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A punching shear mechanical model for reinforced concrete flat slabs with and without shear reinforcement



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ABSTRACT

A punching shear strength mechanical model for RC flat slabs with and without shear reinforcement, based on a beam shear model previously developed by the authors, is presented. The differences in resisting actions between beam shear and punching shear have been identified and incorporated into the governing equations and failure modes, resulting in simple but accurate punching design equations. The model consistently explains and quantifies some experimentally observed phenomena, such as the higher contribution of the concrete to the punching shear strength of slabs than in the case of beams subjected to shear, mainly due to the multi-axial state of stresses that takes place near the support. Furthermore, the model provides physical meaning to some parameters used in the design, such as the position of the critical perimeter or the effective stress of the punching reinforcement, among others. Very good agreement has been obtained between the model predictions and the results of 560 punching tests of concentrically loaded slabs, with and without shear reinforcement, included in two available large databases. The mechanical character of the model allows its extension to post-tensioned flat slabs, border or corner columns, steel fiber and FRP reinforced concrete slabs or different strengthening systems in a consistent way.

1. Introduction

Punching capacity of slabs has been extensively studied in the past, both from the experimental and theoretical viewpoints [1-29]. As a result of these research works, several approaches have been developed for predicting the punching strength of reinforced concrete slabs with and without shear reinforcement. Even though some developed models reproduce quite well the experimental results, there is not yet a generally accepted design model which combines accuracy with the necessary simplicity for daily design, adaptable to the variety of situations that can take place in practice. This is evidenced by the differences in the treatment of the punching strength in relevant codes provisions, such as EC2 [30], ACI [31] and Model Code 2010 [32], or by the changes produced along the time in some essential design parameters. Some examples of aspects still in discussion are the position of the critical perimeter, the effective stress in the shear reinforcement at ULS or the influence of the presence of shear reinforcement on the punching concrete contribution, among others. In fact, many of the punching strength code provisions are based on empirical models, adjusted to tests results, but without a consistent theory behind.

Certainly, advanced numerical models are more and more capable

to simulate the local and global observed punching behavior [33–37]. However, there is still the need to improve the objectivity of the models, which are excessively dependent on the materials parameters used (i.e., post-cracking and softening behavior, bond...) in order to obtain reliable predictions of the experimental results without requiring too much effort and time. Nevertheless, numerical methods have become very useful tools to provide support to the development of conceptual models, by allowing the verification of certain assumptions and quantifying the influence of certain variables by performing parametric studies.

Since punching shear is a brittle -and therefore undesirable- failure, in order to reach the required safety level without an unaffordable cost, simplified, but safe and accurate design models are needed. In order to achieve these characteristics, such models should be based on the principles of concrete mechanics and should be verified with available experimental results.

In this paper, a new mechanical model for the estimation of the punching shear strength of reinforced concrete flat slabs with and without shear reinforcement is presented. The punching shear model presented in this paper is an adaption of a previously existing model for beam shear strength, developed by the authors in [38–40], which

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Nomenclature

Notations

0.15 l_z , l_y and l_z are the span lengths in the y and z directions. See Ref. [40] for complete definition regarding shear in beams

- b width of the cross-section of a beam. For T or I-shaped is equal to the flexural effective compression flange width
- width of the web on T, I or L beams. For rectangular beams b_w $b_w = b$
- effective depth of the cross-section d
- effective depth of the cross-section, d, but not less than d_0 100 mm
- distance between the maximum compressed concrete fibre d, and the centroid of the mild steel tensile reinforcement. In the case of prestressed elements without mild reinforcement, d_s shall be taken equal to d_p
- distance between the maximum compressed concrete fibre d_p and the mechanical centroid of the prestressing tendons placed at the tension zone
- confined concrete compressive strength f_{cc}
- design value of concrete compressive strength f_{cd}
- characteristic compressive strength of concrete f_{ck}
- mean compressive strength of concrete f_{cm} mean tensile strength of concrete, equal to $0.30 f_{ck}^{2/3}$ in f_{ctm} MPa, not greater than 4.60 MPa
- mean yield strength of the shear reinforcement frw
- design yield strength of the shear reinforcement frwd
- slab cracking bending moment per unit width m_{crack}
- bending moment per unit length producing radial stresses m_r around the column
- bending moment per unit length producing tangential m_{φ} stresses around the column
- radial distance from the column axis r
- radial distance from the column axis to the point of zero r_0 radial bending moment (contraflexure point)
- radius of a column with equal perimeter than the actual r_{col} column
- distance from the starting point of the critical crack (due *r*_{crack} to bending) to the column axis, see Fig. 7
- distance from the critical perimeter to the column axis, see r_{crit} Fig. 7
- radial distance s distance from the starting point of the critical crack (due \$_{crack} to bending) to the column face, see Fig. 7
- distance from the critical perimeter to the column face, scrit \$_{crit} = 0.5d, see Fig. 7
- critical perimeter (Fig. 7) placed at a distance s_{crit} from the Ucrit column face
- perimeter where shear reinforcement is not longer reu_{out} quired (Fig. 10) (see Fig. 2).
- neutral axis depth of the cracked section, obtained asх suming zero concrete tensile strength
- x_0 neutral axis depth of a RC member or of a PC member

