maximum absolute error |

Acronyms

| | |
|--------|---|
| AZMI | above zone monitoring intervals |
| BIPP | binary integer programming problem |
| EnKF | ensemble Kalman Filter |
| ES-MDA | ensemble smoother with multiple data assimilation |
| FEHM | Finite Element Heat and Mass transfer |
| GCS | Geologic Carbon Sequestration |
| LHS | Latin Hypercube Sampling |
| MAE | maximum absolute error |
| MARS | Multivariate Adaptive Regression Splines |
| MCMC | Markov chain Monte Carlo |
| PCKF | probabilistic collocation based Kalman Filter |
| PDF | probability density function |
| ROMS | reduced-order-models |
| VOI | value of information |

Yang et al. [39] provided a probabilistic method for predicting the performance of different monitoring networks at GCS sites. The objective of their method is to estimate the probability that a monitoring network will detect CO₂ leakage. Yang et al. [40] developed a risk-based monitoring assessment methodology, which was an extended work of Yang et al. [39], to incorporate background data for monitoring design. In this method, the detection probability defined as the probability that a measured signal will be above the preselected threshold at the monitoring location is first calculated, and then the detection probability is used to estimate the monitoring well density and response time for both known and unknown wellbore leakage locations.

Seto and McRae [41] presented a model-based framework for integrated monitoring design that can provide a quantitative understanding of the trade-offs between operational costs and risks in potential monitoring strategies. In addition, the challenges, risks and design considerations of large scale CO₂ storage were comprehensively reviewed and discussed in their work. In the work of Seto and McRae [42], a method for CO₂ detection based on a Bayesian model selection framework was introduced and applied to distinguish whether detected CO₂ is from a leak or from background fluctuations. The limits of different monitoring technologies, the challenges of leak detection and what are acceptable rates of leakage were thoroughly investigated in their research.

Sun et al. [43] proposed an approach to optimize monitoring networks under geological uncertainty. A binary integer programming problem (BIPP) formulated in their work was demonstrated for effectively selecting optimal monitoring locations in both homogeneous and heterogeneous formations. However, the proposed method requires running a forward full-scale model many times for different design options, which makes the BIPP computationally demanding. Sun et al. [43] suggested that a reduced order model or surrogate model can be used to speed up the BIPP optimization process. Cameron [44] demonstrated an approach to optimize sensor locations for CO₂ plume monitoring at a GCS site under geological uncertainty by minimizing the expected prediction error of the CO₂ plume size.

Dai et al. [45] proposed a data-worth analysis approach using probabilistic collocation based Kalman Filter (PCKF) to optimize the surveillance operation in a GCS project. In this approach, surrogate

models are developed using polynomial chaos expansion to replace the original flow models. Thereafter, the expected variance reduction of field cumulative CO₂ leakage is assessed via data-worth analysis. An optimal monitoring operation scheme is selected by comparing the value of data-worth for different monitoring strategies. Dai et al. [46] applied the data-worth analysis and PCKF based approach to quantify the uncertainty reduction associated with the characterization of a migrating contaminant plume for different monitoring networks in groundwater systems.

Chen et al. [47] proposed an approach based on the Markov chain Monte Carlo (MCMC) method and reduced order models (ROMs) to quantify the uncertainty reduction of different pilot designs in an oil field. Note that a pilot refers to small-scale test and data collection operations prior to a full field development. In the proposed method, multiple realizations of monitoring data from a pilot test are generated, and probabilistic history matching (data assimilation) based on an MCMC method is performed for each data realization to obtain the corresponding posterior distribution. Though the MCMC based history matching is accomplished with the help of ROMs, the computational demand is still high due to the fact that for each data realization, MCMC often takes hundreds of thousands of runs to converge [48–50]. As mentioned in the work of Chen et al. [47], one limitation of their proposed framework is that with the increase of the uncertain model parameters, it would be difficult for the Markov chain to converge to the target distribution.

In this work, we build off the previously mentioned monitoring design algorithms to capture full physics simulations in a computationally efficient manner by using reduced order models and determine the optimal monitoring design for GCS sites based on many potential leakage scenarios that could occur. To quantify the uncertainty reduction, instead of using an MCMC method as in the work of Chen et al. [47], we apply a filtering based data assimilation method [51] in this study, which overcomes the convergence issue inherent in the MCMC method. In addition, a popular machine learning technique, Multivariate Adaptive Regression Splines (MARS) [52], is used to construct the ROMs or proxy models to reduce the computational cost when the filtering based data assimilation method is applied.

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