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Multi-objective active distribution networks expansion planning by scenario-based stochastic programming considering uncertain and random weight of network



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HIGHLIGHTS

- The uncertain random network theory is originally applied in the ADN planning model.
- A modified scenario-generation procedure is proposed to describe uncertainty sources.
- A numerical second-order cone programming is applied to solve the MINLP model.
- · A novel 3-dimensional uncertain space is built to cope with multi-objective problem.
- A sensitivity analysis is performed to find compromise between costs and system performance.

ARTICLE INFO

Keywords: Multi-objective planning Active distribution network Energy management Uncertain random network Minimum spanning tree Stochastic programming

ABSTRACT

This paper presents a novel multi-objective model of active distribution network planning based on stochastic programming and uncertain random network (URN) theory. The planning model is proposed to find the final scheme with optimal alternative, location, size and operational strategy for the candidate distribution lines, transformer substations (TSs), distribution generations (DGs), static var compensators (SVCs) and on-load tap changers (OLTCs). Firstly, a scenario-based approach is developed to analyse the uncertainties in network system, such as the demand and intermittency of renewable sources. Since the impact of multiple uncertain factors on network cannot be ignored, a network frame is then modelled by uncertain and random weights of spanning tree (ST) instead of fixed value. In order to achieve the minimization of total cost, and further the selection of a minimum spanning tree (MST) with the uncertain random weight, a 3-dimensional uncertain space is constructed based on the combination of the previous two targets. In addition, a second-order cone programming (SOCP) is applied to cope with the multi-objective, mixed-integer nonlinear nature of the proposed planning model. Simulation is performed on a modified Pacific Gas and Electric Company (PG&E) 69-bus distribution system, and the results demonstrate the effectiveness of the proposed model.

1. Introduction

In a centralized power generation system, the electricity is generally supplied by a large-scale generation unit, and transmitted and distributed through network to domestic, commercial and industrial consumers, as shown in Fig. 1(a). In recent years, high penetration of renewable DGs have been considered as one of the key issues for power distribution network system. Among different renewable DGs, wind turbines generations (WTGs) and photovoltaic plants generations (PVGs) have attracted more attention due to their commercial products and supply ability in distribution system [2], as shown in Fig. 1(b). Nevertheless, several challenges have to be addressed before their mass commercialization in distribution network planner (DSP).

Nowadays, the distribution system planning has been successfully implemented by distribution system planners with centralized framework. The primary objective of conventional distribution network planning (DNP) is to identify the optimal expansion of system assets at minimum cost, in order to meet the load growth demand and newly added loads, and at the same time complying with the security requirements and quality standards [3,4]. However, with the widespread growth of distributed generation (DG) penetration, mainly due to renewable energy policy-making [5–7] and its substantial advantages to