considering P = 0 and the same amounts of reinforcements

- inner lever arm. In the shear analysis of reinforced concrete beams without axial force, the approximate value z $\approx 0.9d$ may normally be used. See Eq. (2)
- A_{sw} cross-sectional area of the shear reinforcement. For punching. Asw is the total area of the shear reinforcement placed around the column that crosses the critical inclined crack that can be approximated by considering the reinforcement placed between 0.5d and 1.5d from the support face

 E_{cm} secant modulus of elasticity of concrete, $E_{cm} = 22000 (f_{cm}/10)^{0.3} \neq 39 \text{ GPa}$

 E_s modulus of elasticity of reinforcing steel

7.

- concrete fracture energy, $G_f = 0.028 f_{cm}^{0.18} d_{max}^{0.32}$, in Eq. (4)
- G_f K_c factor equal to the relative neutral axis depth, x/d, but not greater than 0.20, in Eqs. (10) and (31)
- factor that accounts for the effectiveness of the anchorage K_s of the shear reinforcement
- M_{cr} cracking moment at the section where shear strength is checked calculated using the mechanical properties of the gross concrete section and the flexural tensile strength
- concomitant design bending moment, considered positive M_{Ed}
- V_{Ed} design shear force in the section considered
- design shear resistance of the member V_{Rd}
- design value of the maximum shear force which can be V_{Rd,max} sustained by the member, limited by crushing of the struts V_u shear resistance of the member calculated by the background mechanical model, Eq. (1)
- $V_{u,max}$ maximum shear force which can be sustained by the member, limited by crushing of the struts in the back-
- ground mechanical model or multi-action model, Eq. (2) angle between shear reinforcement and the beam axis α perpendicular to the shear force in Eqs. (11) and (32). In Eq. (18) α is a parameter taking into account the nonuniform distribution of the vertical stresses
- coefficient taking account the state of the stress in the $\alpha_{\rm cw}$ struts. See EC2 [30] for further information.
- modular ratio, $\alpha_e = E_s/E_{cm}$ α_e
- parameter for the determination of the maximum α_{max} punching shear capacity, Eq. (35) ν

Poisson coefficient

- strength reduction factor for concrete cracked in shear. ν_1 See EC2 [30] for further information
- angle between the concrete compression strut and the θ beam axis perpendicular to the shear force
- longitudinal tensile reinforcement ratio. The neutral axis ρ_l depth x/d should be obtained using the average of the longitudinal reinforcement ratios, ρ_{lx} , ρ_{ly} , in the two orthogonal directions, adopting an effective slab width $b_{s.eff}$ approximately equal to the column side or diameter plus 3 times the slab effective depth at each side of the column
- normal radial stresses around the column produced by m_r σ_r σ_{φ} normal tangential stresses around the column produced by m_{ω}
- vertical stresses in the slab in the vicinity of the column, σ_{v} see Fig. 5
- size and slenderness effect factor, given by Eq. (12) ζ

incorporates the contribution of the main shear resisting mechanisms. For this purpose, the relevant differences between the shear in beams and punching shear resisting actions have been identified and accounted for into the governing equations and into the failure criteria

used in the mechanical model. Numerical simulations using a nonlinear finite element model have been used to verify some of the assumptions made. Different authors have developed very complete and comprehensive databases on punching tests performed

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