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Nomenclature		$\widetilde{\sigma}_{max}$	maximum permissible tap position value of OLTC
Indices and sets		\widetilde{U}^{OLTC}	original voltage of OLTC before adjustment
malees and sets		h_k	voltage variation value for changing each tap of
ij	index for lines	n_k	OLTC
i,j	index for buses		0010
b,s	index for time blocks and scenarios	Variables	
t	index for time stages		
р	index for DG types	$x_{ij,k}^{Line}$	binary investment variable for feeders ij with
k	index for available investment alternatives		type k
g	index for spanning trees	$x_{j,k}^{Tr}/x_{j,k}^{Dg}/x_j^{OLTC}$	binary investment variable for TS/DG(type <i>p</i>)/
В	set of time blocks	SVC	OLTC with alternative k at bus j
S(b)	set of scenarios of time block b	$x_{j,k}^{SVC}$	integer investment variable for SVC type k at <i>j</i>
Т	set of time stages	$\mathcal{Y}^{Line}_{ij,k}$	binary utilization variable for feeders <i>ij</i> with
Ω,Γ	set of uncertain variables and random variables	,.Tr /,.Dg /,.OLTC	type k
Ω^{Tree}	set of spanning trees	$y_{j,k}^{Tr}/y_{j,k}^{Dg}/y_j^{OLTC}$	binary utilization variable for TS/DG(type p)/
Π^{Line}	set of candidate replaceable feeders	$\mathcal{Y}^{SVC}_{j,k}$	OLTC with alternative k at bus j integer utilization variable for SVC type k at j
Γ^b	set of all buses		integer variable for tap position value of OLTC
$\Omega^{Line}/\Omega^{Dg}/\Omega^{Tr}$	set of candidate feeders/DGs/TSs/SVCs/OLTCs	$\sigma_{j,s,t}$ $I_{j,s,t}$	current injection at bus <i>j</i>
$\Omega^{SVC}/\Omega^{OLTC}$		$U_{j,s,t}$ $U_{j,s,t}$	voltage magnitude at bus j
$\Gamma^{Line}/\Gamma^{Dg}/\Gamma^{Tr}$	set of all existing and candidate feeders/DGs/	$\delta(j),\pi(j)$	set of buses whose parent/child is bus j
TzLine / Tz Dg / Tz Tr	TSs	$P_{j,s,t},Q_{j,s,t}$	active power and reactive power injection at <i>j</i>
$\mathbf{K}^{Line}/\mathbf{K}_{p}^{Dg}/\mathbf{K}^{Tr}$	set of available alternatives for feeders/DG(type	$P_{ij,s,t}, Q_{ij,s,t}$	active power and reactive power flow via line <i>ij</i>
$/ \mathrm{K}^{SVC}/\mathrm{K}^{OLTC}$	n) /TS2 /SVC2 /OI TC2	$P_{j,s,t}^{WTG,cur}, Q_{j,s,t}^{WTG,cur}$	curtailment of WTG active/reactive power at <i>j</i>
Λ^{Dg}	p)/TSs/SVCs/OLTCs set of type for DC $A^{Dg} = (WTC, BV)$	$P_{j,s,t}^{PVG,cur}, Q_{j,s,t}^{PVG,cur}$	curtailment of PVG active/reactive power at <i>j</i>
Λ ⁻ °	set of type for DG. $\Lambda^{Dg} = \{WTG, PV\}$	$P_{j,s,t}^{L,cur}, Q_{j,s,t}^{L,cur}$	curtailment of load active/reactive power at j
Parameters and con	stants	$P_{j,s,t}^{PVG,cur}, Q_{j,s,t}^{PVG,cur}$	curtailment of PVG active/reactive power at <i>j</i>
i uluneters unu con		$P_{j,s,t}^{L,cur}, Q_{j,s,t}^{L,cur}$	· · ·
$C_k^{I,Line}/C_{k,p}^{I,Dg}/C_k^{I,Tr}$		$P_{j,s,t}$, $Q_{j,s,t}$	curtailment of load active/reactive power at <i>j</i>
	investment cost of feeders/DG (type p)/TSs/	Abbreviations	
$/ C_k^{I,SVC} / C^{I,OLTC}$	SUCCOUTCO with alternative k (\$)	ribbreviationa	
CM,Line $(CM,Dg)(CM,T)$	SVCs/OLTCs with alternative k (\$)	PG&E	Pacific Gas and Electric Company
$C_k^{M,Line}/C_{k,p}^{M,Dg}/C_k^{M,Tr}$	investment cost of feeders/DG(type p)/TSs/	DSP	distribution system planner
$/ C_k^{M,SVC}/C^{M,OLTC}$		ADN	active distribution network
aTr LaWTGLaPVG	SVCs/OLTCs with alternative k (\$)	URN	uncertain random network
$C_{ope}^{Tr}/C_{ope}^{WTG}/C_{ope}^{PVG}$	operation cost of TSs/WTGs/PVGs (\$/MWh)	TSs	transformer substations
$C_{loss}^{Line}/C_{loss}^{Tr}/C_{loss}^{OLTC}$	energy losses cost of network/TSs/OLTCs	DGs	distribution generators
- (-)	(\$/MWh)	CBs	capacitor banks
$\rho(s)$	probabilities of scenario s	SVCs	static var compensators
ℓ_{ij} i	feeder length of line <i>ij</i>	OLTCs	on-load tap changers
Δt_{b}	annual interest rate duration of time block <i>b</i>	STs	spanning tree
$\frac{\Delta \iota_b}{N_B}$	total number of time blocks	WTG	wind turbine generator
N _S	number of scenarios per time block	PVG	photovoltaic generator
N_j^{Dg}/N_j^{SVC}	installation number of DGs/SVCs at bus j	MST	minimum spanning tree
$\approx^{Dg} \approx^{Dg}$	•	SOCP	second order cone programming
$\widetilde{P}_{j,k,p}^{Dg}, \widetilde{Q}_{j,k,p}^{Dg}$	rated active and reactive power of DG	MISOCP	mixed-integer second order cone programming
z_{k}^{OLTC}	resistance of OLTC/transformer with type k	DNP	distribution network planning
r_{ij}, x_{ij}	resistance and reactance of line <i>ij</i>	ANMs	active network managements
P_j^L	maximum active power of load at bus <i>j</i>	DSM	demand side management
$\beta_{\min}, \beta_{\max}$	minimum and maximum penetration of DG	ADNP	active distribution network planning
$\widetilde{U}_{min}, \widetilde{U}_{max}$	minimum and maximum permissible voltage	SOCR	second order cone relaxation
$\lambda^{WTG}/\lambda^{PVG}/\lambda^L \simeq SVC$	maximum curtailment rate of WTG/PVG/load	MINLP	mixed-integer nonlinear programming
Q_{max}	maximum capacity of SVC	CDF	cumulative distribution function
$\widetilde{Q}_{max}^{SVC}$ $\widetilde{P}_{max}^{Tr}, \widetilde{Q}_{max}^{Tr}$	maximum active and reactive power of TS	AU	average unavailability
\widetilde{I}_{max}	maximum permissible current of line	AFVSI	average fast voltage stability index

operation and planning [1,8], the traditional distribution networks are undergoing the transformation from passive unidirectional flow networks to active distribution network (ADN) [9,10]. This transition introduces the enormous challenges to DSP in both economy and technology. As a system with controllable mechanism and flexible energies, the ADN technologies can provide significant solution to achieve the goal of system stability, reliability and sustainability, and this approach can be effectively used in wind and solar power application. On the other hand, the main active network management (ANM) schemes including demand side management (DSM), wind power curtailment, solar power curtailment, OLTC tap adjustment, continuous reactive power compensation, are proved to be able to decrease the operation costs and thus avoid unnecessary investment in active distribution network planning (ADNP) [11–13].

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